

# Working with Giano

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# Procedures

- Installing Giano
- Running Simulations in Giano from Visio
- Running Simulations from the Command Line
- Connecting to Simulations using Serplexd
- Simulating EB63 with HostFS
- Creating/modifying a configuration
- Creating a new Giano module

# Procedure #1

- **Installing Giano**
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# Installing Giano

1. Install Giano from MSI file (V2), in a writeable directory.
2. Rebuild Giano if necessary. Look at the bin\recompile\* scripts for debug/release differences.

# Rebuilding Giano

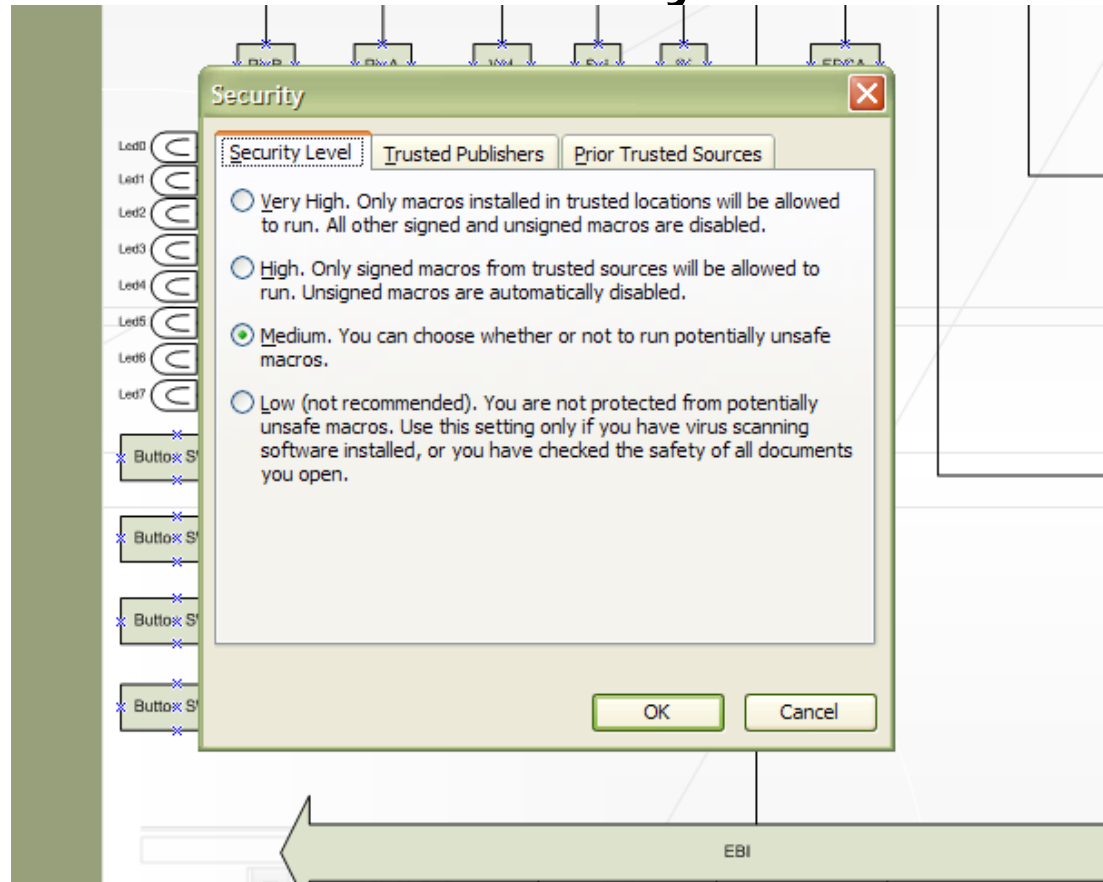
1. Have Microsoft Visual Studio installed on the Computer (VC6,7 and 8 are all ok)
2. Delete all \*.manifest files from the subtree
3. Do not delete the following files from the 'bin' folder:

- bbuniq.exe
- bbw.dll
- cbw32.dll
- mcc.dll
- msvcr71.dll
- np.dll
- vpi2g.dll
- vssver.scc
- vvp.dll
- bbcats.exe
- bbdump.exe
- bbfind.exe
- bbmatch.exe
- bbmerge.exe
- bbrewrite.exe
- bbs.dll
- bbselect.exe
- bbsort.exe

4. Open a MVS Command Prompt and call 'nmake clean all' or "nmake clean debug"

# Visio and Macros

- You must enable Visio macros, set Tools:::Macros:::Security to Medium or Low



# Procedure #2

- Installing Giano
- **Running Simulations in Giano from Visio**
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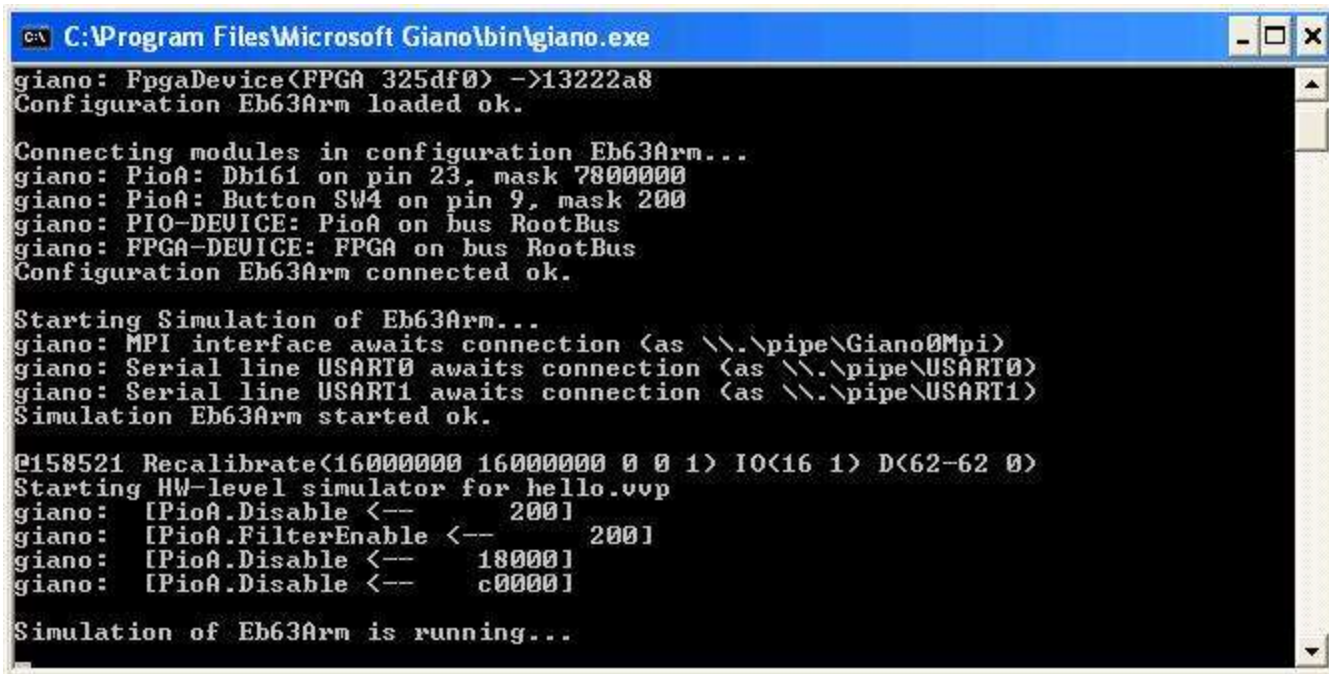


# Running Simulations in Giano from Microsoft Visio

2. Right Click on CPU model and select 'Create the Simulation Configuration File'. This creates the \*.plx configuration file based on the model drawn in Microsoft Visio
3. Right Click on the CPU model and select 'Start Simulation'. The simulation will start in a command window.



# Running Simulations in Giano from Microsoft Visio



```
C:\Program Files\Microsoft Giano\bin\giano.exe
giano: FpgaDevice<FPGA 325df0> ->13222a8
Configuration Eb63Arm loaded ok.

Connecting modules in configuration Eb63Arm...
giano: PioA: Db161 on pin 23, mask 7800000
giano: PioA: Button SW4 on pin 9, mask 200
giano: PIO-DEVICE: PioA on bus RootBus
giano: FPGA-DEVICE: FPGA on bus RootBus
Configuration Eb63Arm connected ok.

Starting Simulation of Eb63Arm...
giano: MPI interface awaits connection (as \\.\pipe\Giano0Mpi)
giano: Serial line USART0 awaits connection (as \\.\pipe\USART0)
giano: Serial line USART1 awaits connection (as \\.\pipe\USART1)
Simulation Eb63Arm started ok.

@158521 Recalibrate<16000000 16000000 0 0 1> IO<16 1> D<62-62 0>
Starting HW-level simulator for hello.vvp
giano: [PioA.Disable <-- 200]
giano: [PioA.FilterEnable <-- 200]
giano: [PioA.Disable <-- 180001]
giano: [PioA.Disable <-- c0000]

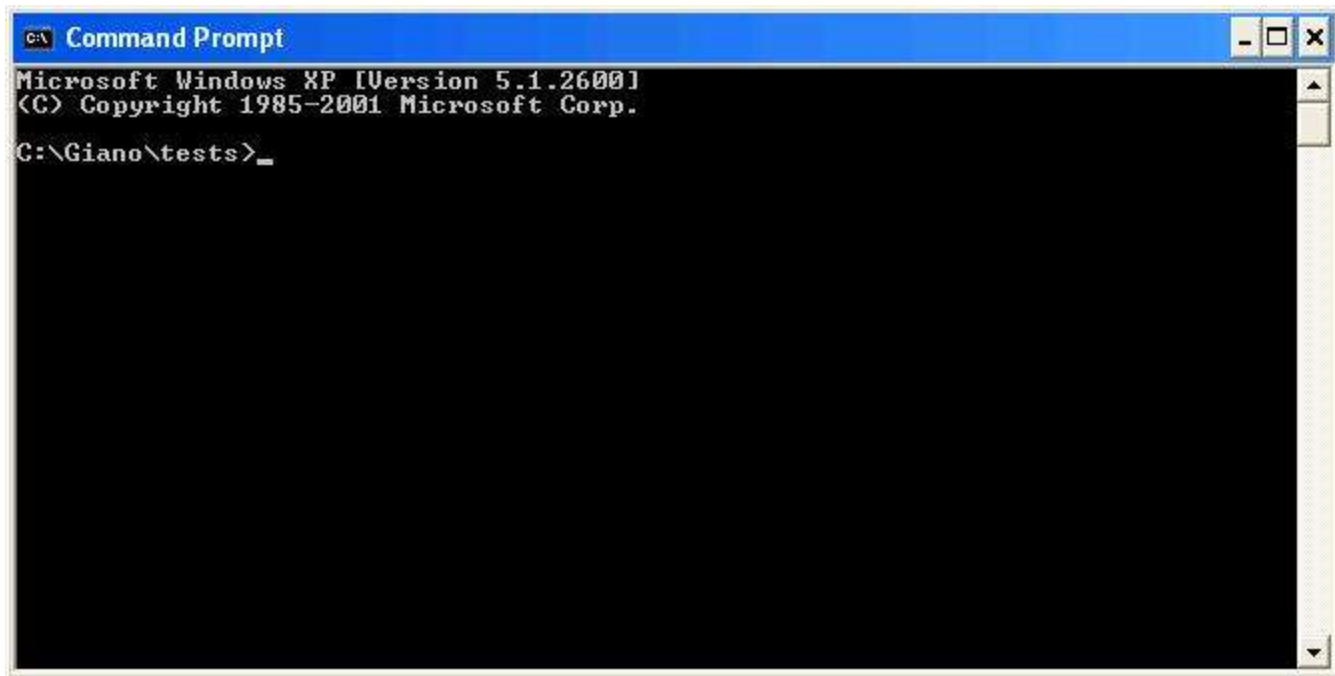
Simulation of Eb63Arm is running...
```

# Procedure #3

- Installing Giano
- Running Simulations in Giano from Visio
- **Running Simulations from the Command Line**
- Connecting to Simulations using Serplexd
- Simulating EB63 with HostFS
- Creating/modifying a configuration
- Creating a new Giano module

# Running Simulations from the Command Line

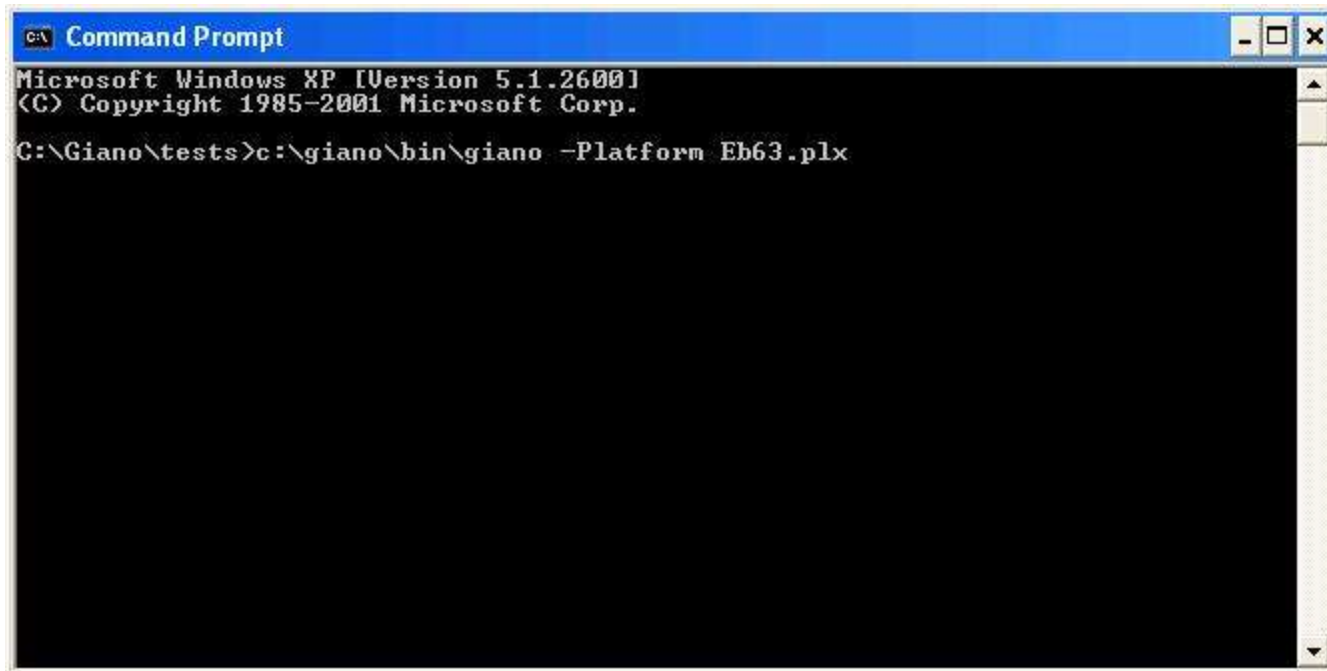
1. Open a Command Prompt to the directory where your \*.plx configuration file is located.



```
Command Prompt
Microsoft Windows XP [Version 5.1.2600]
(C) Copyright 1985-2001 Microsoft Corp.
C:\Giano\tests>
```

# Running Simulations from the Command Line

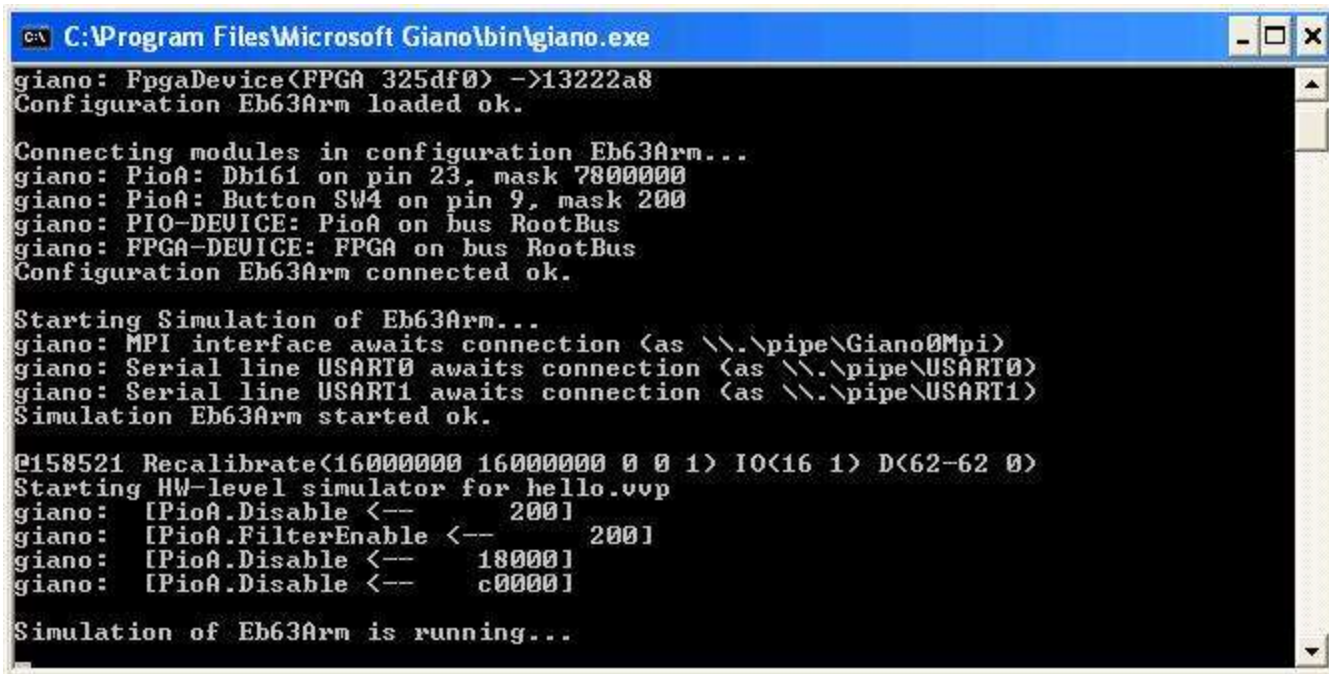
2. Type “giano.exe –Platform <name of \*.plx file>” and press ‘Enter’. The simulation will begin running in this Command Window.



```
c:\ Command Prompt
Microsoft Windows XP [Version 5.1.2600]
(C) Copyright 1985-2001 Microsoft Corp.

C:\Giano\tests>c:\giano\bin\giano -Platform Eb63.plx
```

# Running Simulations from the Command Line



```
C:\Program Files\Microsoft Giano\bin\giano.exe
giano: FpgaDevice<FPGA 325df0> ->13222a8
Configuration Eb63Arm loaded ok.

Connecting modules in configuration Eb63Arm...
giano: PioA: Db161 on pin 23, mask 78000000
giano: PioA: Button SW4 on pin 9, mask 200
giano: PIO-DEVICE: PioA on bus RootBus
giano: FPGA-DEVICE: FPGA on bus RootBus
Configuration Eb63Arm connected ok.

Starting Simulation of Eb63Arm...
giano: MPI interface awaits connection (as \\.\pipe\Giano0Mpi)
giano: Serial line USART0 awaits connection (as \\.\pipe\USART0)
giano: Serial line USART1 awaits connection (as \\.\pipe\USART1)
Simulation Eb63Arm started ok.

@158521 Recalibrate<16000000 16000000 0 0 1> IO<16 1> D<62-62 0>
Starting HW-level simulator for hello.svp
giano: [PioA.Disable <-- 200]
giano: [PioA.FilterEnable <-- 200]
giano: [PioA.Disable <-- 18000]
giano: [PioA.Disable <-- c0000]

Simulation of Eb63Arm is running...
```

# Procedure #4

- Installing Giano
- Running Simulations in Giano from Visio
- Running Simulations from the Command Line
- **Connecting to Simulations using Serplexd**
- Simulating EB63 with HostFS
- Creating/modifying a configuration
- Creating a new Giano module



# Connecting to Simulation using Serplexd

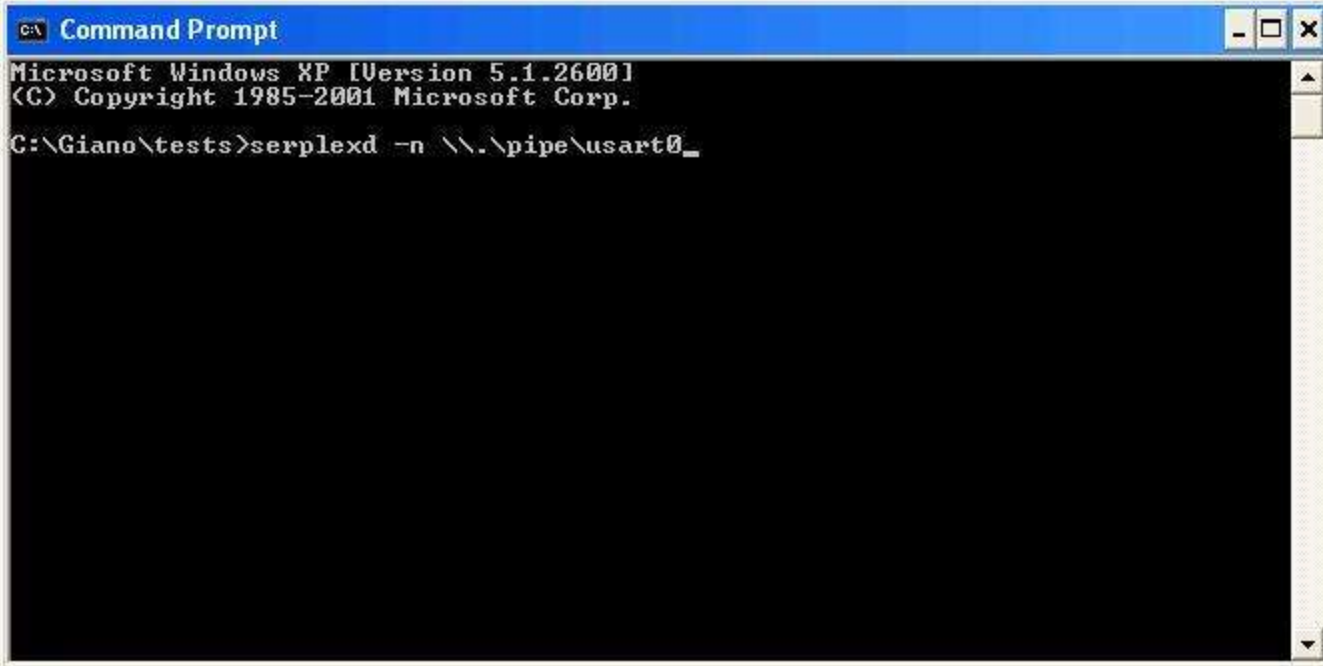
1. Open a Command Prompt to the directory where serplexd.exe is located, e.g. Giano\tests.



```
Command Prompt
Microsoft Windows XP [Version 5.1.2600]
(C) Copyright 1985-2001 Microsoft Corp.
C:\Giano\tests>_
```

# Connecting to Simulation using Serplexd

2. Type 'serplexd -n \\.\\pipe\\usart0' and press 'Enter'. Serplexd will begin running in this Command Window.



```
c:\ Command Prompt
Microsoft Windows XP [Version 5.1.2600]
(C) Copyright 1985-2001 Microsoft Corp.
C:\Giano\tests>serplexd -n \\.\\pipe\\usart0_
```

# Connecting to Simulation using Serplexd



```
C:\ Command Prompt - serplexd -n \\.\pipe\usart0
Microsoft Windows XP [Version 5.1.2600]
(C) Copyright 1985-2001 Microsoft Corp.

C:\Giano\tests>serplexd -n \\.\pipe\usart0
Will NOT attempt to use the NIC
GetCommState() failed on \\.\pipe\usart0 (xd)
SetCommState() failed on \\.\pipe\usart0 (xd)
SetCommTimeouts() failed (xd), ignoring..
Console Thread ...
```

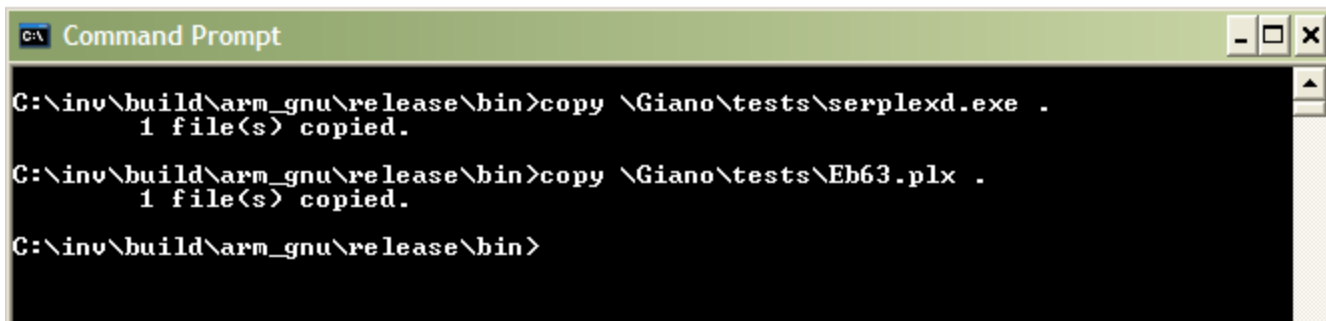


# Procedure #5

- Installing Giano
- Running Simulations in Giano from Visio
- Running Simulations from the Command Line
- Connecting to Simulations using Serplexd
- **Simulating EB63 with HostFS**
- Creating/modifying a configuration
- Creating a new Giano module

# Simulating EB63 with HostFS

1. Build MMLite (compile source code)
2. Copy serplexd to MMLite build directory bin of the desired compiler (EX. C:\inv\build\arm\_gnu\release\bin)
3. Copy the \*.plx configuration file to the MMLite build directory



```
C:\ Command Prompt
C:\inv\build\arm_gnu\release\bin>copy \Giano\tests\serplexd.exe .
        1 file(s) copied.
C:\inv\build\arm_gnu\release\bin>copy \Giano\tests\Eb63.plx .
        1 file(s) copied.
C:\inv\build\arm_gnu\release\bin>
```

# Simulating EB63 with HostFS

4. Run Microsoft Giano in the Command Line with the following in the location of the Eb63.plx file:  
giano.exe -Platform Eb63.plx  
FLASH::PermanentStorage eb63.bin



```
C:\> Command Prompt
C:\inv\build\arm_gnu\release\bin>giano -Platform Eb63.plx FLASH::PermanentStorage eb63.bin_
```

# Simulating EB63 with HostFS

```
C:\ Command Prompt - giano -Platform Eb63.plx FLASH::PermanentStorage eb63.bin
C:\inv\build\arm_gnu\release\bin>giano -Platform Eb63.plx FLASH::PermanentStorage eb63.bin

Loading modules in configuration Eb63Arm...
giano: PioDevice<PioA 369d10 3fffffff 200> ->934010
giano: FpgaDevice<FPGA 369168> ->934f58
giano: Could not read optional file romfs.bin into 10100000..10280000

Configuration Eb63Arm loaded ok.

Connecting modules in configuration Eb63Arm...
giano: PioA: Db161 on pin 23, mask 7800000, inter -1
giano: PioA: Button SW4 on pin 9, mask 200, inter -1
giano: PIO-DEVICE: PioA on bus RootBus
giano: FPGA-DEVICE: FPGA on bus RootBus
Configuration Eb63Arm connected ok.

Starting Simulation of Eb63Arm...
giano: MPI interface awaits connection (as \\.\pipe\Giano0Mpi)
giano: Serial line USART0 awaits connection (as \\.\pipe\USART0)
giano: USART1: 9600 baud, 8 bits per char, no parity, 1 stop bits
giano: Serial line USART1 is connected to com1:
Simulation Eb63Arm started ok.

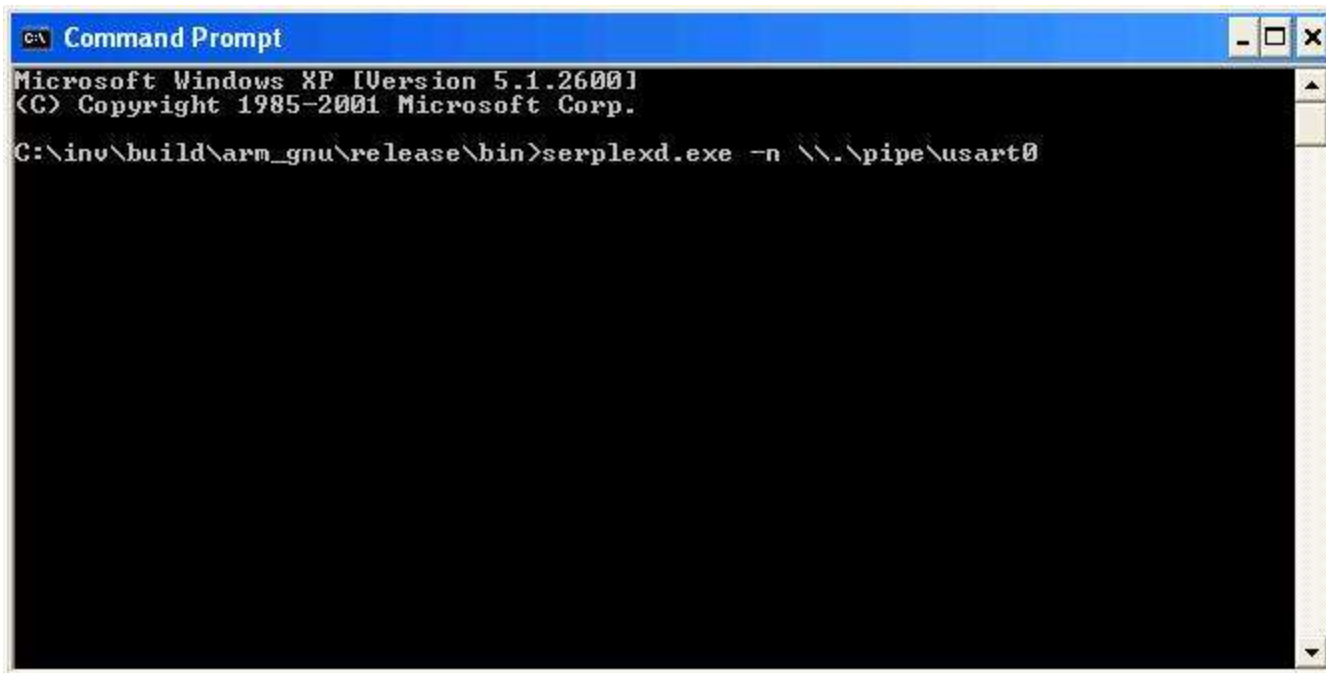
@16829 Recalibrate<12000000 12000000 0 0 1> IO<12 1> D<83-83 0>
giano: [PioA.Disable <-- 200]
giano: [PioA.FilterEnable <-- 200]
giano: [PioA.Disable <-- 18000]
giano: [PioA.Disable <-- c0000]
giano: USART1: 38109 baud, 8 bits per char, no parity, 1 stop bits
Starting HW-level simulator for hello.vvp
giano: USART1: 38109 baud, 8 bits per char, no parity, 1 stop bits

Simulation of Eb63Arm is running...
```



# Simulating EB63 with HostFS

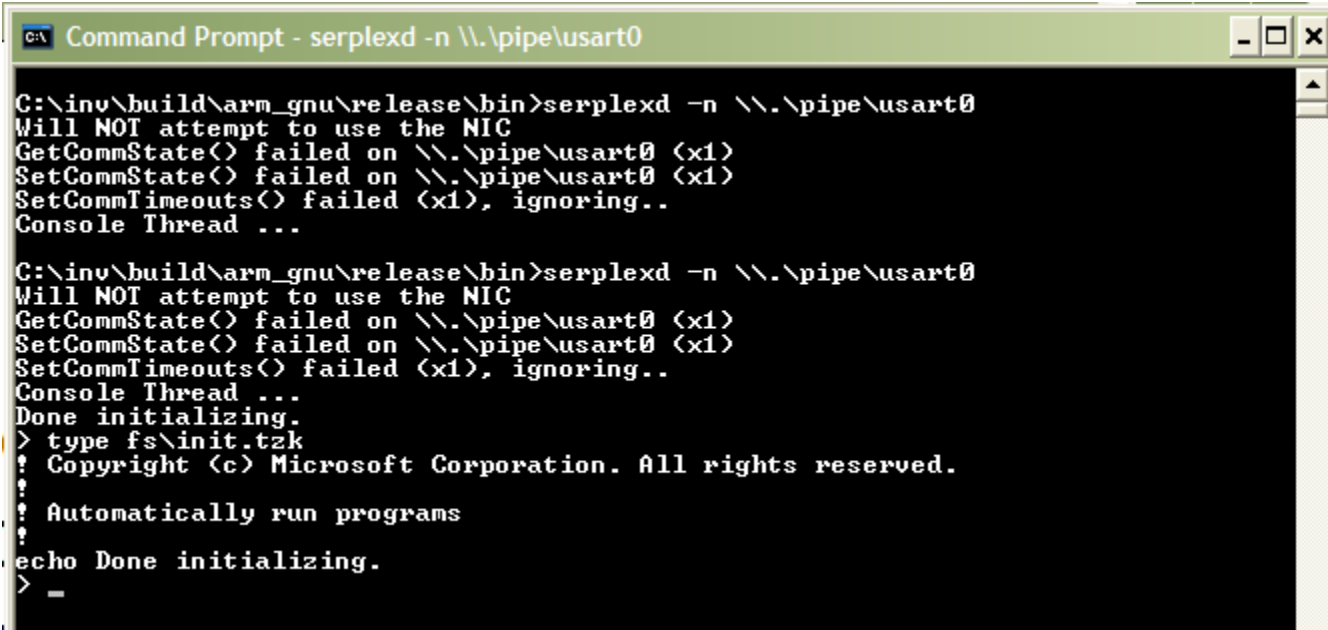
5. Run serplexd.exe from the MMLite build directory bin.



```
c:\ Command Prompt
Microsoft Windows XP [Version 5.1.2600]
(C) Copyright 1985-2001 Microsoft Corp.
C:\inv\build\arm_gnu\release\bin>serplexd.exe -n \\.\pipe\usart0
```

# Simulating EB63 with HostFS

6. After a short time you should see the 'Done Prompt' to inform you that it has completed loading the first program from HostFS



```
C:\> Command Prompt - serplexd -n \\.\pipe\usart0
C:\inv\build\arm_gnu\release\bin>serplexd -n \\.\pipe\usart0
Will NOT attempt to use the NIC
GetCommState() failed on \\.\pipe\usart0 (x1)
SetCommState() failed on \\.\pipe\usart0 (x1)
SetCommTimeouts() failed (x1), ignoring..
Console Thread ...

C:\inv\build\arm_gnu\release\bin>serplexd -n \\.\pipe\usart0
Will NOT attempt to use the NIC
GetCommState() failed on \\.\pipe\usart0 (x1)
SetCommState() failed on \\.\pipe\usart0 (x1)
SetCommTimeouts() failed (x1), ignoring..
Console Thread ...
Done initializing.
> type fs\init.tzk
! Copyright (c) Microsoft Corporation. All rights reserved.
!
! Automatically run programs
!
echo Done initializing.
>
> =
```

# Procedure #6

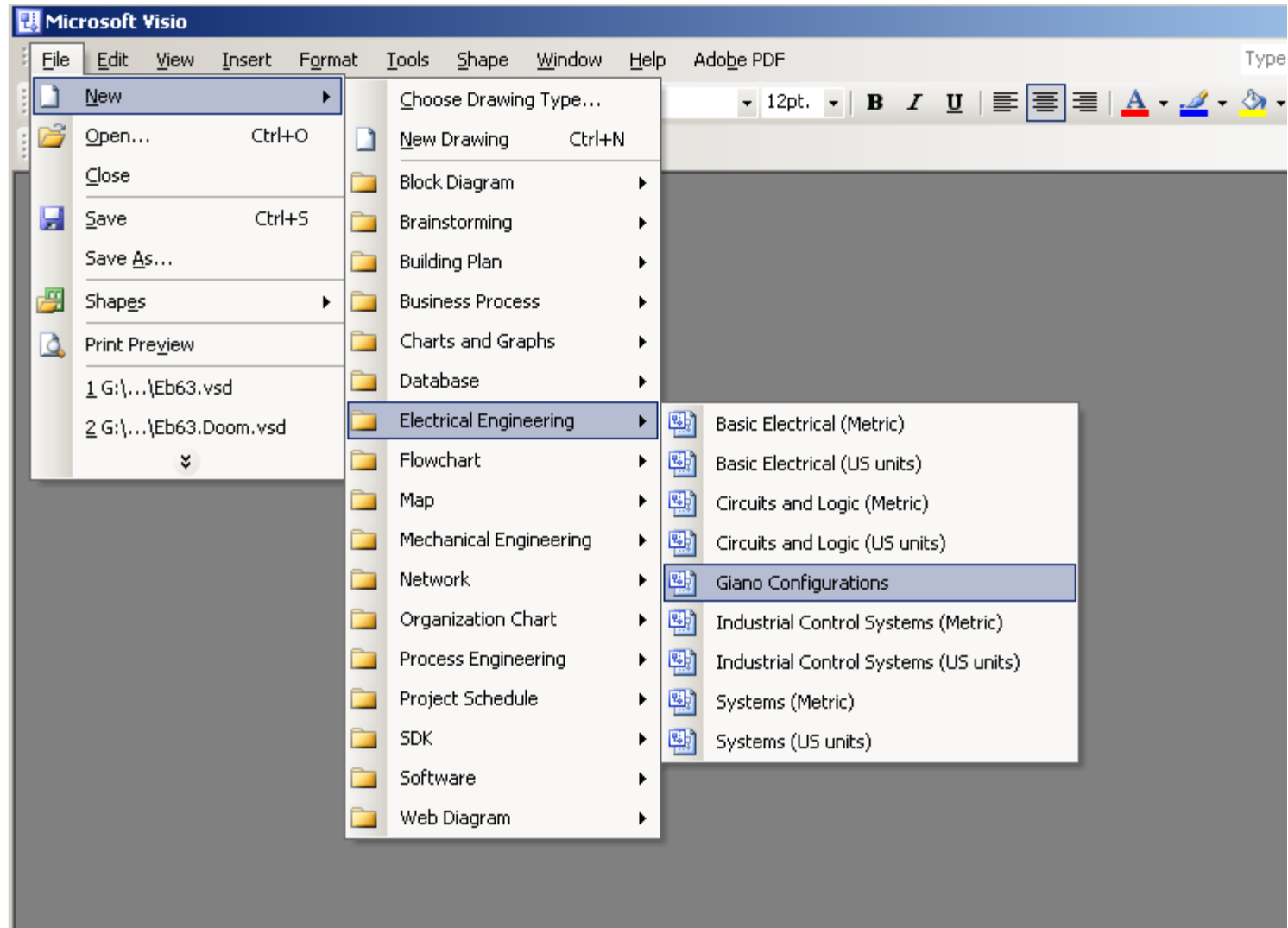
- Installing Giano
- Running Simulations in Giano from Visio
- Running Simulations from the Command Line
- Connecting to Simulations using Serplexd
- Simulating EB63 with HostFS
- **Creating/modifying a configuration**
- Creating a new Giano module

# Creating/modifying a Configuration

- 1- Start Visio and select File::New::Electrical Engineering::Giano Configurations or..
- 1a- Open an existing .VSD configuration

*Note: the .plx file is just XML, you can edit it directly but Visio is much easier*

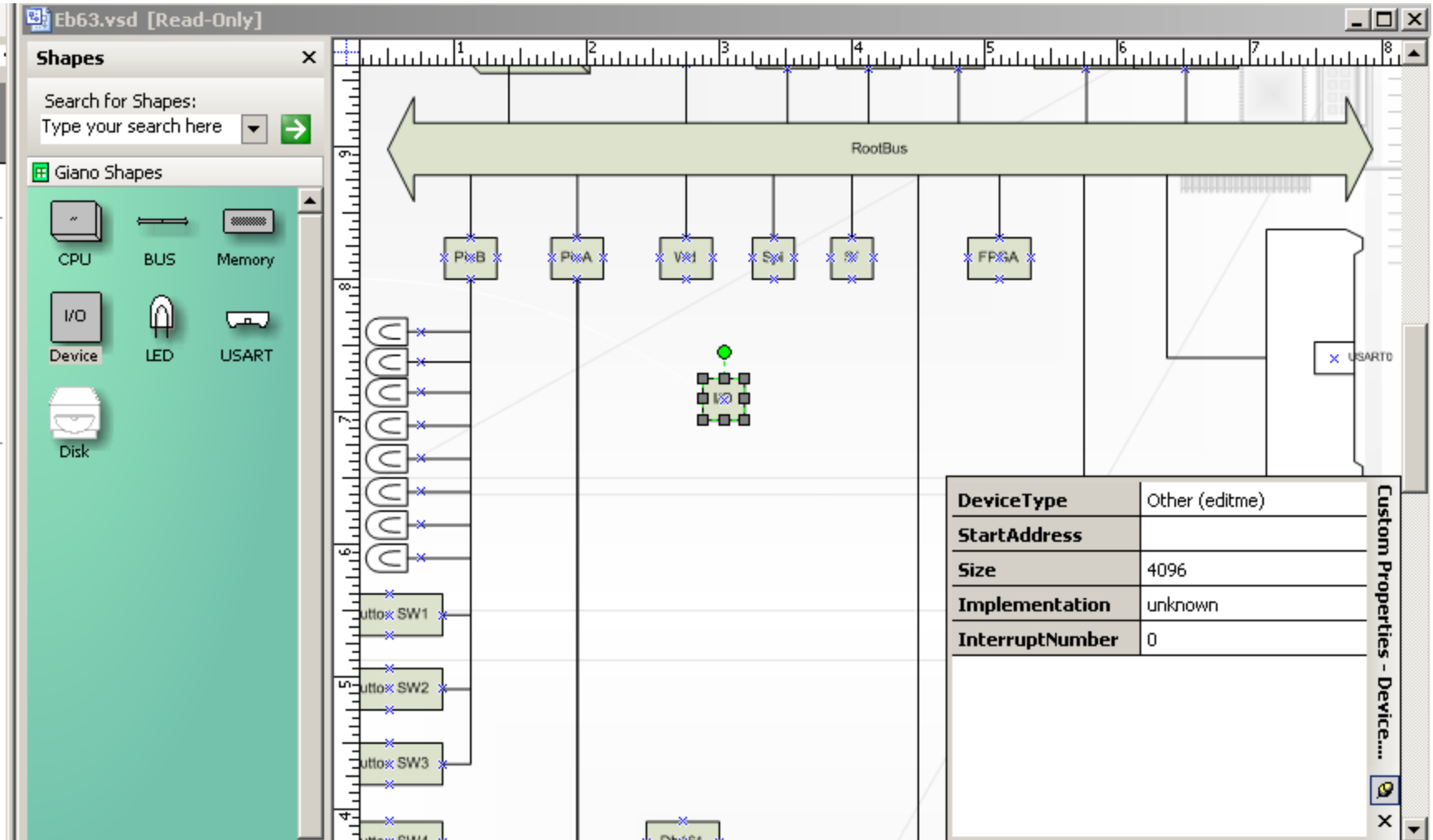
# Creating/modifying a Configuration



# Creating/modifying a Configuration

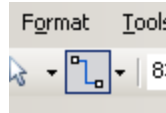
2- Drag&drop new objects from “Giano Shapes” to your configuration

# Creating/modifying a Configuration



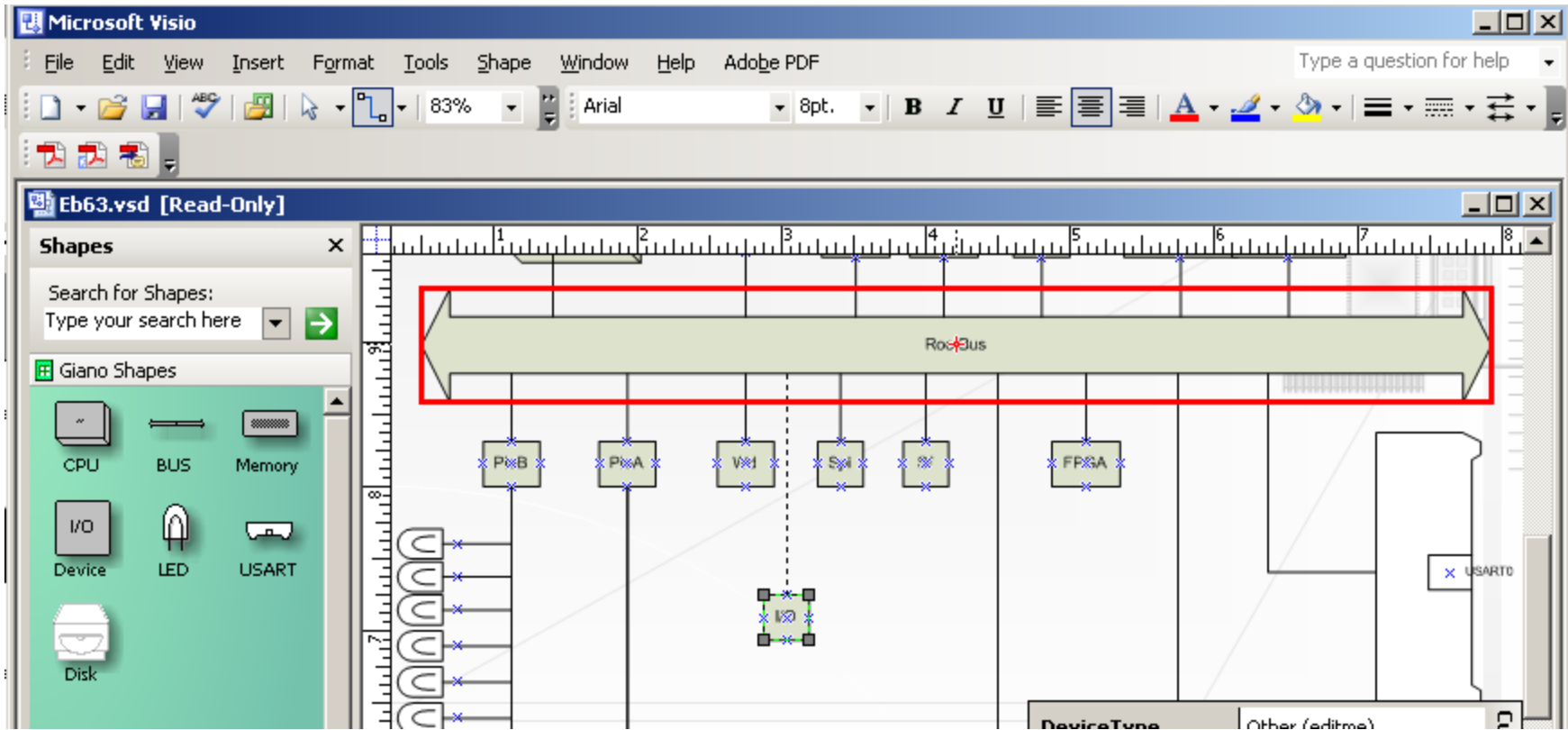
# Creating/modifying a Configuration

3- Connect objects with the “Connector Tool”:

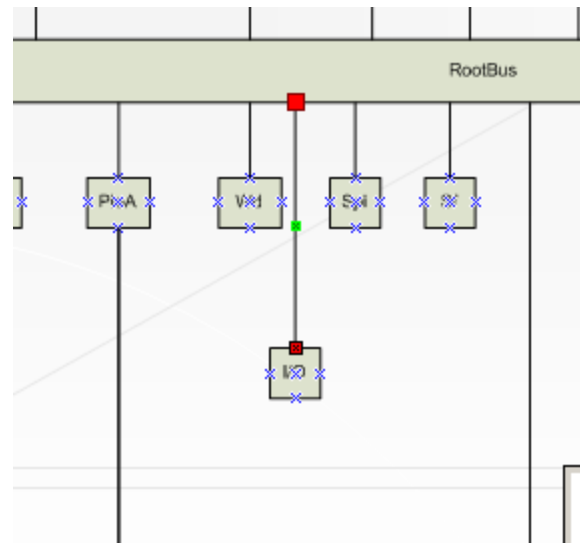




# Creating/modifying a Configuration



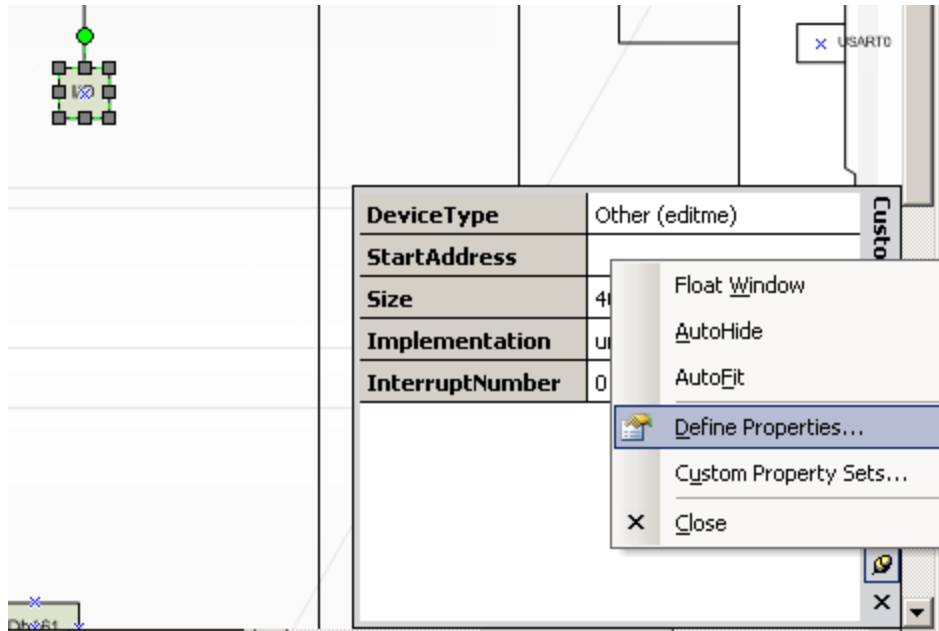
# Creating/modifying a Configuration



# Creating/modifying a Configuration

- 4- Edit an object properties by selecting it and working on the “Custom Properties”
- 5- Add/Remove properties by right-clicking on the Custom Properties and selecting “Define Properties”

# Creating/modifying a Configuration



# Creating/modifying a Configuration

The screenshot shows the 'Define Custom Properties' dialog box in a software development environment. The dialog is titled 'Define Custom Properties' and has a close button (X) in the top right corner. It contains the following fields and options:

- Label:** DeviceType
- Type:** Variable List (dropdown menu)
- Language:** English (U.S.) (dropdown menu)
- Format:** InterruptController;Timer;C (dropdown menu)
- Calendar:** (dropdown menu)
- Value:** Other (editme)
- Prompt:** Type of this Device

Below these fields is a 'Properties:' section with a table listing various properties:

Label	Type	Format
DeviceType	Variable List	InterruptCon...
StartAddress	Number	#####
Size	Number	#####
IsaGianoShape	Boolean	
Implementation	String	@
InterruptNumber	Number	0

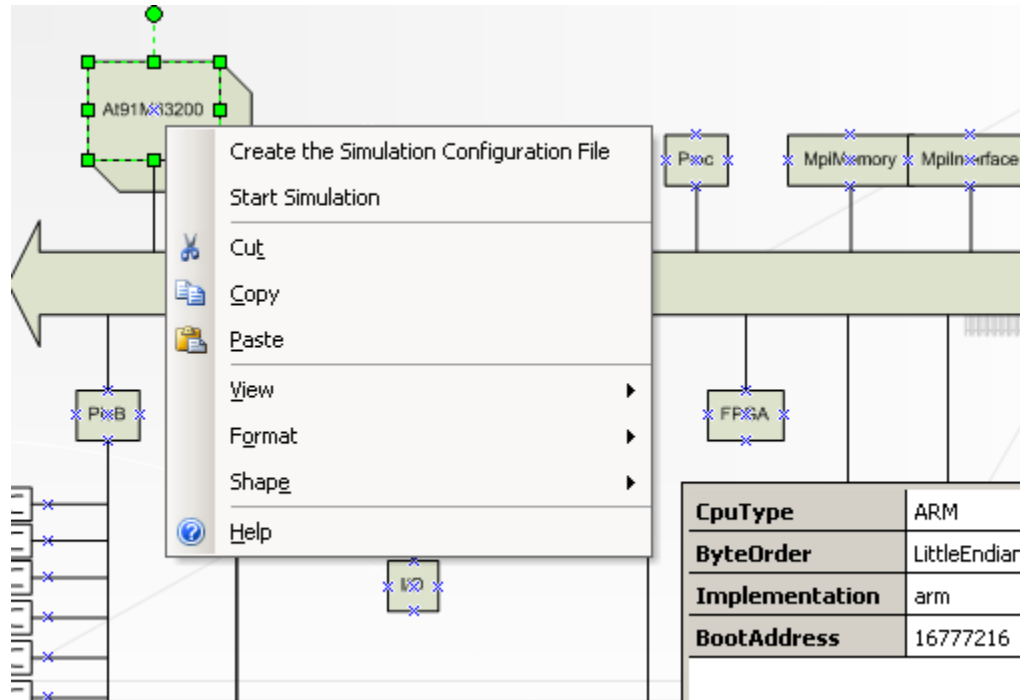
At the bottom of the dialog are buttons for 'New', 'Delete', 'OK', and 'Cancel'. To the right of the dialog, a portion of the main application window is visible, showing a schematic diagram with components like 'FPGA' and 'USART0'. A large green arrow points from the 'DeviceType' field in the dialog towards the schematic. Below the schematic, a 'Custom Properties - Device...' table is visible, showing the values for the properties defined in the dialog:

Property	Value
DeviceType	Other (editme)
StartAddress	
Size	4096
Implementation	unknown
InterruptNumber	0

# Creating/modifying a Configuration

- 6- Save your new configuration with  
File::SaveAs
- 7- Create your .PLX file by right-clicking on a CPU module and selecting “Create the Simulation Configuration File”
- 8- Run your new configuration

# Creating/modifying a Configuration



# Procedure #7

- Installing Giano
- Running Simulations in Giano from Visio
- Running Simulations from the Command Line
- Connecting to Simulations using Serplexd
- Simulating EB63 with HostFS
- Creating/modifying a configuration
- **Creating a new Giano module**

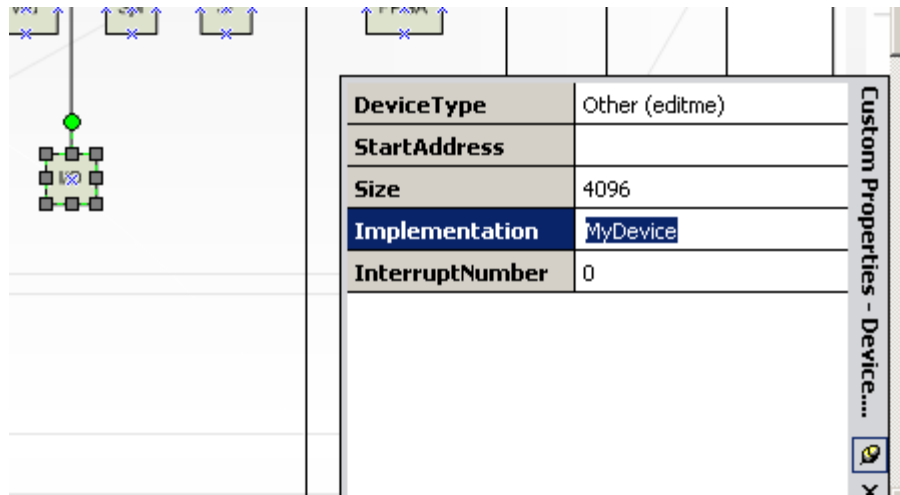


# Creating a new Giano module

- 1- Create a suitable new object in your configuration and change the “Implementation” property to the name of your new device, such as “MyDevice”

*Note: We will create a new Device object. Busses, CPUs and memories are similar*

# Creating a new Giano module



The screenshot displays a software interface for creating a new Giano module. On the left, a hardware diagram shows a central green dot connected to a 3x3 grid of smaller squares, with a blue 'X' in the center square. Above the diagram are several rectangular boxes with blue 'X' marks. On the right, a 'Custom Properties' table is visible, containing the following data:

Property	Value
DeviceType	Other (editme)
StartAddress	
Size	4096
Implementation	MyDevice
InterruptNumber	0

The table is titled 'Custom Properties - Device...' and includes a search icon and a close button (X) at the bottom right.

# Creating a new Giano module

- 2- Go to the Peripherals folder and copy the template file Unknown.cpp to MyDevice.cpp
- 3- Edit the file as needed to implement your functionality

*Note: To debug you should build Giano for debugging with "nmake clean debug"*

# Creating a new Giano module

```
emacs@GTB4
File Edit Options Buffers Tools C++ Help

    int Debug;
};

#define DPRINTF(x) if (Debug) Giano->Verbosef x

/* BUS_INTERFACE
*/
void MyDevice::Fetch(ADDRESS Address, void *Destination, unsigned int nBytes)
{
    DPRINTF ( ("%ls.Fetch(%x,@%x,%d) ", MyName, Address, Destination, nBytes) );
    memset (Destination, 0xaa, nBytes);
}

void MyDevice::Store(ADDRESS Address, void *Source, unsigned int nBytes)
{
    DPRINTF ( ("%ls.Store(%x,@%x,%d) ", MyName, Address, Source, nBytes) );
}
}
```

# Creating a new Giano module

4- Edit the `Peripherals\makefile` to build your module along with the others

# Creating a new Giano module

```
emacs@GTB4
File Edit Options Buffers Tools Makefile Help

$(BINDIR)\epmc.dll $(BINDIR)\epio.dll \
$(BINDIR)\frame.dll $(BINDIR)\simpal.dll $(BINDIR)\gsound.dll \
$(BINDIR)\simkbd.dll $(BINDIR)\simms.dll \
$(BINDIR)\dbg.dll \
$(BINDIR)\unknown.dll $(BINDIR)\MyDevice.dll

INCLUDES = -I..
LFLAGS = -merge:.rdata=.text -merge:.bss=.data
LIBRARIES = msvcrt.lib kernel32.lib
--\-- makefile (Makefile)--L23--23%-----

..\GianoModule.h: ..\ConfigManager.h ..\GianoConfig.h

# Generic, do-nothing I/O device
$(BINDIR)\unknown.obj: unknown.cpp ..\GianoModule.h
$(BINDIR)\MyDevice.obj: MyDevice.cpp ..\GianoModule.h
# I/O Devices (EBI, real)
$(BINDIR)\aic.obj: aic.cpp ..\GianoModule.h
$(BINDIR)\tc.obj: tc.cpp ..\GianoModule.h
--\-- makefile (Makefile)--L47--42%-----
```

# Creating a new Giano module

5- Rebuild from the top with “nmake debug”

# Creating a new Giano module

```
N:\Giano>pushd Peripherals && nmake /nologo /L install DEFS="-D_X86_=1 -Di386=1 -D_MT=1 -DSTD_CALL -D_WIN32_WINNT=0x0500 -DFPO=0 -D_DEBUG -DDBG=1 -DDEUL=1 -D_GIANO_=1 -D_CRT_SECURE_NO_DEPRECATED=1" FLAGS="/Z1 /Zp8 /Gy /W4 /WX /Gz /Gm- /EHs-c- /GR- /GF /GS /RTCsu -Z7 /Od /Oy- /MTd" SIXTY4="" LIBRARIES="..\lib\GianoModule.lib winmm.lib msvcrt.lib gdi32.lib user32.lib advapi32.lib" && popd

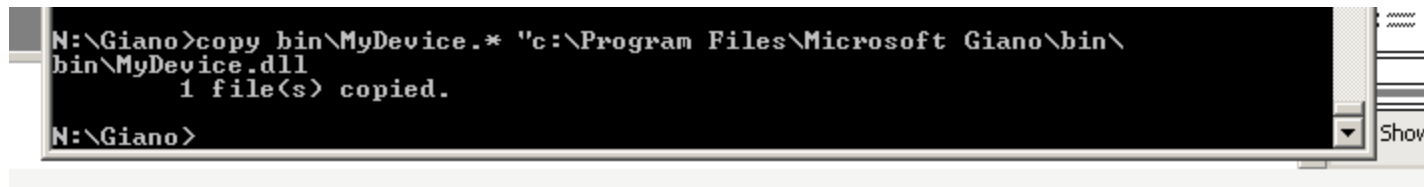
      cl /nologo /c /Fo".\bin\" /Fd".\bin\" -D_X86_=1 -Di386=1 -D_MT=1 -DSTD_CALL -D_WIN32_WINNT=0x0500 -DFPO=0 -D_DEBUG -DDBG=1 -DDEUL=1 -D_GIANO_=1 -D_CRT_SECURE_NO_DEPRECATED=1 /Z1 /Zp8 /Gy /W4 /WX /Gz /Gm- /EHs-c- /GR- /GF /GS /RTCsu -Z7 /Od /Oy- /MTd -I.. MyDevice.cpp
Command line warning D4002 : ignoring unknown option '/GS'
Command line warning D4002 : ignoring unknown option '/RTCsu'
MyDevice.cpp
      cl /nologo /Z1 /Zp8 /Gy /W4 /WX /Gz /Gm- /EHs-c- /GR- /GF /GS /RTCsu -Z7 /Od /Oy- /MTd /Fm /LD -o .\bin\MyDevice.dll .\bin\MyDevice.obj /link -merge:.rdata=.text -merge:.bss=.data ..\lib\GianoModule.lib winmm.lib msvcrt.lib gdi32.lib user32.lib advapi32.lib
Command line warning D4002 : ignoring unknown option '/GS'
Command line warning D4002 : ignoring unknown option '/RTCsu'
LINK : LNK6004: .\bin\MyDevice.dll not found or not built by the last incremental link; performing full link
      Creating library .\bin\MyDevice.lib and object .\bin\MyDevice.exp
LINK : warning LNK4078: multiple ".text" sections found with different attributes (40000040)
LINK : warning LNK4078: multiple ".data" sections found with different attributes (C0000080)

N:\Giano\Peripherals>copy /y .\bin\aic.dll ..\bin\aic.dll
1 file(s) copied.
```



# Creating a new Giano module

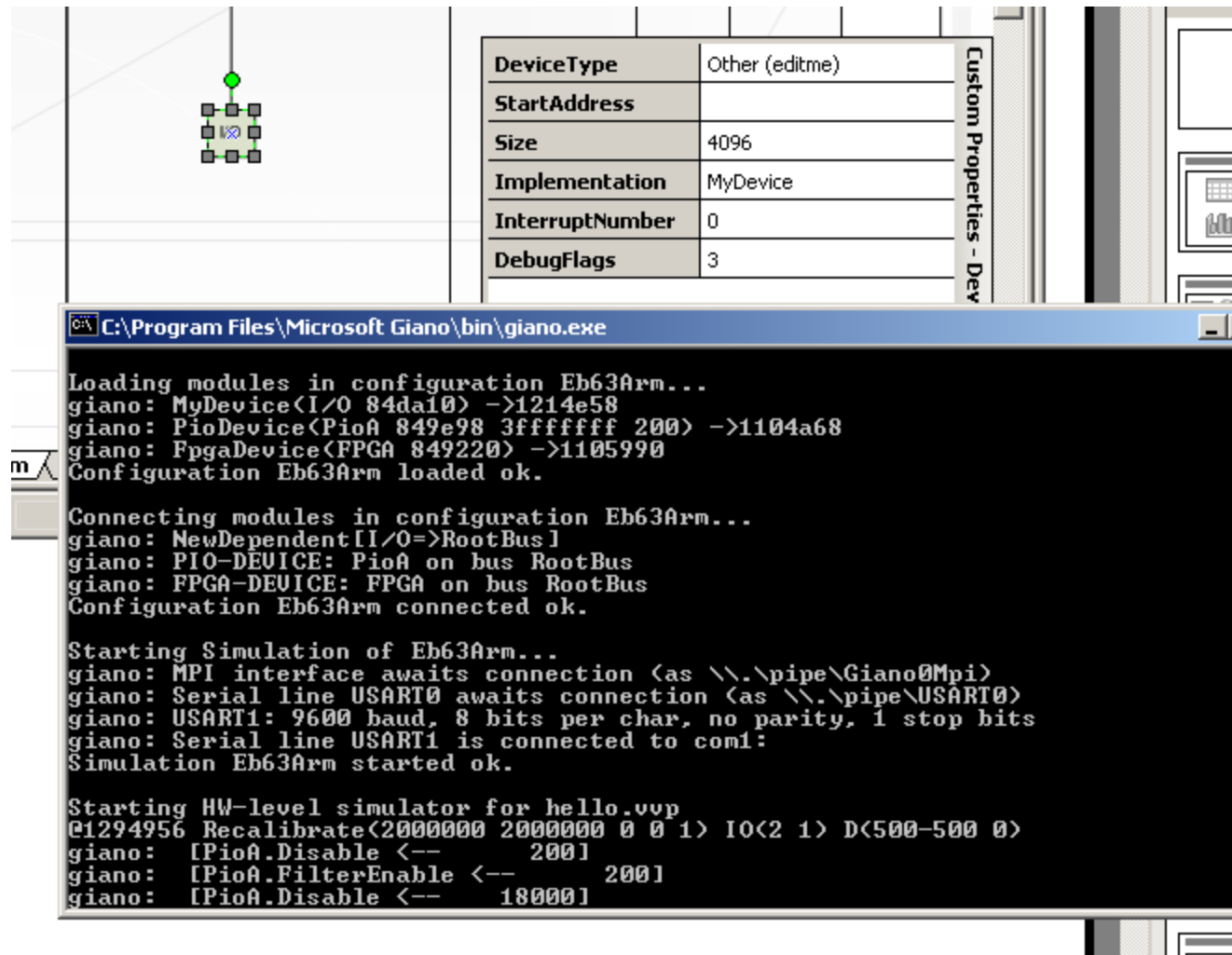
6- Copy your module in the installation directory



```
N:\Giano>copy bin\MyDevice.* "c:\Program Files\Microsoft Giano\bin\  
bin\MyDevice.dll  
1 file(s) copied.  
N:\Giano>
```

7- Add the “DebugFlags” property to your device and try out your configuration

# Creating a new Giano module



The screenshot displays the Giano software interface. On the left, a small schematic diagram shows a central green component connected to a grid of other components. On the right, a table titled 'Custom Properties - Dev' lists the configuration for a device. Below this, a terminal window shows the execution of the Giano simulator, including module loading, connection, and simulation start messages.

Property	Value
DeviceType	Other (editme)
StartAddress	
Size	4096
Implementation	MyDevice
InterruptNumber	0
DebugFlags	3

```
C:\Program Files\Microsoft Giano\bin\giano.exe
Loading modules in configuration Eb63Arm...
giano: MyDevice<I/O 84da10> ->1214e58
giano: PioDevice<PioA 849e98 3fffffff 200> ->1104a68
giano: FpgaDevice<FPGA 849220> ->1105990
Configuration Eb63Arm loaded ok.

Connecting modules in configuration Eb63Arm...
giano: NewDependent[I/O=>RootBus]
giano: PIO-DEVICE: PioA on bus RootBus
giano: FPGA-DEVICE: FPGA on bus RootBus
Configuration Eb63Arm connected ok.

Starting Simulation of Eb63Arm...
giano: MPI interface awaits connection (as \\.\pipe\Giano0Mpi)
giano: Serial line USART0 awaits connection (as \\.\pipe\USART0)
giano: USART1: 9600 baud, 8 bits per char, no parity, 1 stop bits
giano: Serial line USART1 is connected to com1:
Simulation Eb63Arm started ok.

Starting HW-level simulator for hello.vvp
01294956 Recalibrate(2000000 2000000 0 0 1) IO(2 1) D(500-500 0)
giano: [PioA.Disable <-- 200]
giano: [PioA.FilterEnable <-- 200]
giano: [PioA.Disable <-- 18000]
```