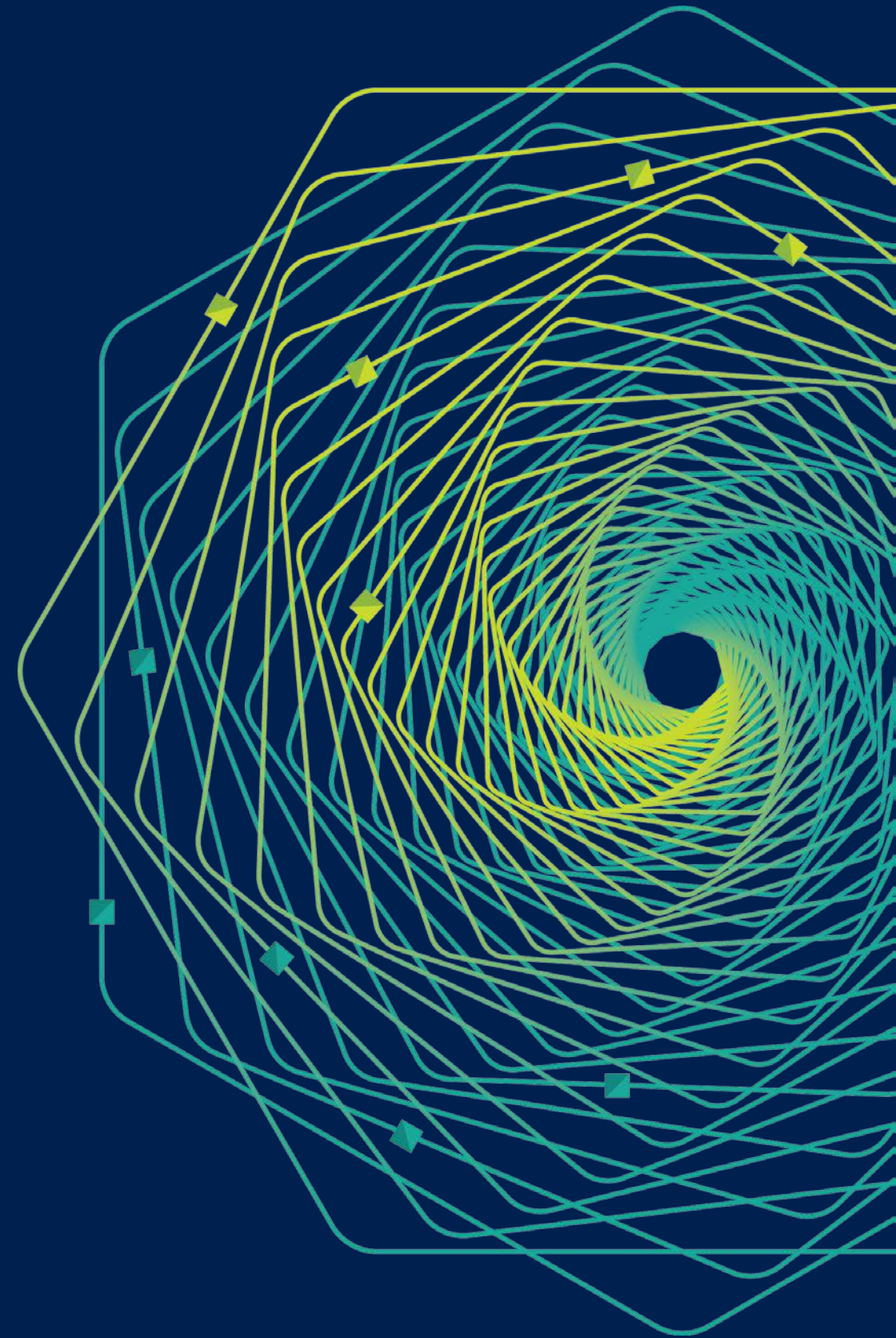
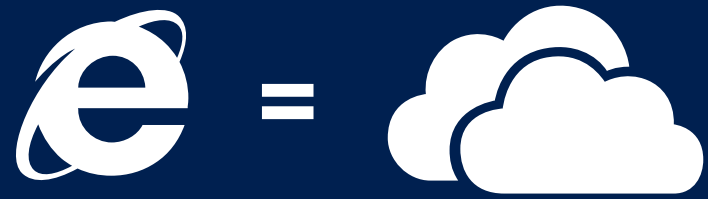




Research Faculty Summit 2018

Systems | Fueling future disruptions

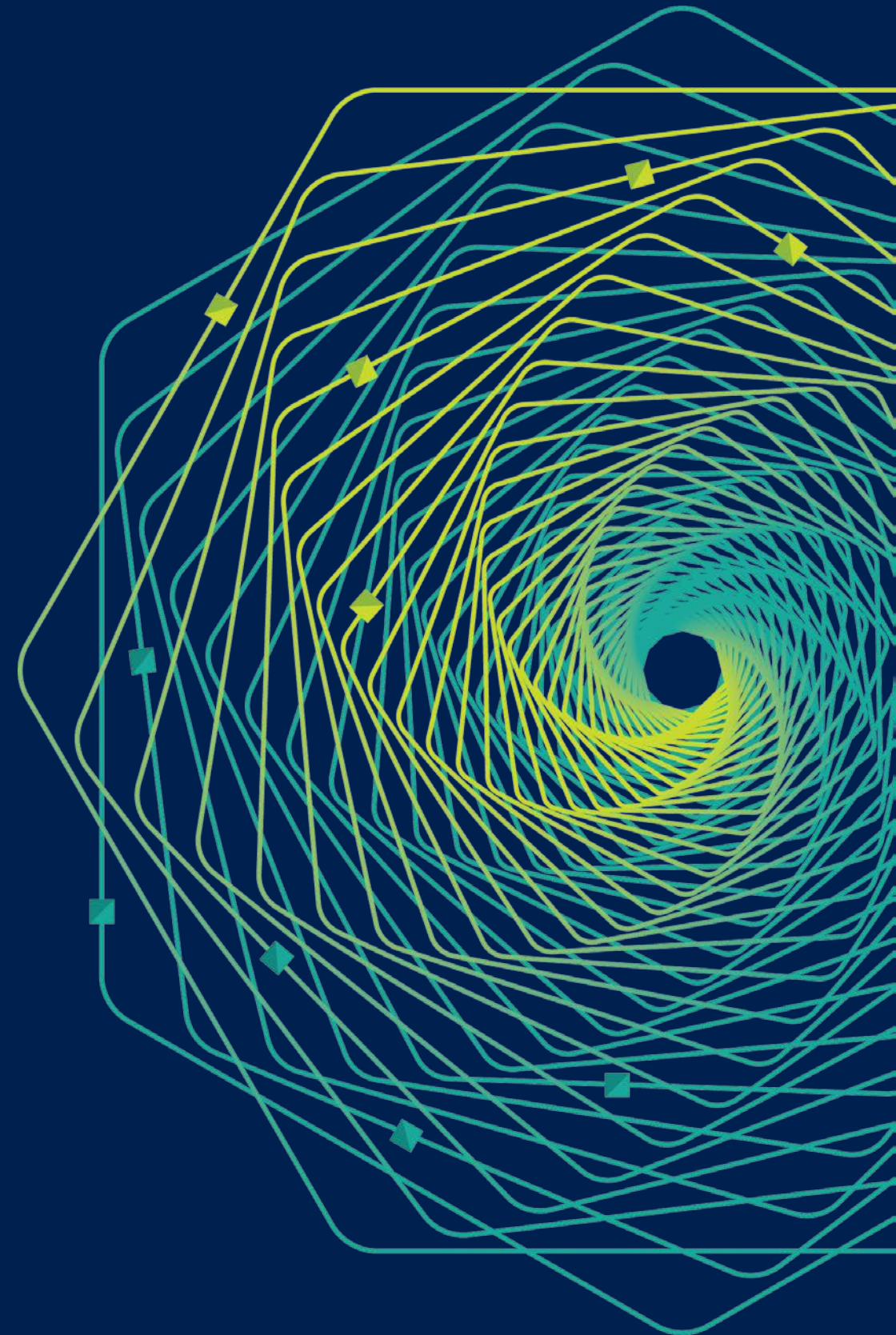




Elevating the Edge to be a Peer of the Cloud

Kishore Ramachandran

Embedded Pervasive Lab, Georgia Tech



Acknowledgements



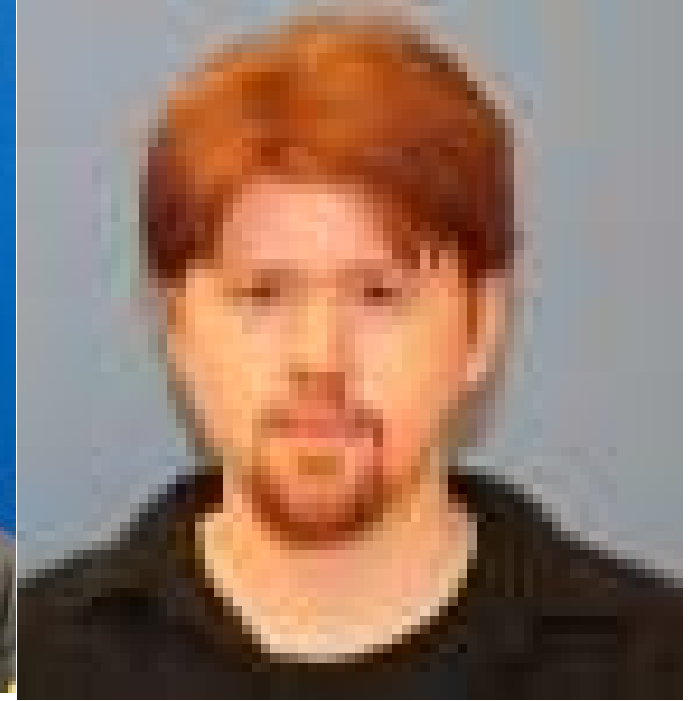
Enrique Saurez



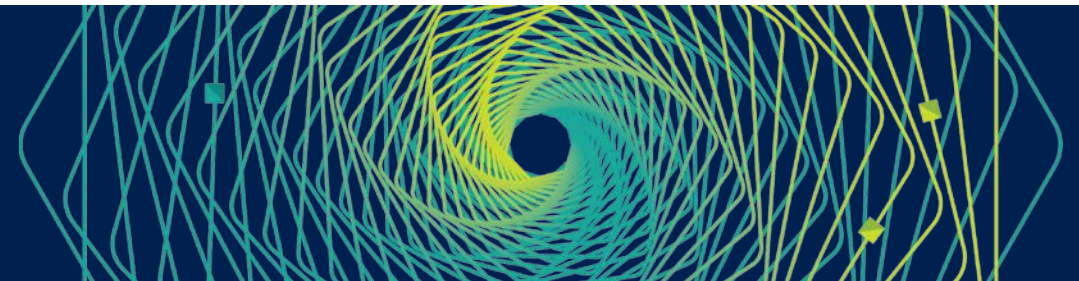
Harshit Gupta



Zhuangdi Xu



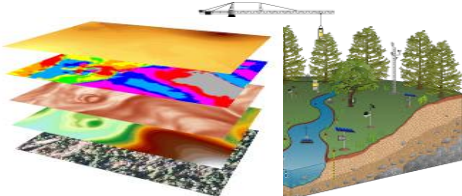
Adam Hall



A Broad Set of IoT Applications



Predictive maintenance



Enable New Knowledge



Agriculture



Smart Grid

Energy Saving (I2E)



Intelligent Buildings



Defense



Industrial Automation



Transportation and Connected Vehicles

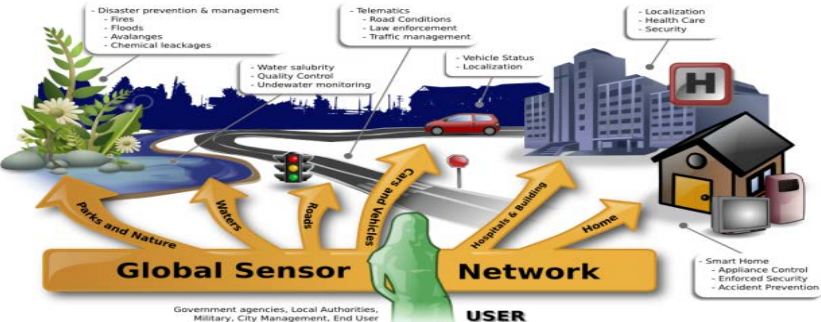


Healthcare

Enhance Safety & Security



Smart Home



Thanks to CISCO for this slide

Future Internet Applications on IoT

- Sense -> Process -> Actuate
- Common Characteristics
 - Dealing with real-world data streams
 - Real-time interaction among mobile devices
 - Wide-area analytics
- Requirements
 - Dynamic scalability
 - Low-latency communication
 - Efficient in-network processing

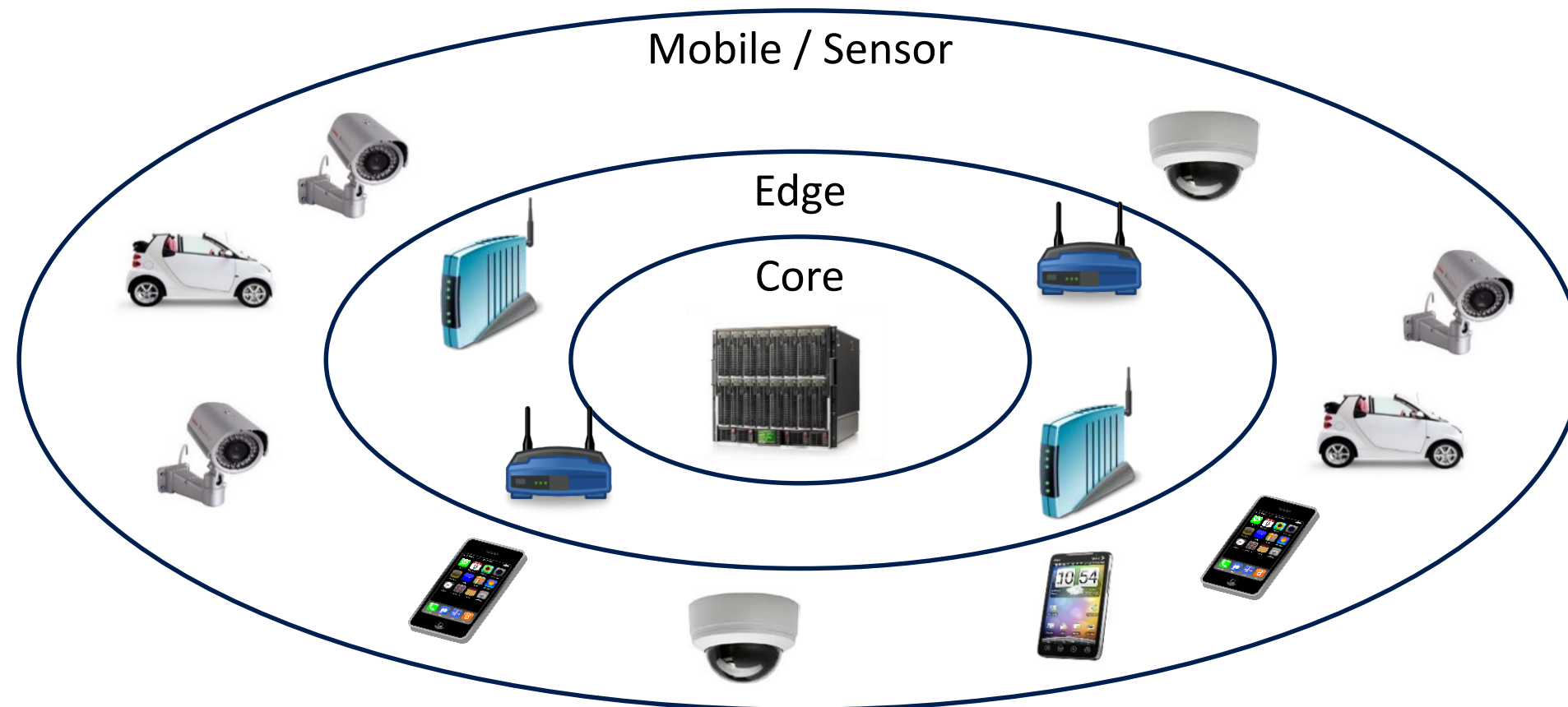


Cloud Computing

- Good for web apps at human perception speeds
 - Throughput oriented web apps with human in the loop
- Not good for many latency-sensitive IoT apps at computational perception speeds
 - sense -> process -> actuate
- Other considerations
 - Limited by backhaul bandwidth for transporting plethora of 24x7 sensor streams
 - Not all sensor streams meaningful
 - => Quench the streams at the source
 - Privacy and regulatory requirements

Fog/Edge Computing

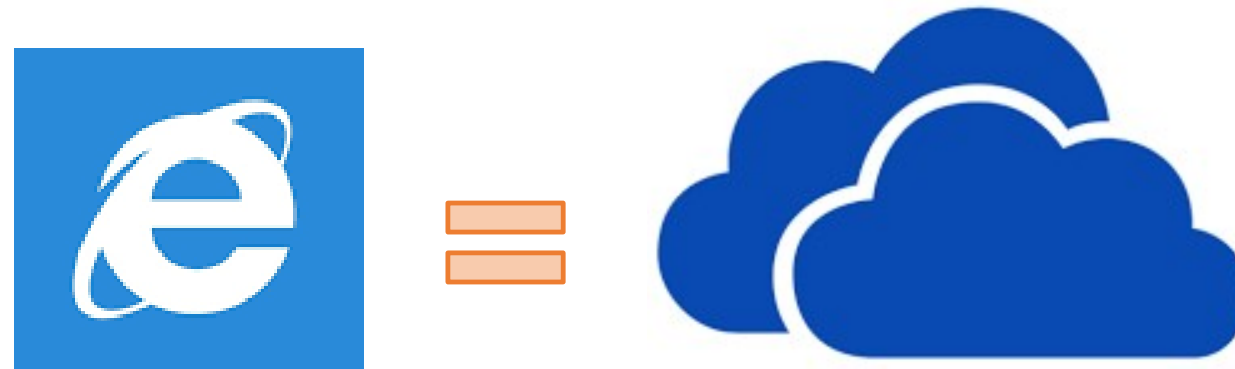
- Extending the cloud utility computing to the edge
- Provide utility computing using resources that are
 - Hierarchical
 - Geo-distributed



Fog/edge computing today

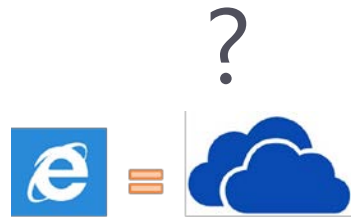
- Edge is slave of the Cloud
 - Platforms: IoT Azure Edge, CISCO Iox, Intel FRD, ...
- Mobile apps beholden to the Cloud

Vision for the future

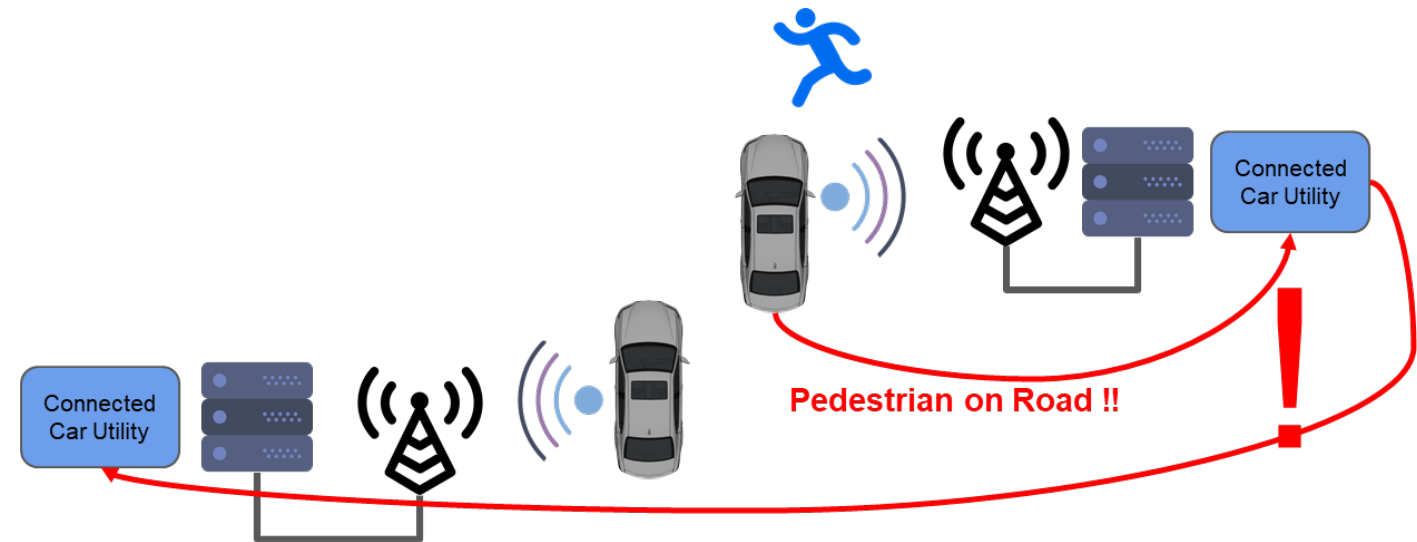
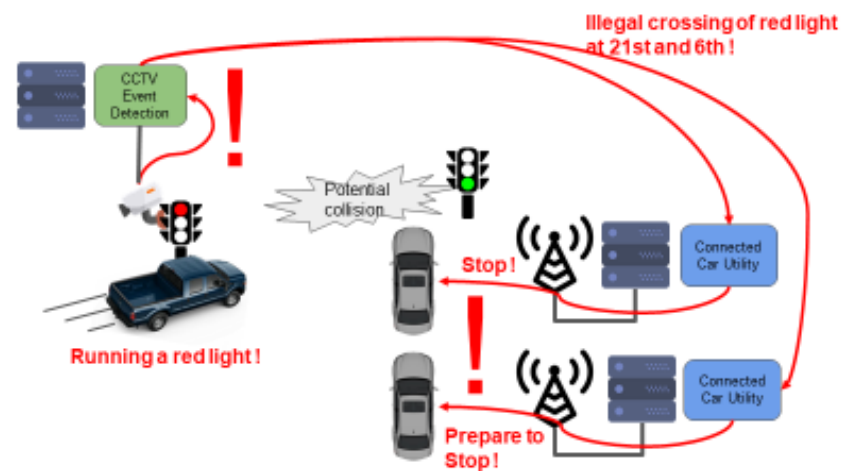


- Elevate Edge to be a peer of the Cloud
 - Prior art: Cloudlets (CMU+Microsoft), MAUI (Microsoft)
- In the limit
 - Make the Edge autonomous even if disconnected from the Cloud

Why



- Interacting entities (e.g., connected vehicles) connected to different edge nodes
- Horizontal (p2p) interactions among edge nodes essential

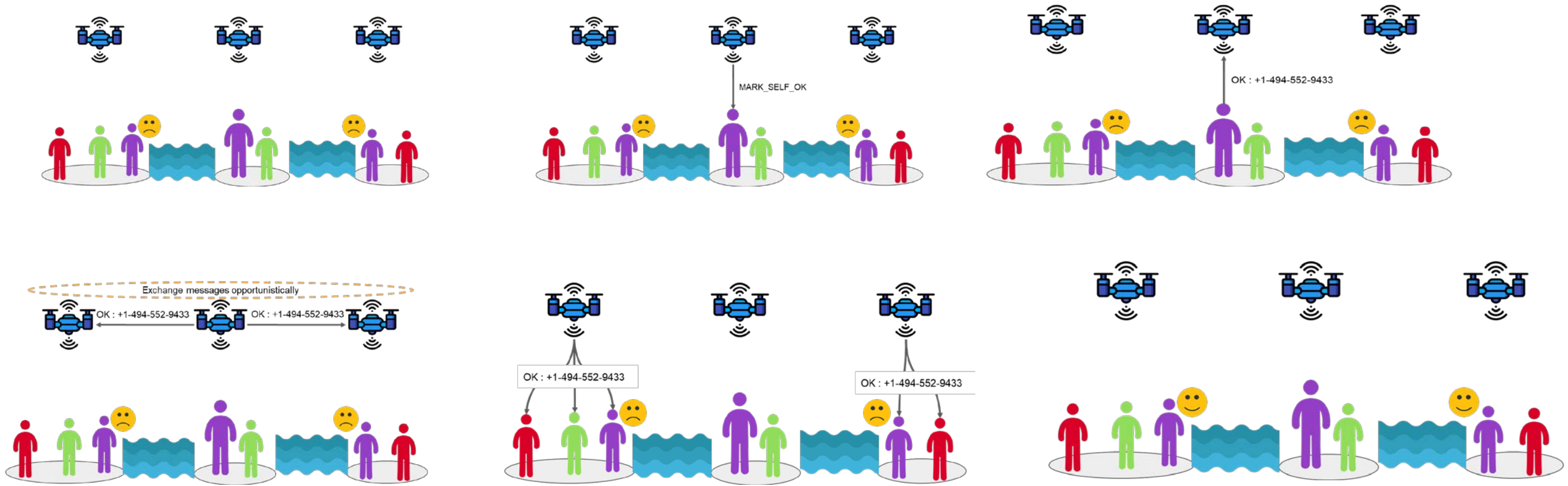


Why



?

- Autonomy of edge (disaster recovery)



Challenges for making



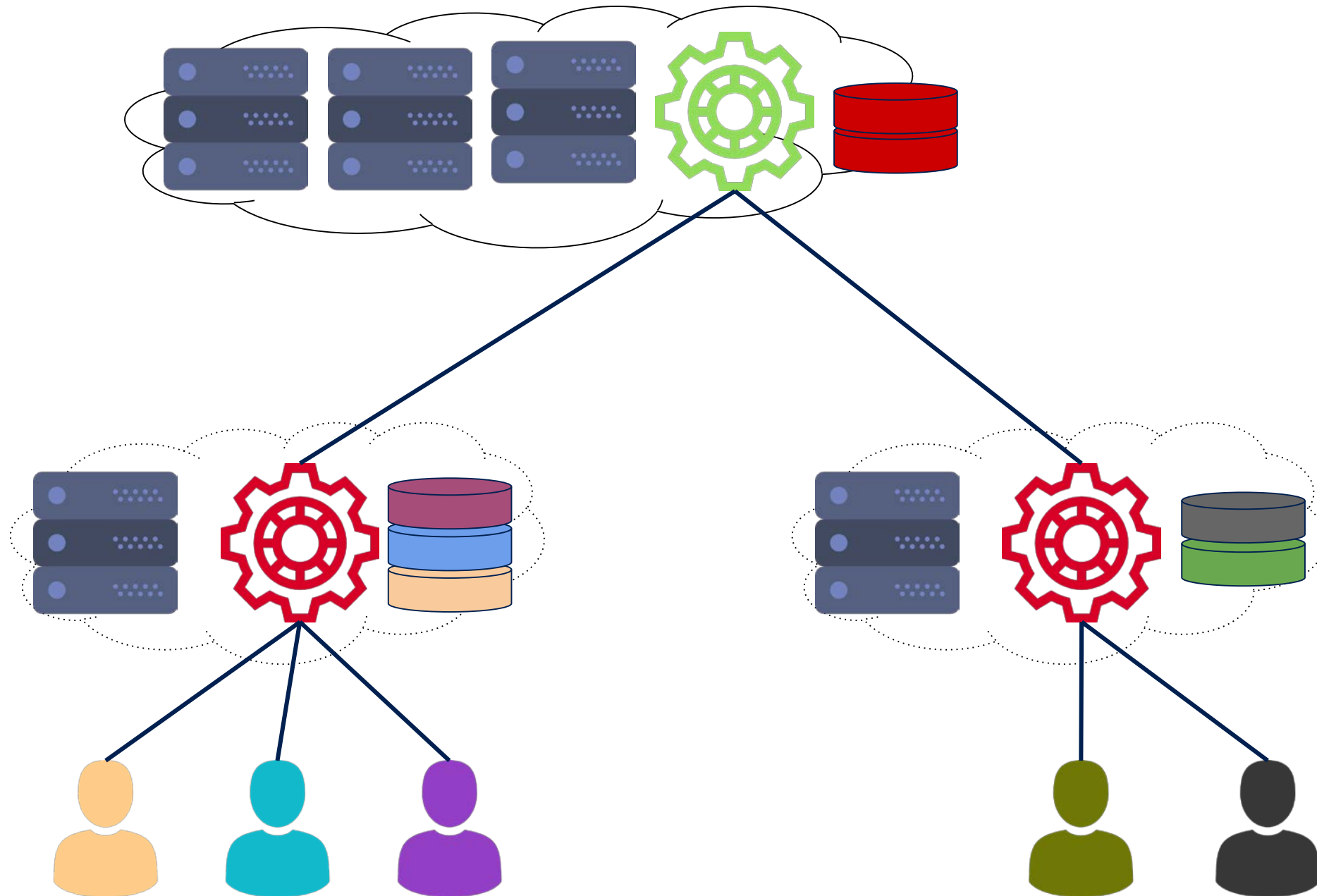
- Need for powerful frameworks akin to the Cloud at the edge
 - Programming models, storage abstractions, pub/sub systems, ...
- Geo-distributed data replication and consistency models
 - Heterogeneity of network resources
 - Resilience to coordinated power failures
- Rapid deployment of application components, multi-tenancy, and elasticity at the edge
 - Cognizant of limited computational, networking, and storage resources

Thoughts on meeting these challenges

- Geo-distributed programming model for Edge/Cloud continuum
 - Foglets (ACM DEBS 2016)
- Geo-distributed data replication and resource management
 - FogStore (ACM DEBS 2018)
 - DataFog (HotEdge 2018)
- Applications using autonomous Edge
 - STTR: Space Time Trajectory Registration (ACM DEBS 2018)
 - Social Sensing *sans* Cloud (SocialSens 2017)

Geo-distributed programming model

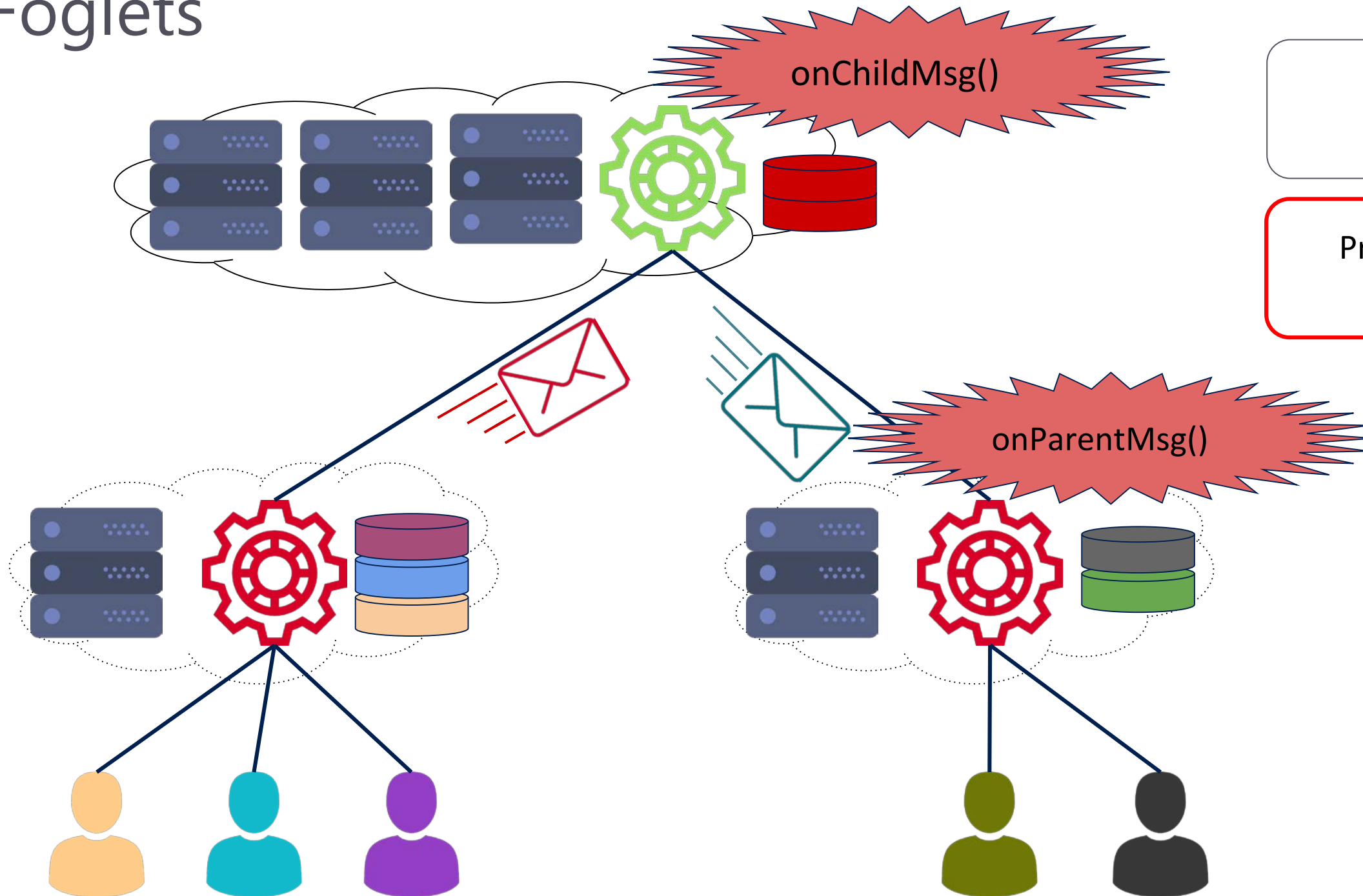
Foglets



App as dataflow graph

Geo-distributed programming model

Foglets

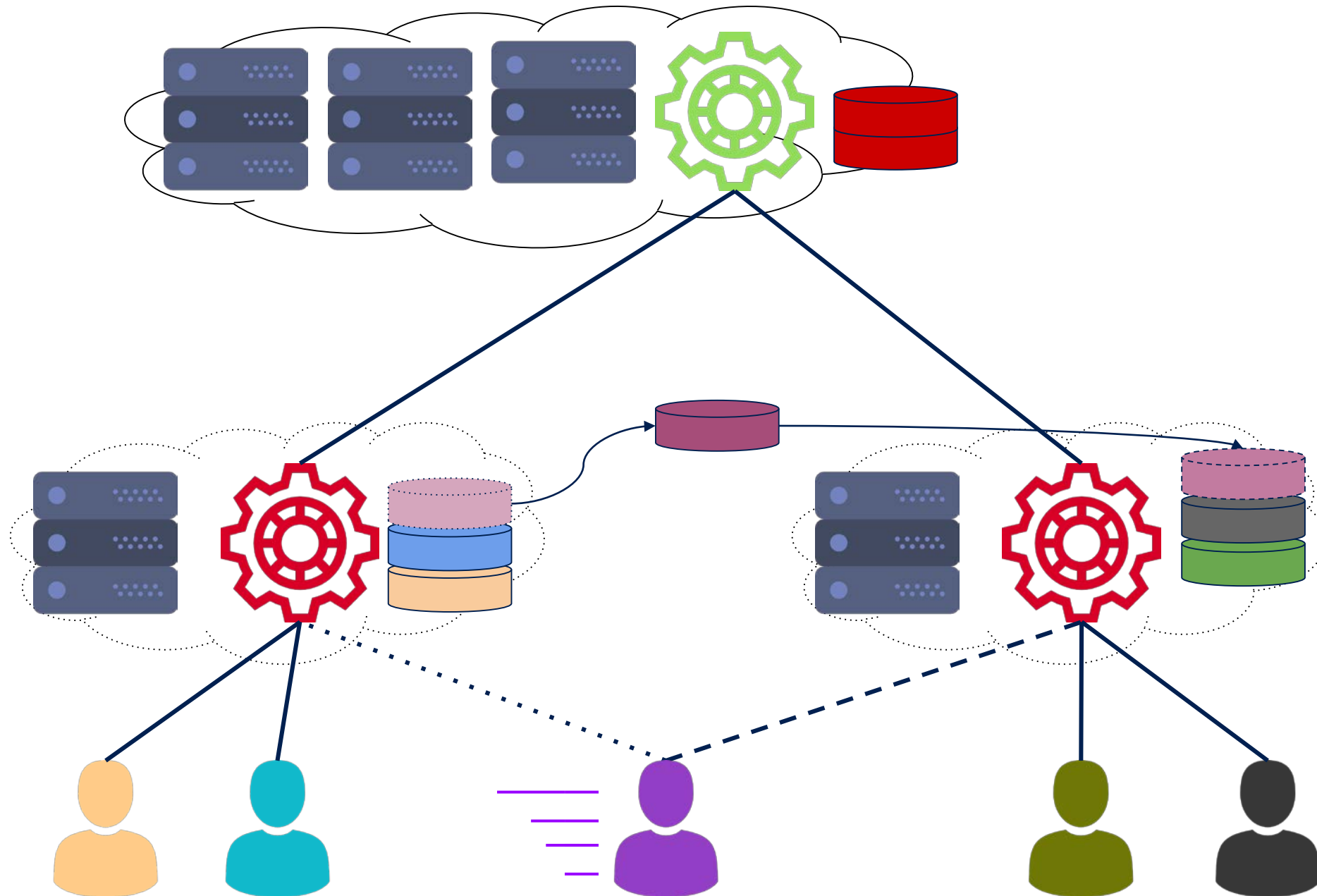


App as dataflow graph

Provides event handlers for communication

Geo-distributed programming model

Foglets



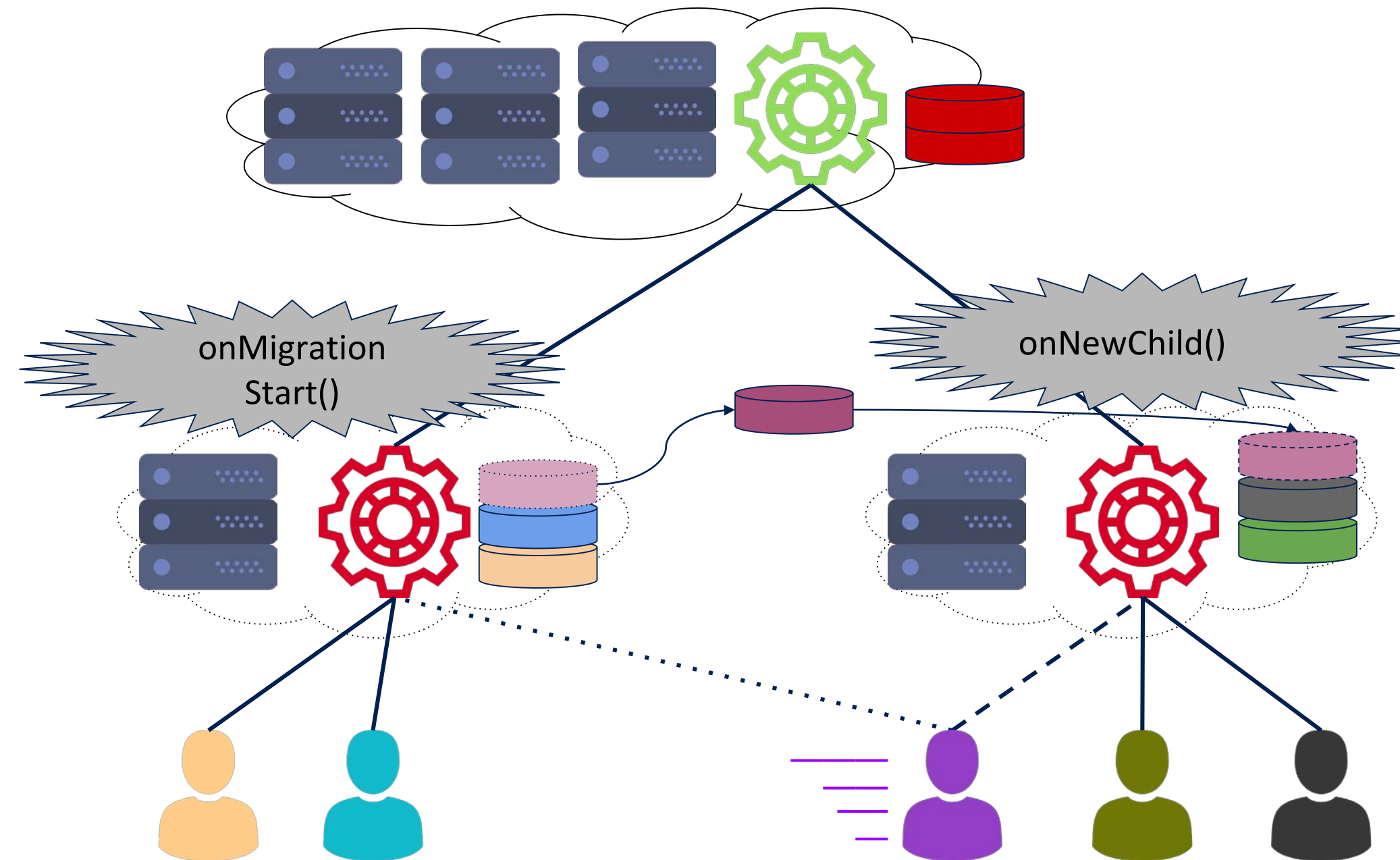
App as dataflow graph

Provides event handlers for communication

Transparent state migration

Geo-distributed programming model

Foglets



App as dataflow graph

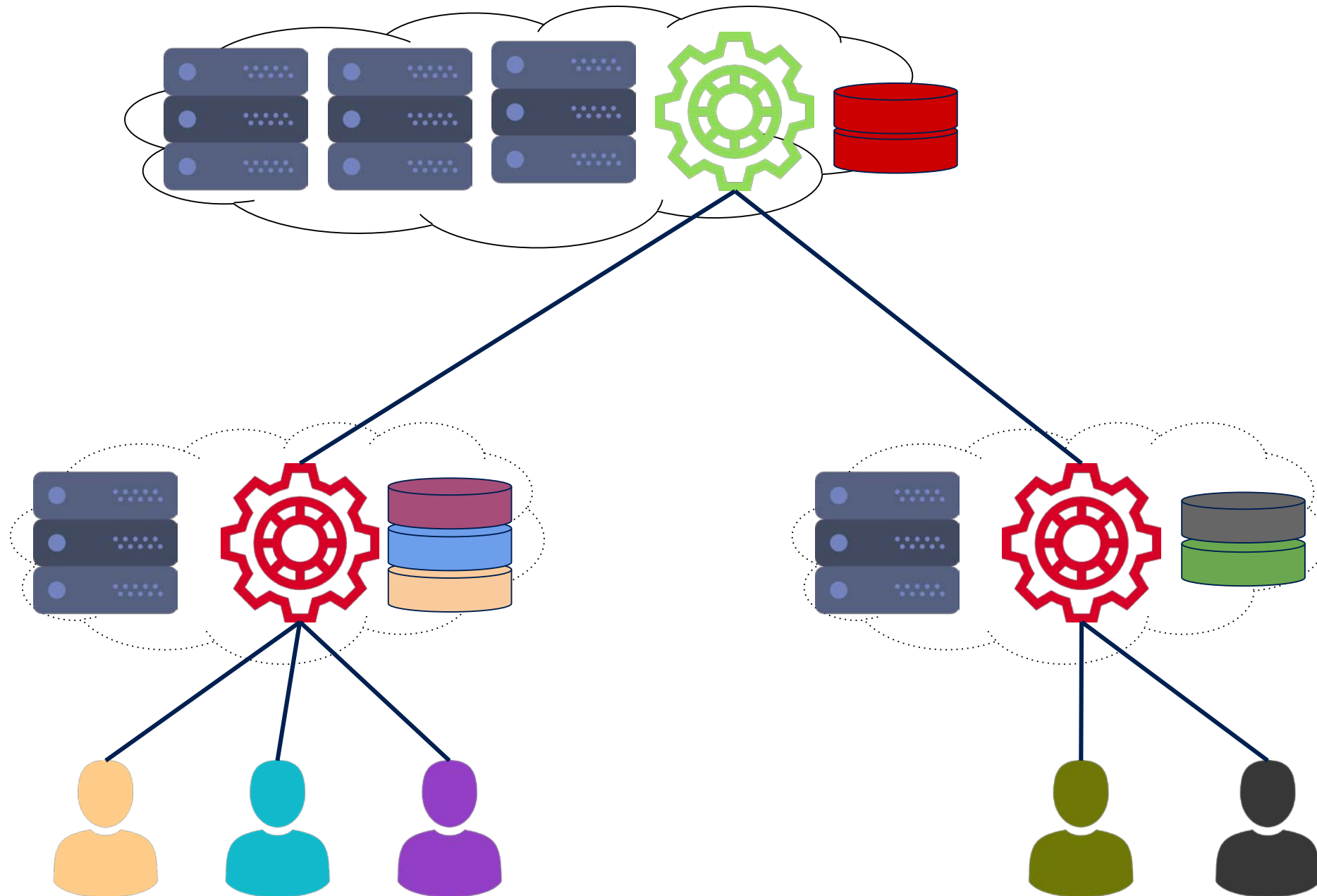
Provides event handlers for communication

Transparent state migration

Handlers for migration events

Geo-distributed programming model

Foglets

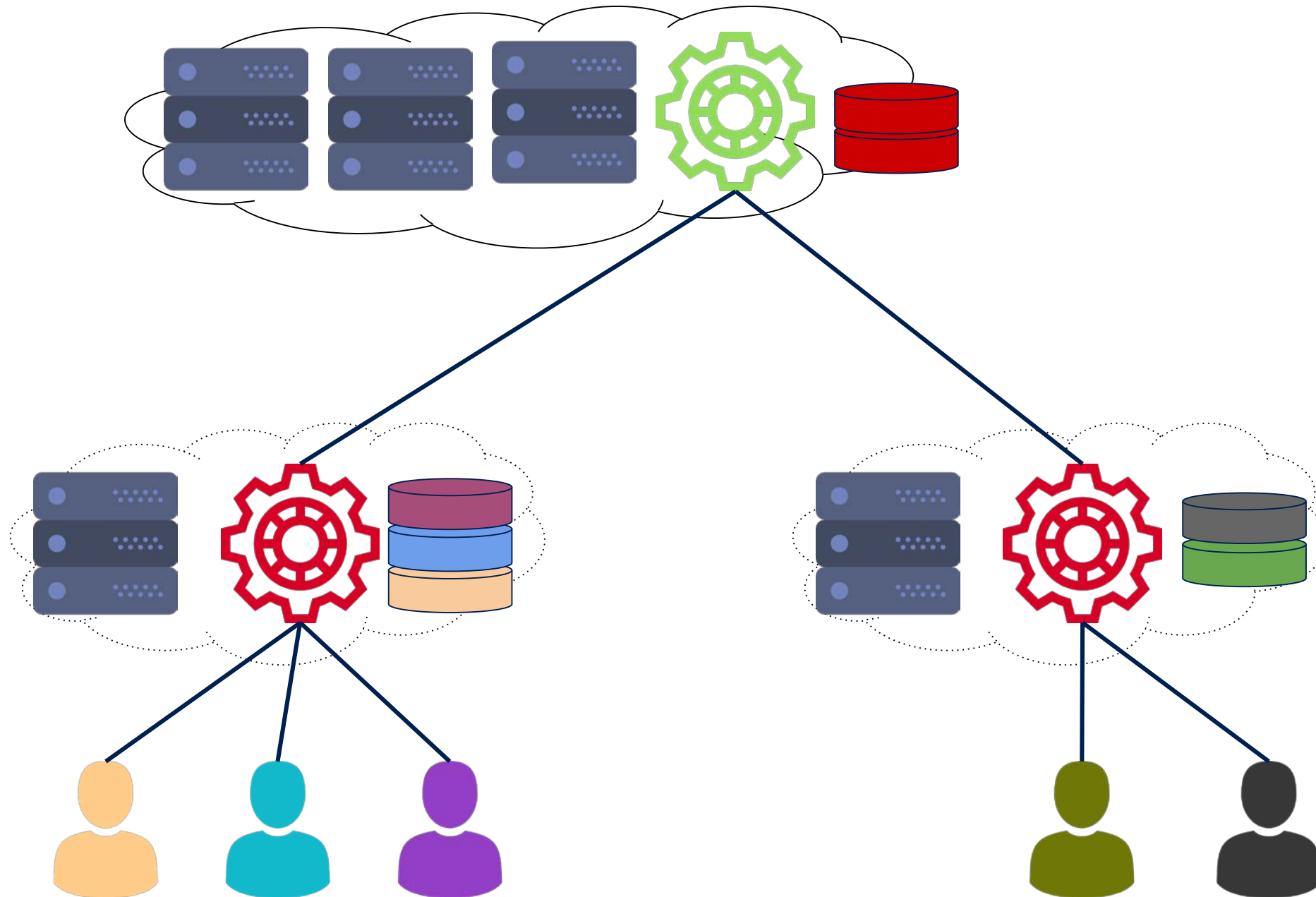


Summary:

- Sense->process->actuate app as a data flow graph with latency SLAs
- Auto discovery and placement of app components in Fog-Cloud continuum
- Migration of computation and state commensurate with mobility and/or resource constraints
- Spatio-temporal KV store for stashing state
- Multi-tenancy in the Fog nodes via virtualization

Geo-distributed programming model

Foglets



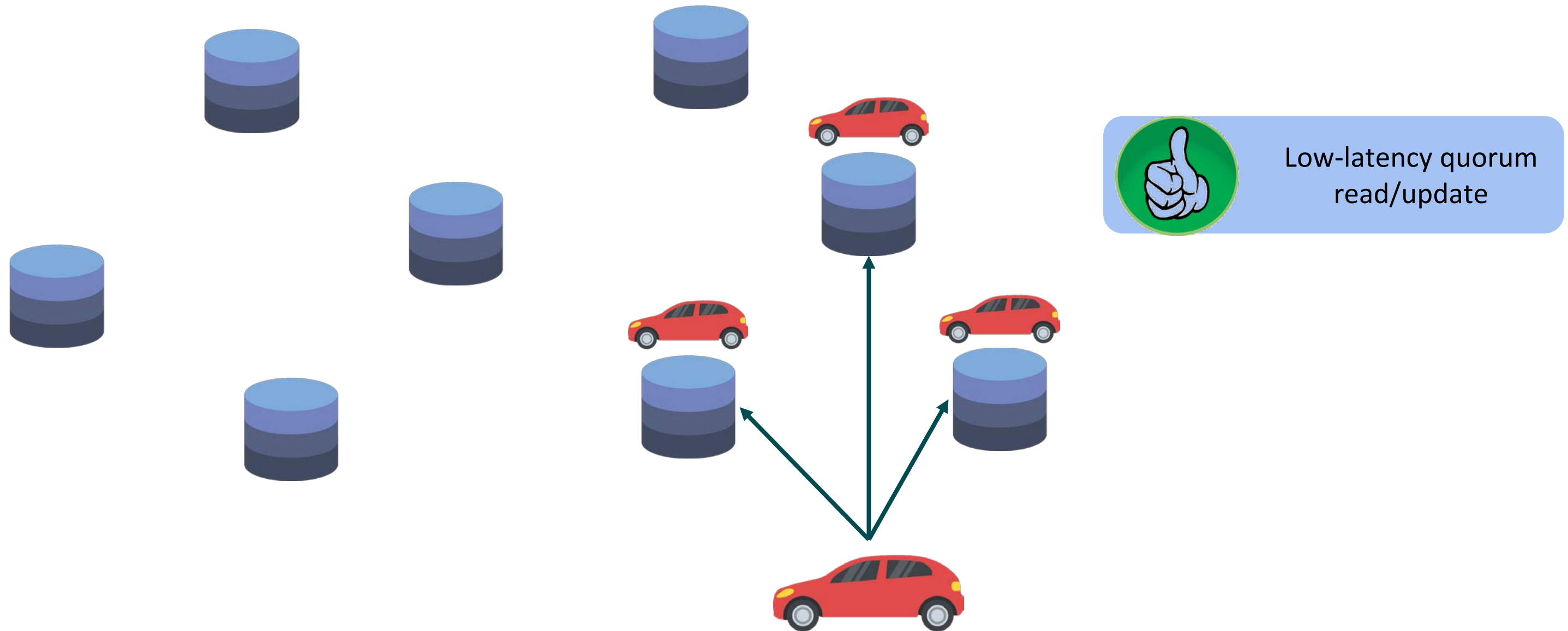
Summary:

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ACM DEBS 2016 for details

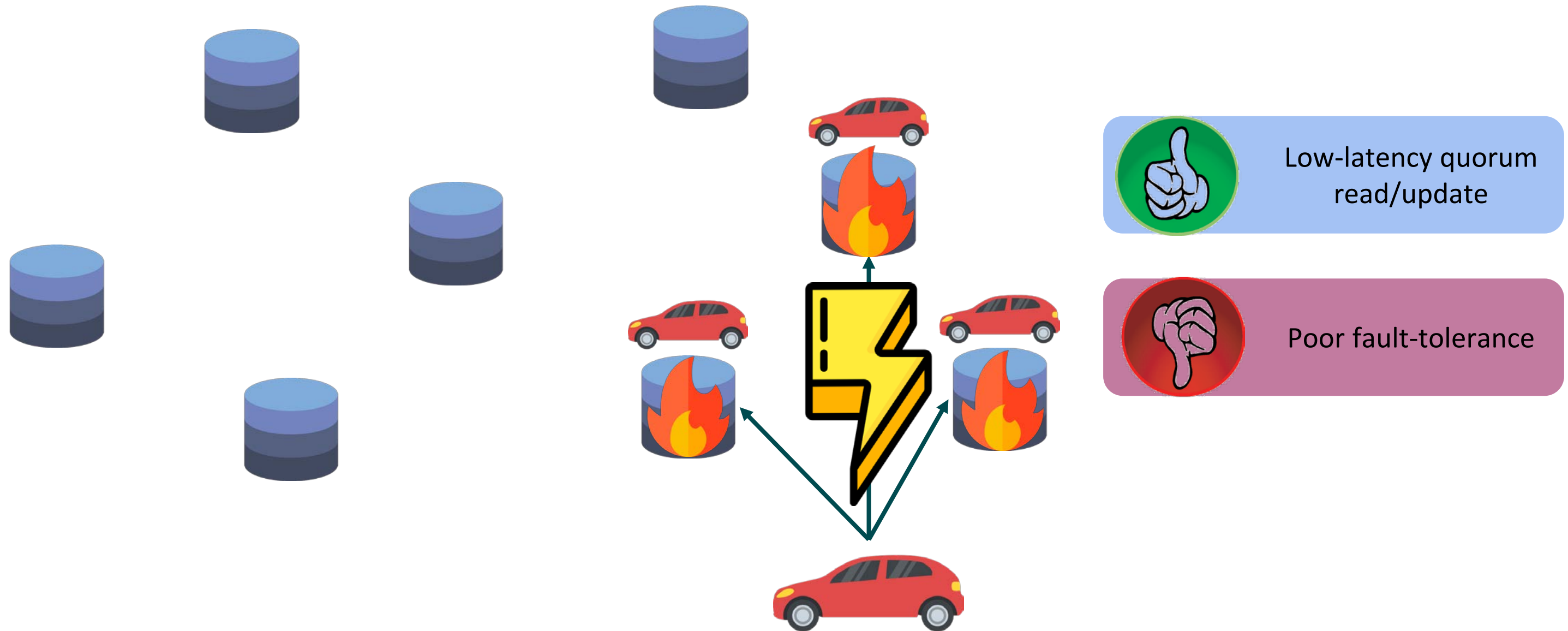
Replication: Consistency/Latency tradeoff

FogStore



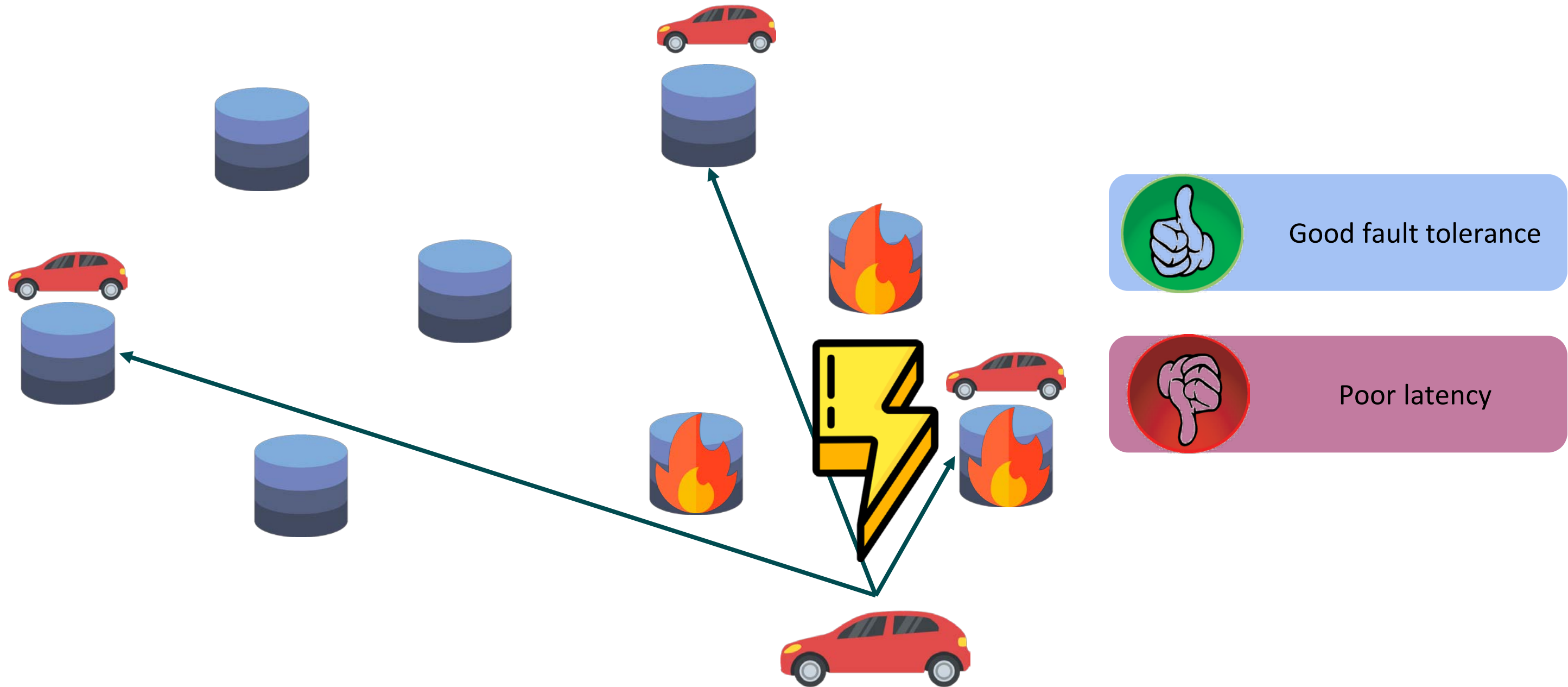
Replication: Consistency/Latency tradeoff

FogStore



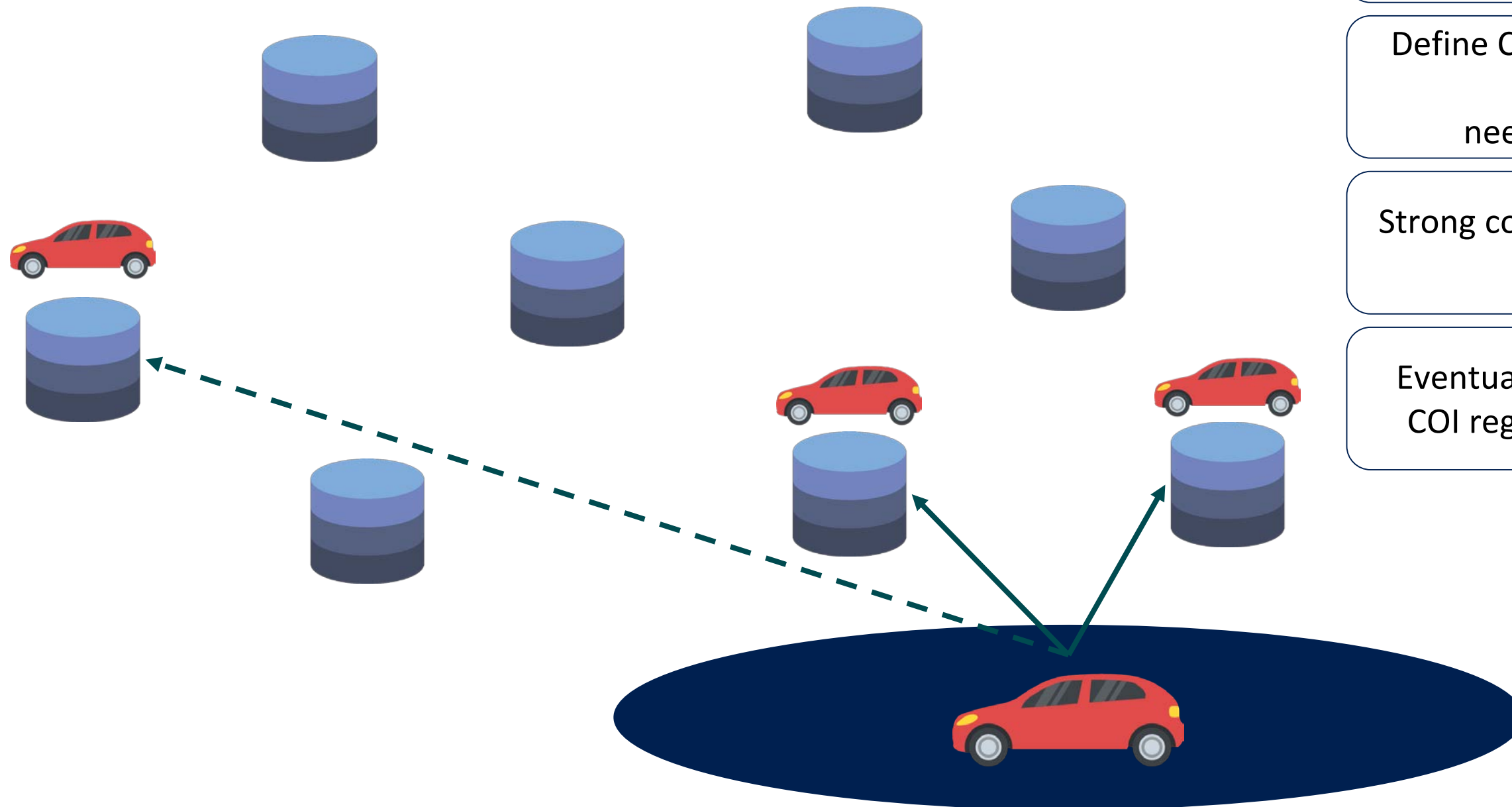
Replication: Consistency/Latency tradeoff

FogStore



Replication: Consistency/Latency tradeoff

FogStore



Utilize spatio-temporal locality nature of queries

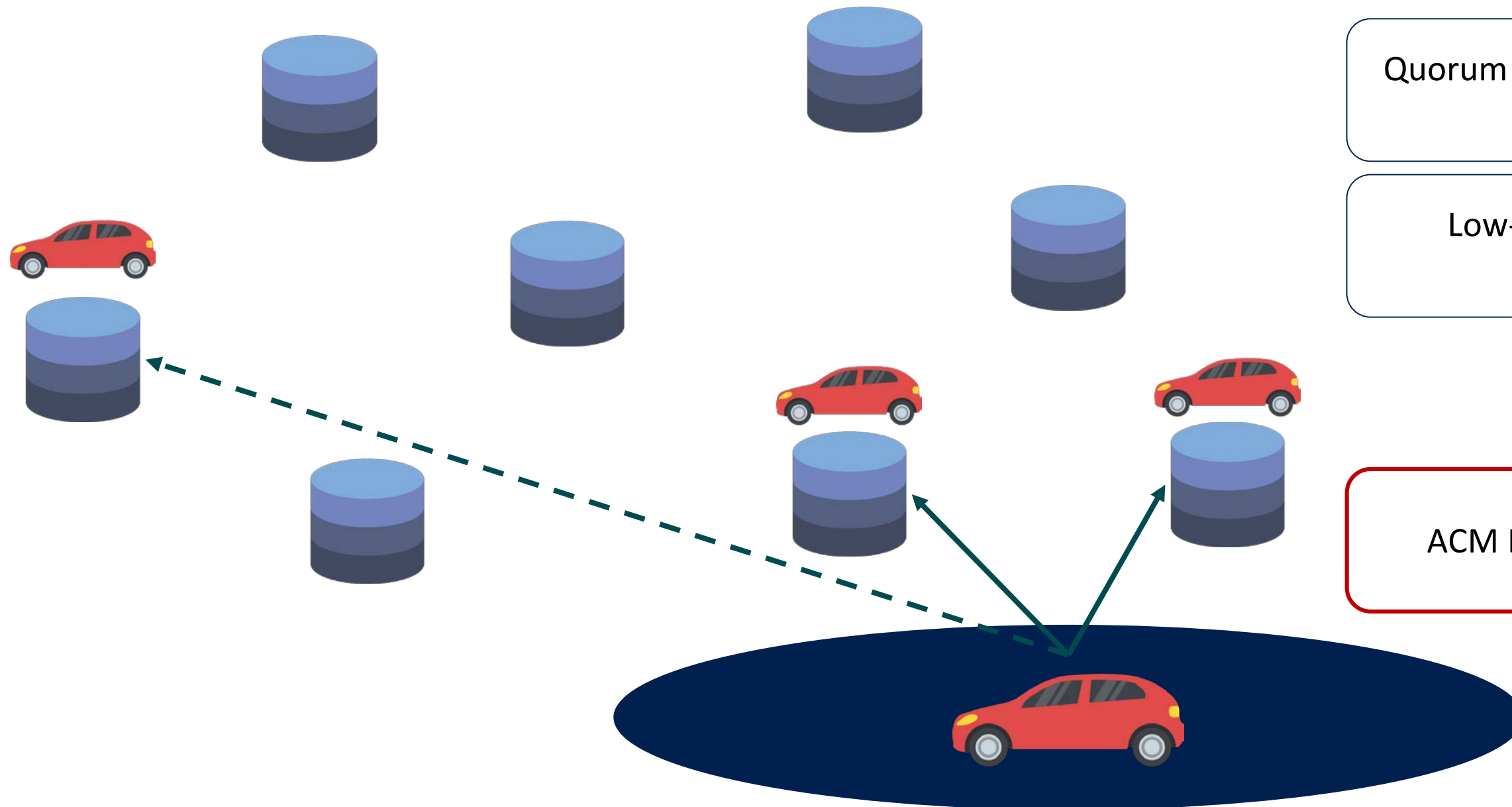
Define Context of Interest (COI) region which needs consistent data

Strong consistency only to clients in COI

Eventual consistency for out of COI region for fault-tolerance

Replication: Consistency/Latency tradeoff

FogStore



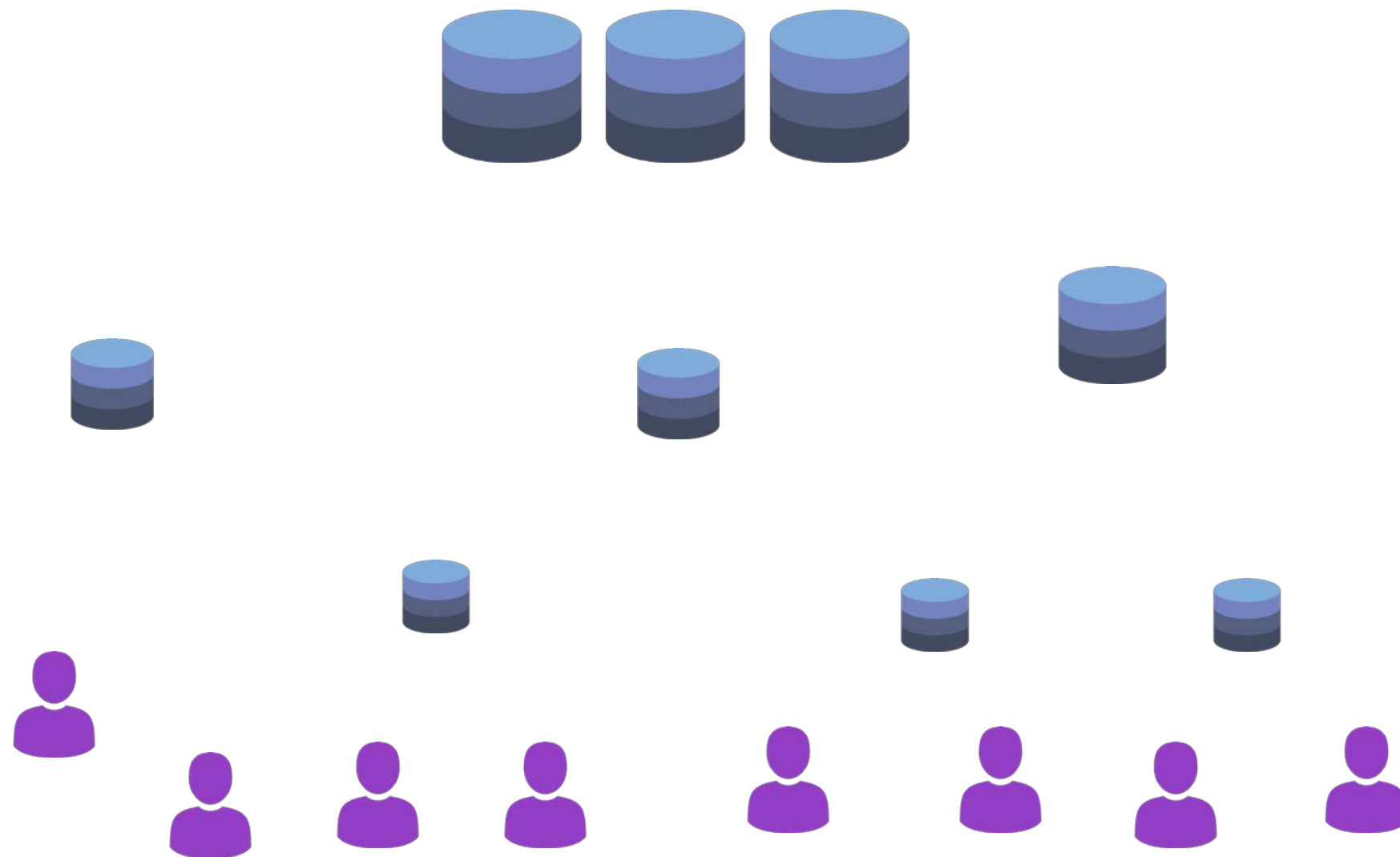
Quorum always involves replicas in proximity

Low-latency with strong consistency

ACM DEBS 2018 for details

Capacity conscious data replication

DataFog



Continuous data generation

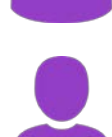
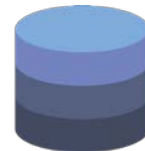
Pressure on low storage capacity
of edge nodes

Capacity conscious data replication

DataFog

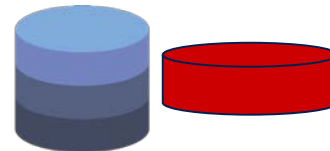
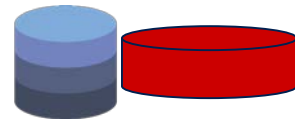
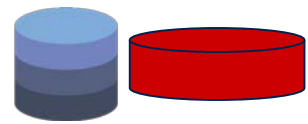
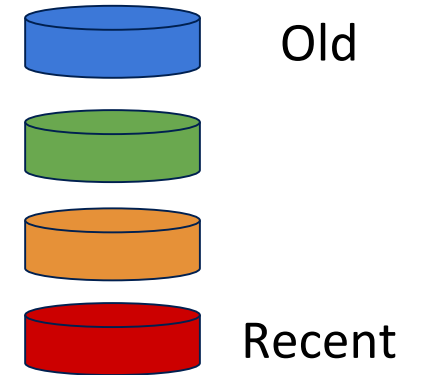
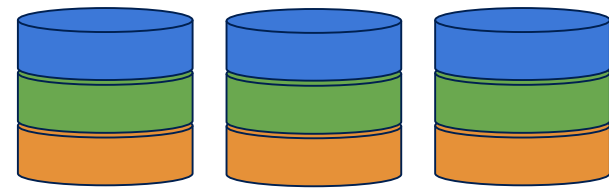


Skews in workload distribution

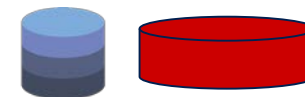
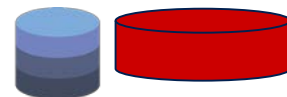
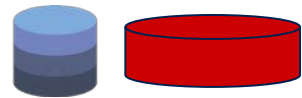


Capacity conscious data replication

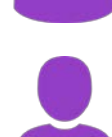
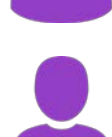
DataFog



Edge used only for critical data



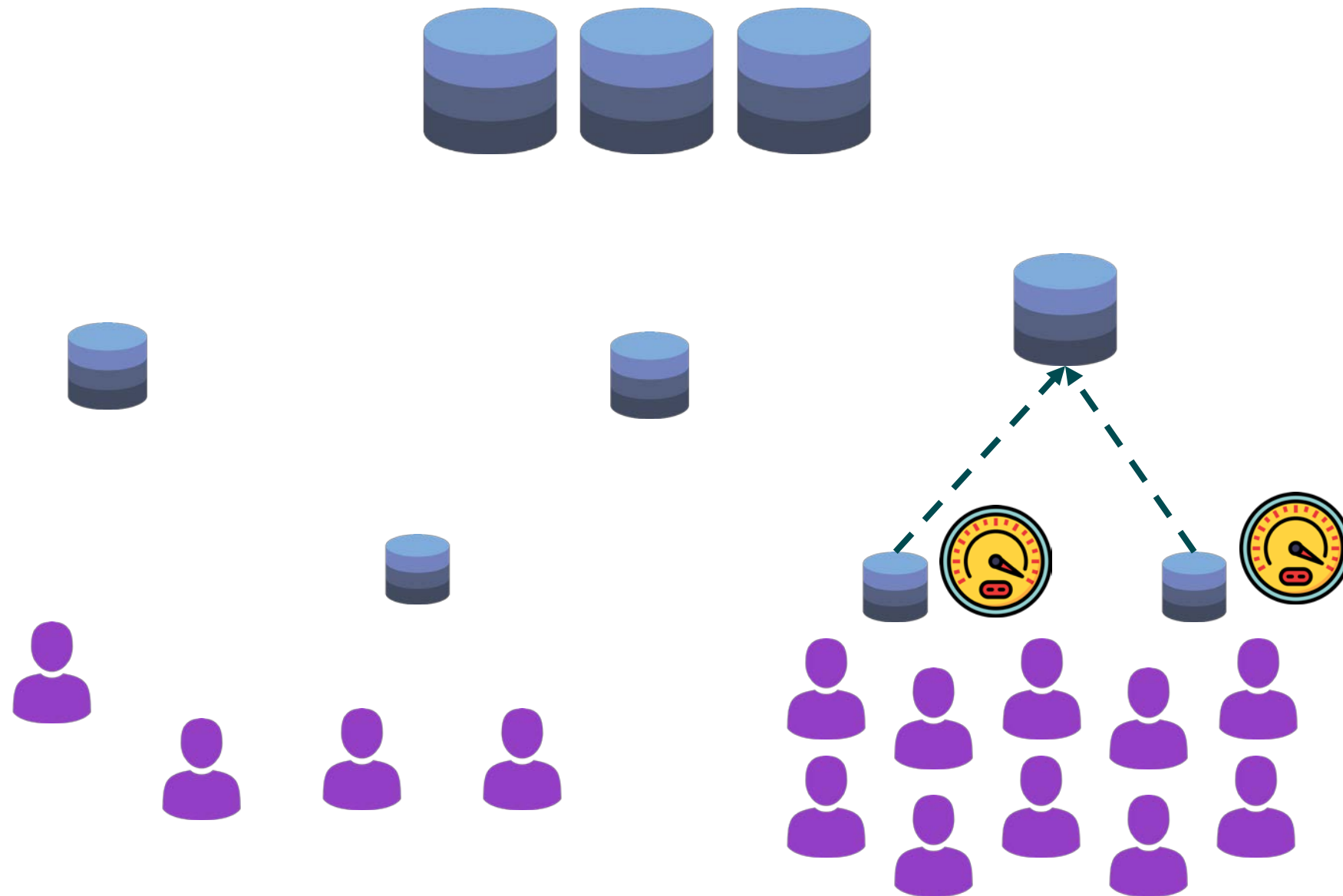
Important for real-time queries



Capacity conscious data replication

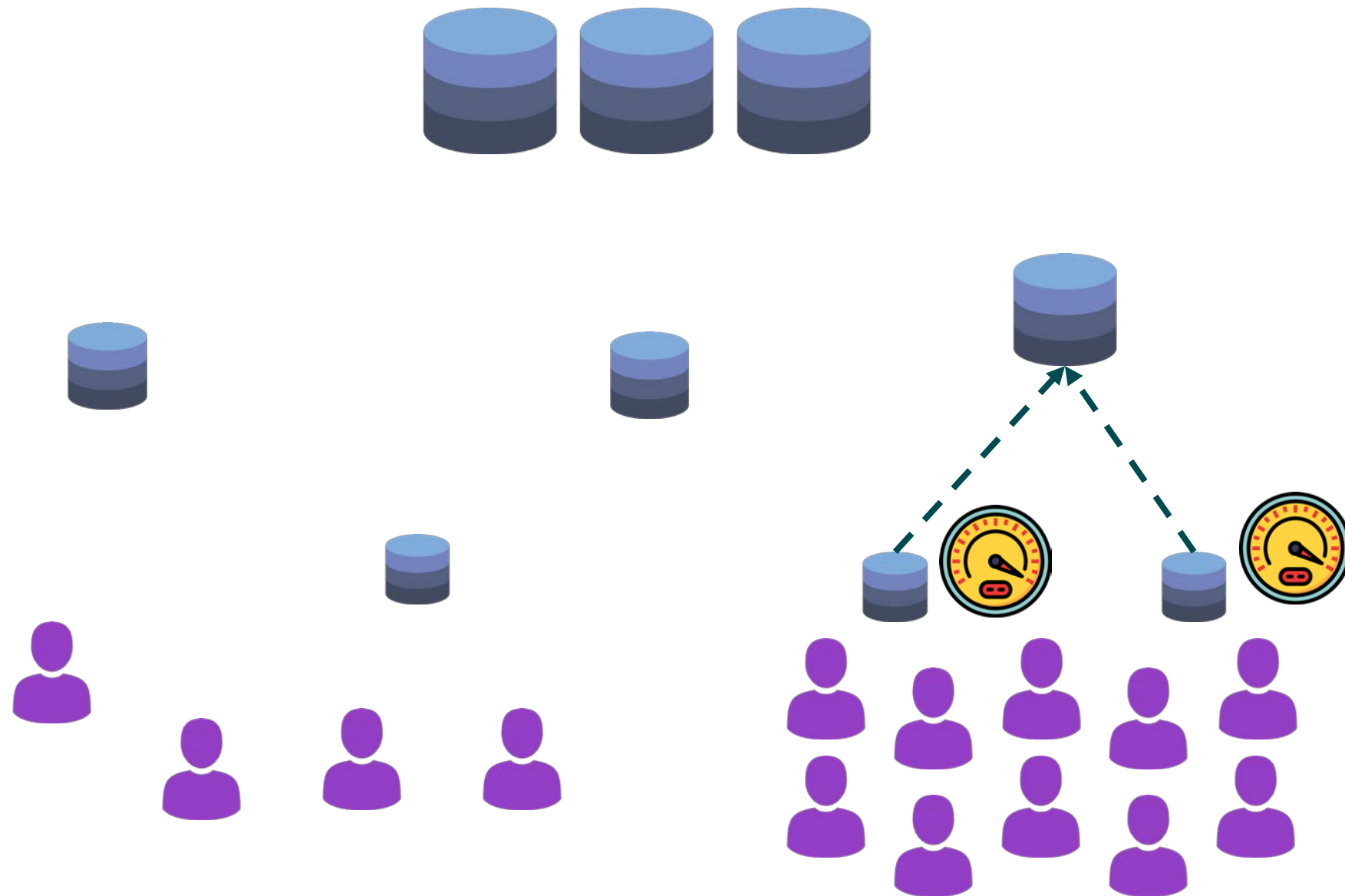
DataFog

Agile load balancing for
skew tolerance



Capacity conscious data replication

DataFog



Agile load balancing for skew tolerance

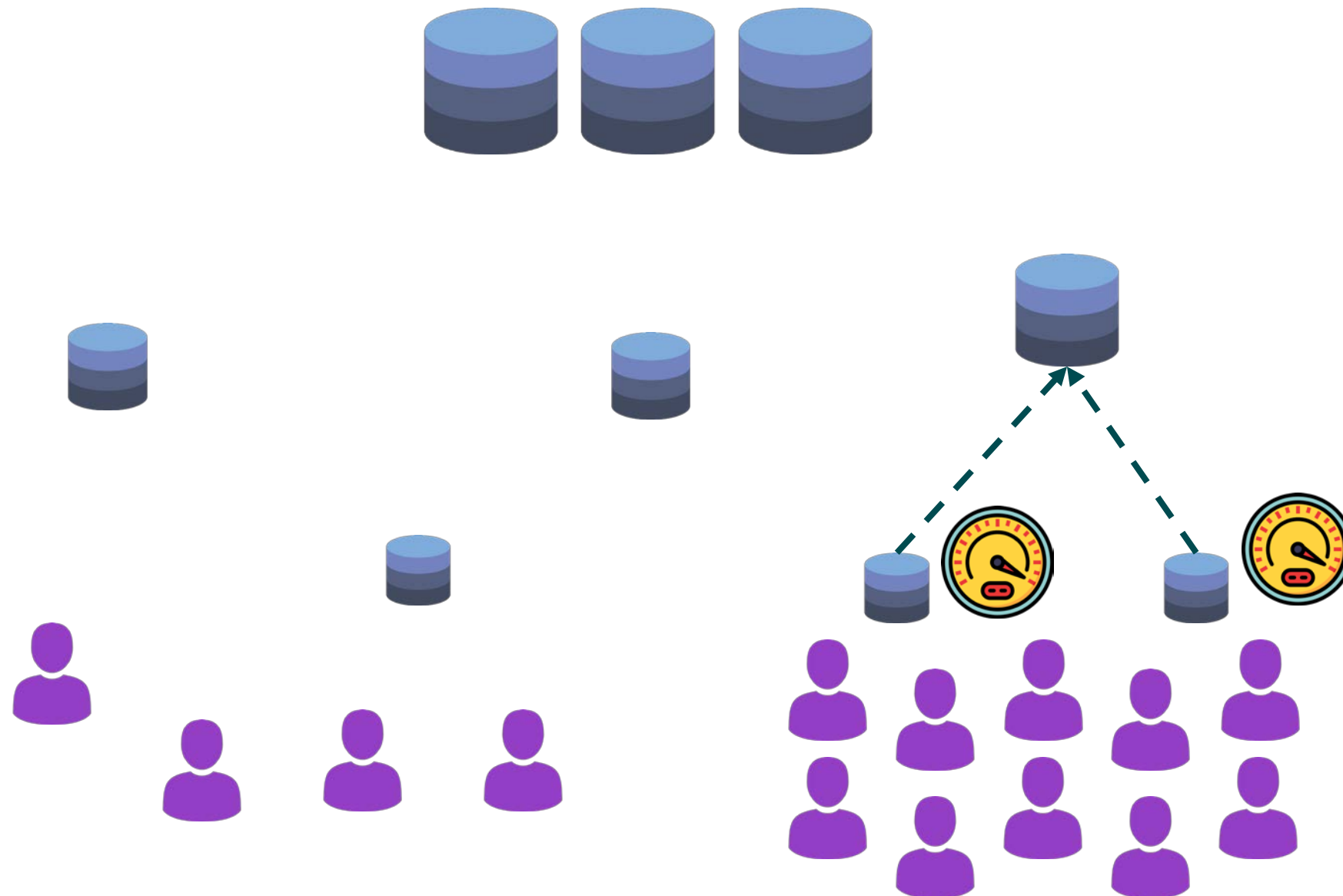
- Data-items are indexed based on their spatio-temporal attributes (e.g., Geohash)
- Consistent hashing for the location, timestamp and item-type attributes is used for partitioning data across nodes
- Multiple replicas on Edge nodes for low latency
- Multiple replicas on remote datacenter nodes for tolerance from geographically correlated failures
- Mechanisms for adapting to hotspots

Capacity conscious data replication

DataFog

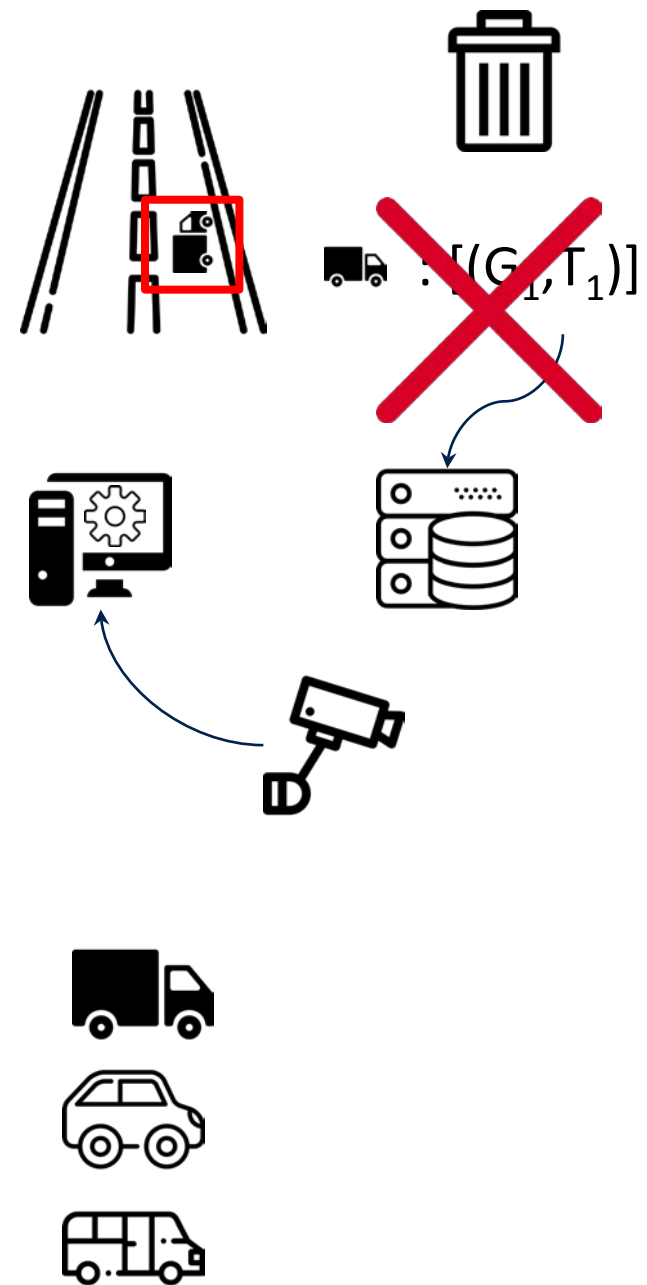
HotEdge 2018 for details

Agile load balancing for skew tolerance



- Data-items are indexed based on their spatio-temporal attributes (e.g., Geohash)
- Consistent hashing for the location, timestamp and item-type attributes is used for partitioning data across nodes
- Multiple replicas on Edge nodes for low latency
- Multiple replicas on remote datacenter nodes for tolerance from geographically correlated failures
- Mechanisms for adapting to hotspots

Applications using Autonomous Edge Space Time Trajectory Registration (STTR)



~~Truck : $[(G_1, T_1), (G_2, T_2)]$~~

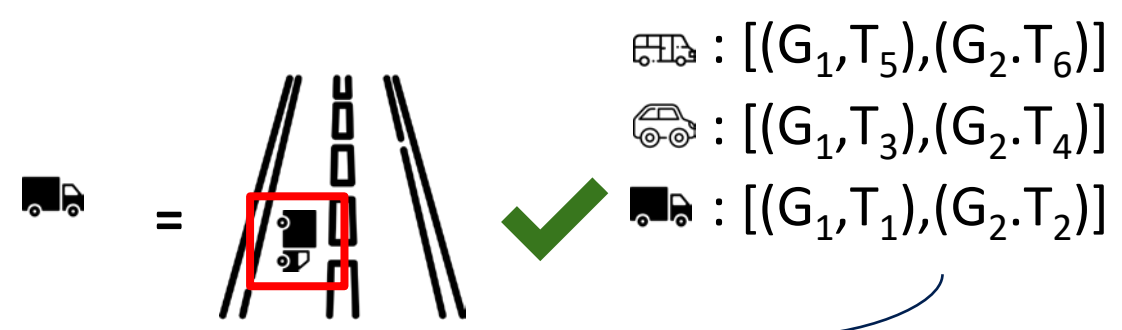
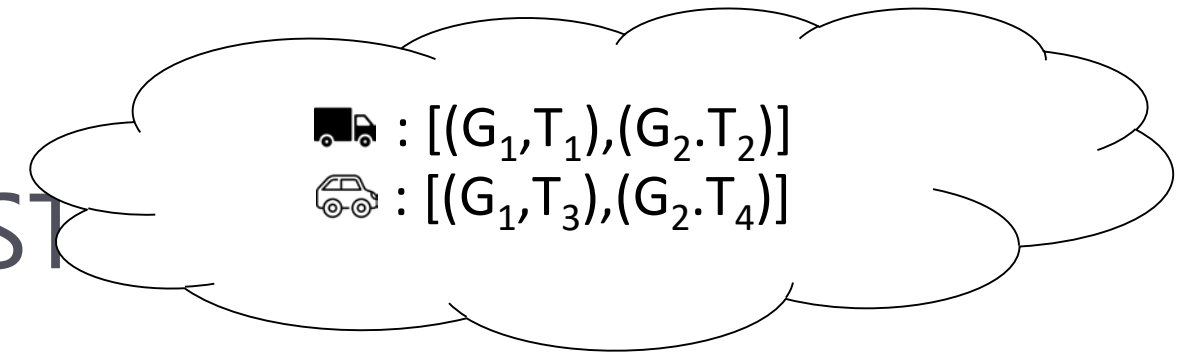
ACM DEBS 2018 for details

Forward/Backward propagation
between cameras

Greedy/Lazy trajectory
aggregation

Storage is bounded by the
activities within each camera

Edge as real-time processing
Cloud as history

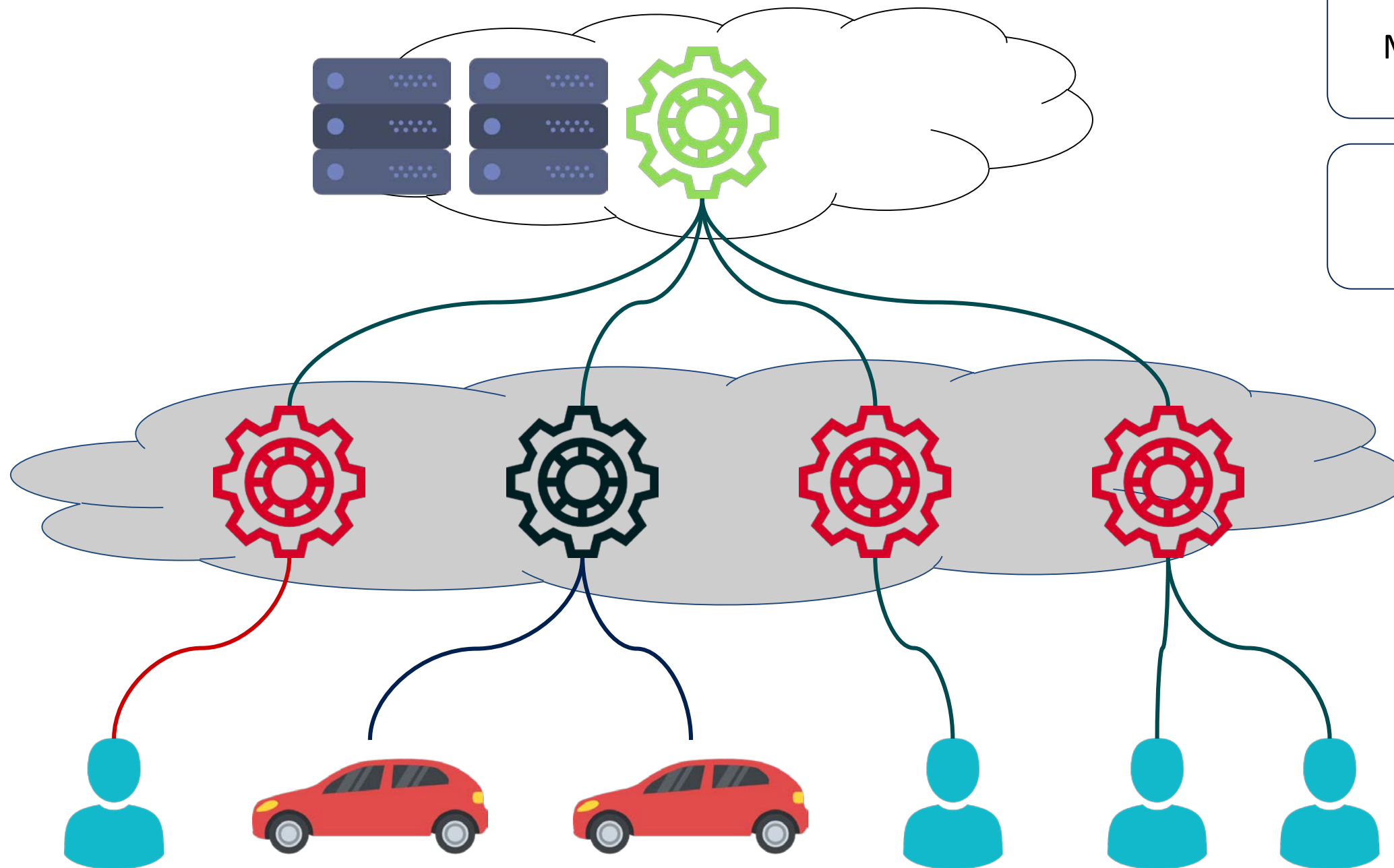


Truck : $[(G_1, T_5), (G_2, T_6)]$
Car : $[(G_1, T_3), (G_2, T_4)]$
Truck : $[(G_1, T_1), (G_2, T_2)]$ ✓



Applications using Autonomous Edge

Social sensing

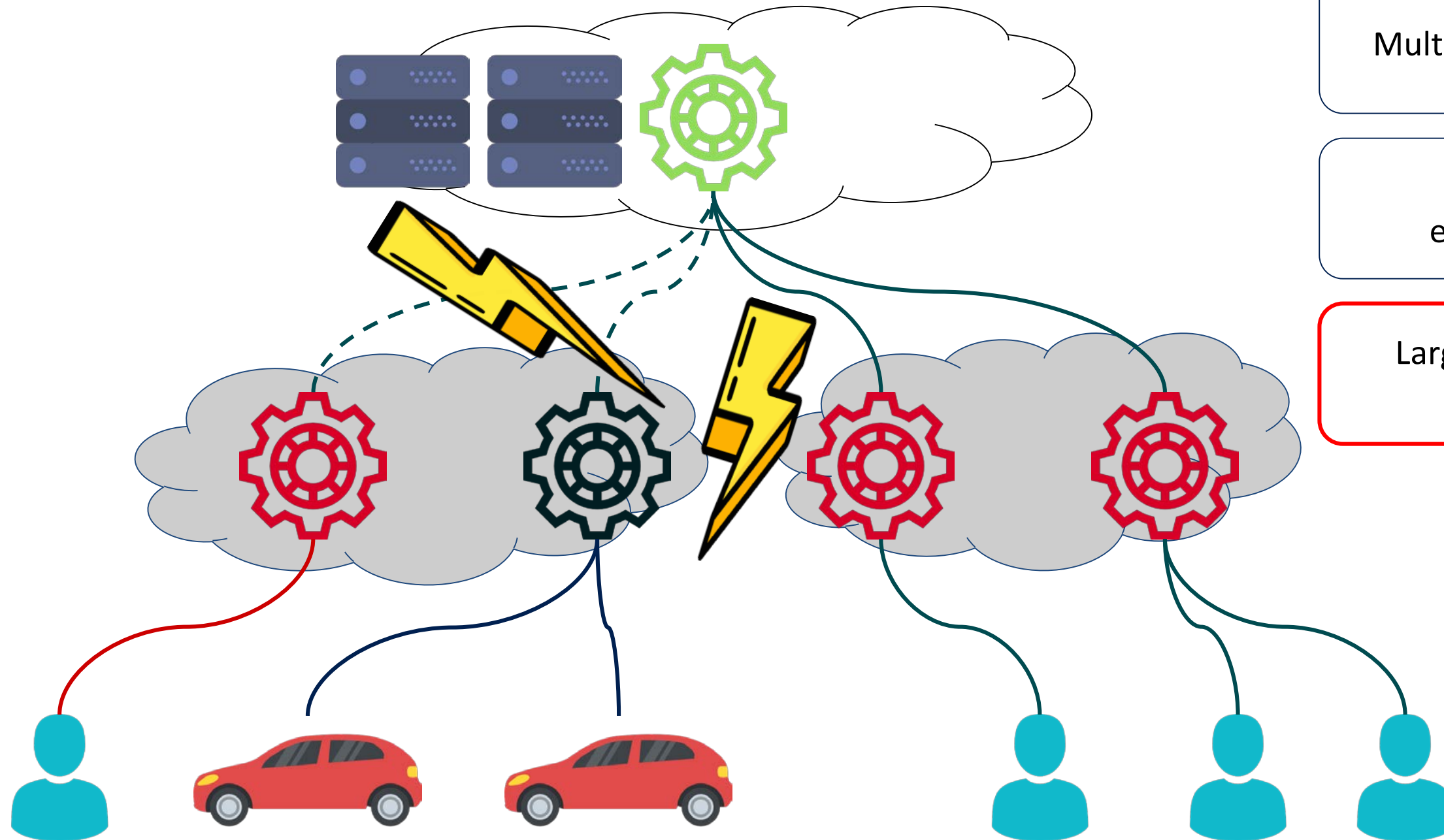


Multi-component applications

Deployed across
edge-cloud continuum

Applications using Autonomous Edge

Social sensing



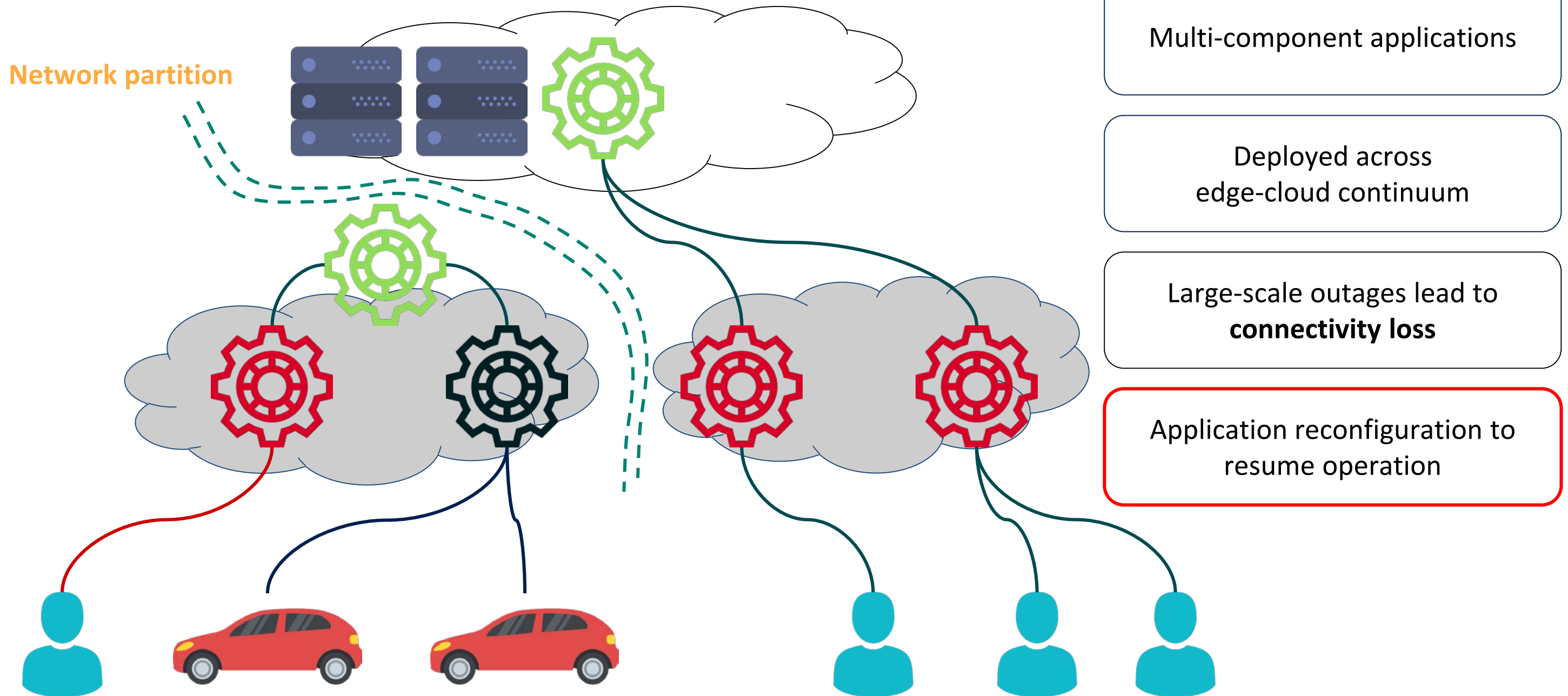
Multi-component applications

Deployed across
edge-cloud continuum

Large-scale outages lead to
connectivity loss

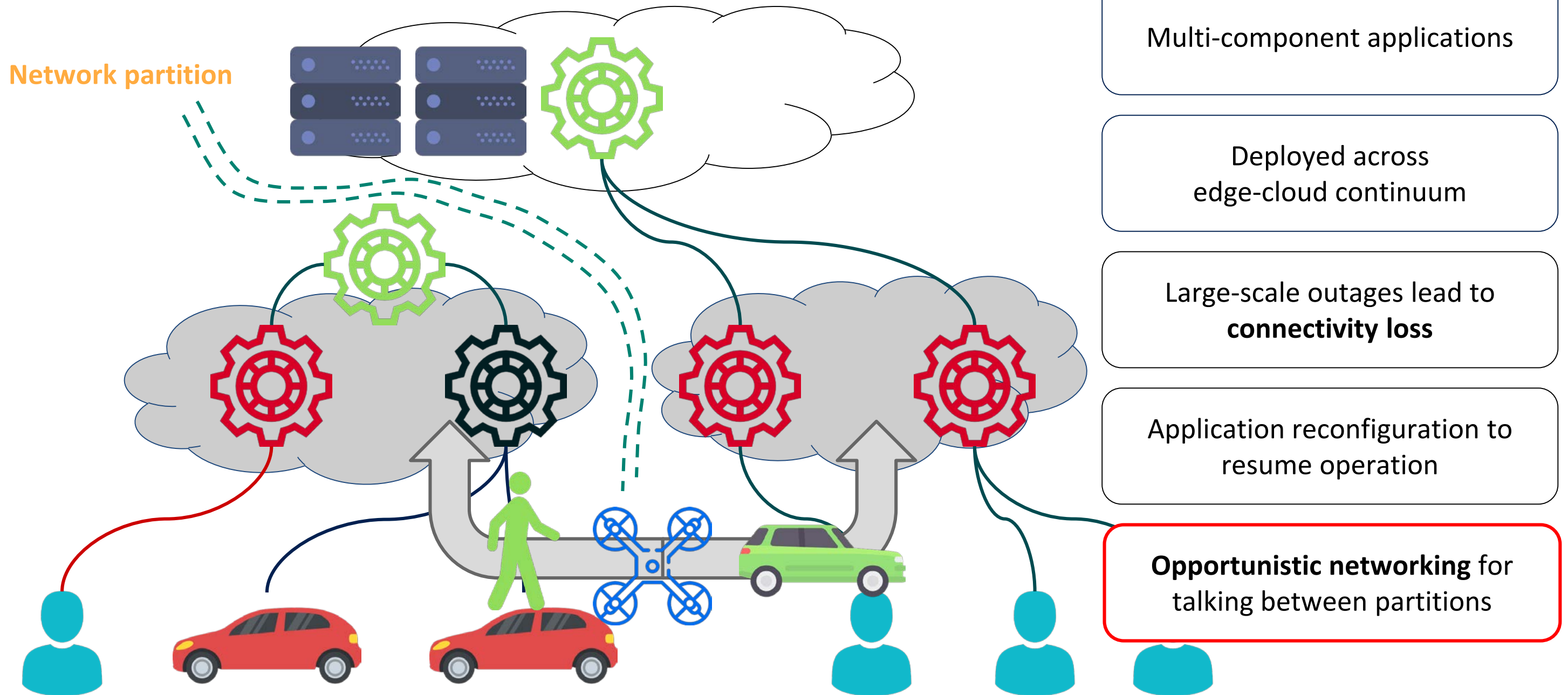
Applications using Autonomous Edge

Social sensing



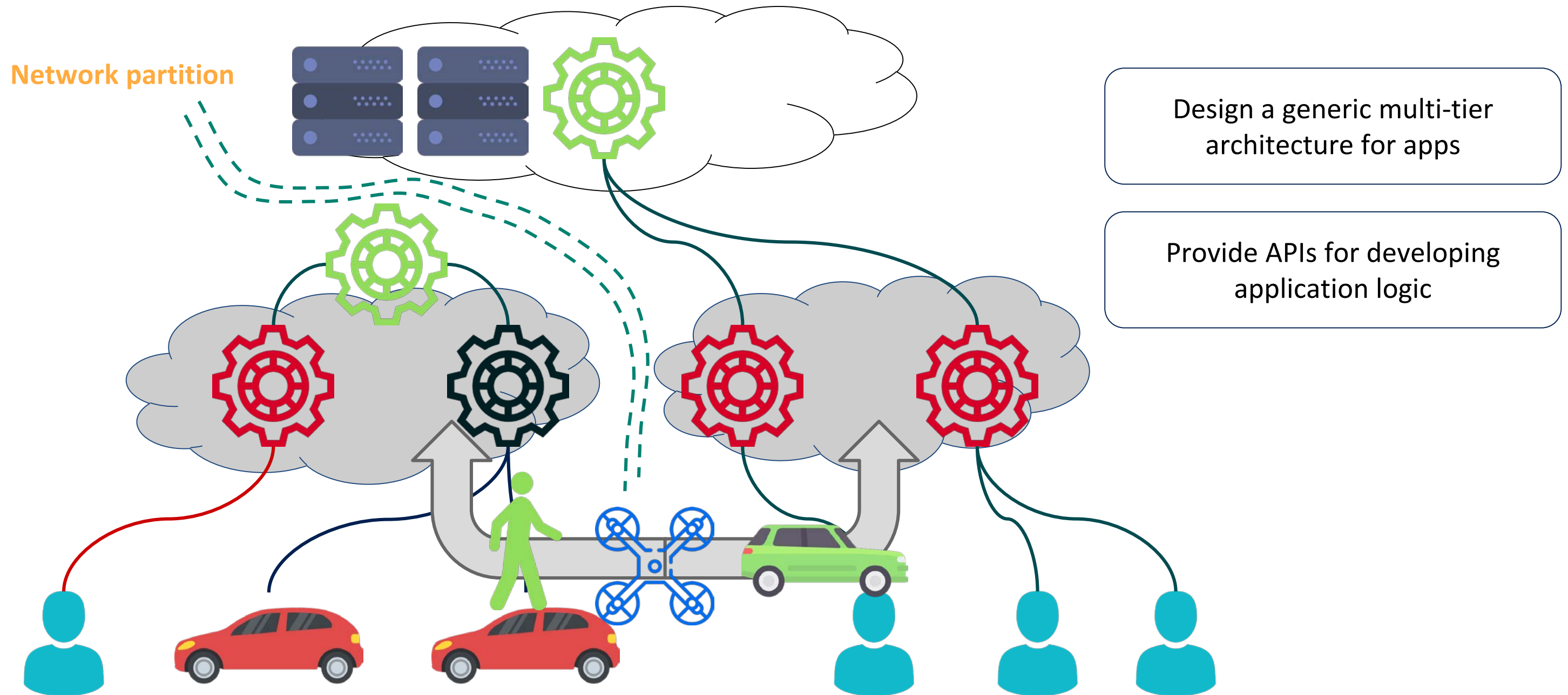
Applications using Autonomous Edge

Social sensing



Applications using Autonomous Edge

Social sensing

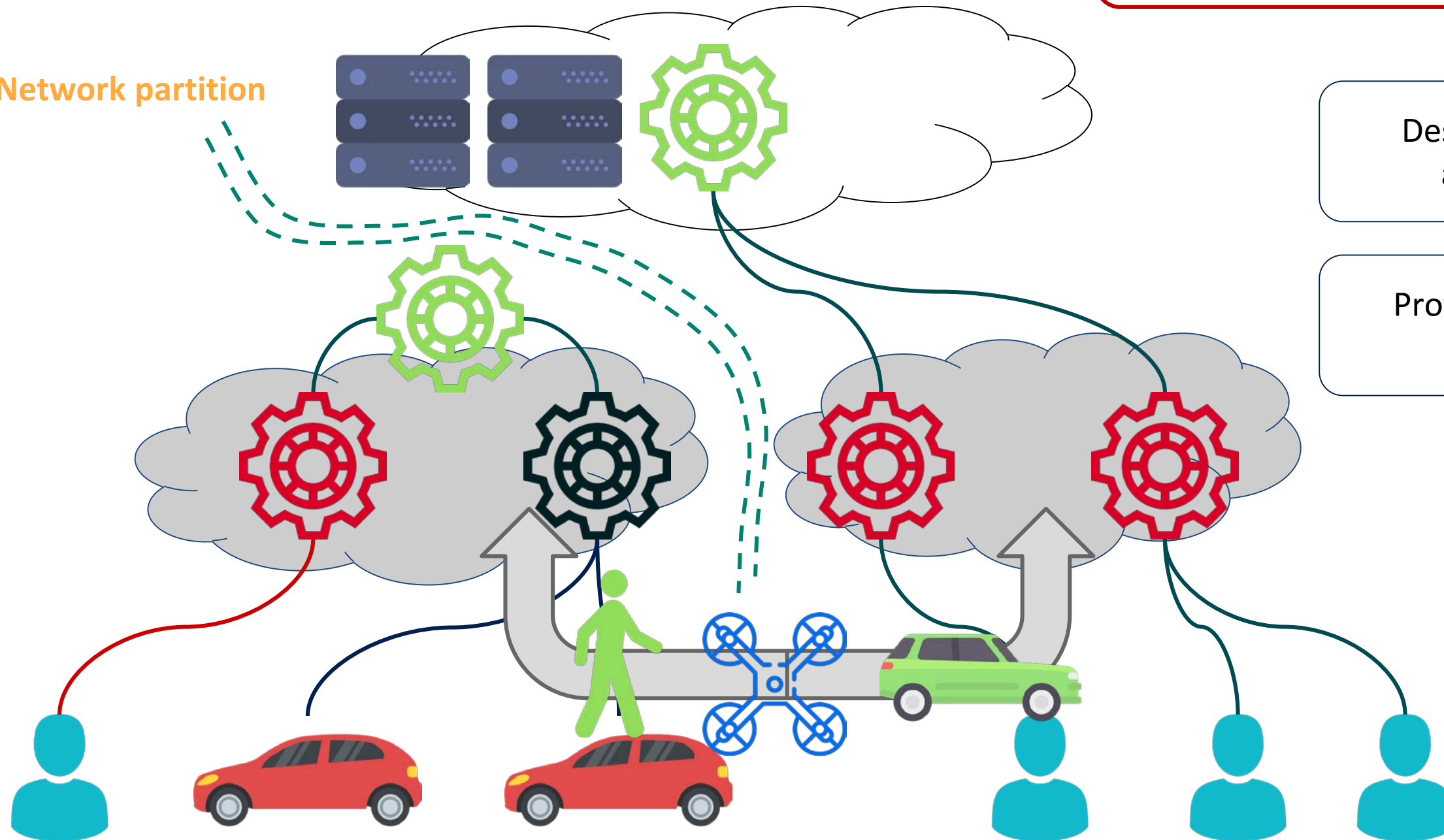


Applications using Autonomous Edge

Social sensing

SocialSens 2017 for details

Network partition

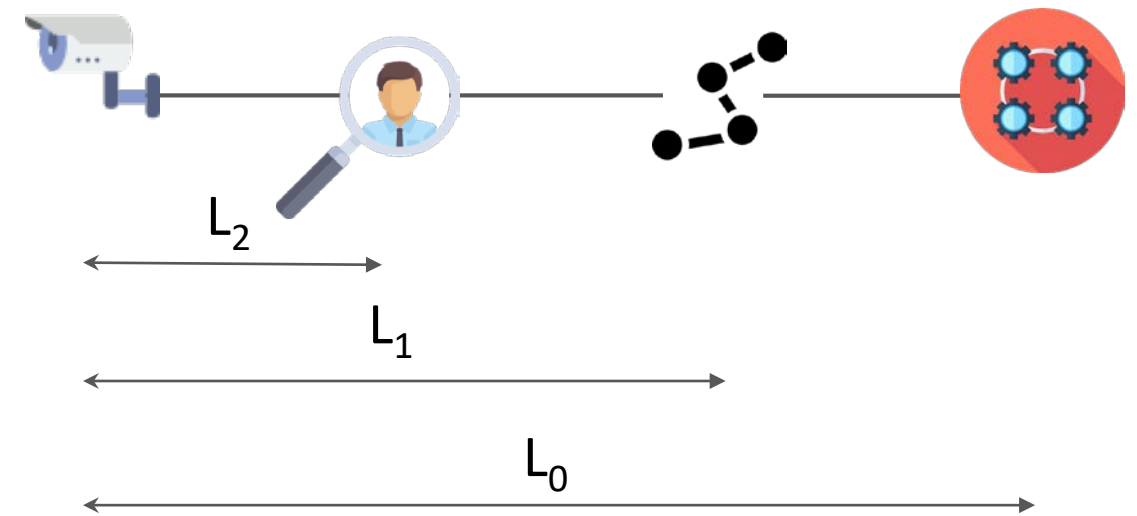


Design a generic multi-tier architecture for apps

Provide APIs for developing application logic

Ongoing work: Logically centralized control plane

1. Extension of Foglets programming model to add QoS requirements
 - Max data staleness at each level
2. Centralized control for end-to-end allocation respecting SLAs
3. Enables high level resource management policies
 - E.g. resource consolidation for energy minimization



Ongoing work: Logically centralized control plane

1. How distributed can the control plane be?
 - Tradeoff between control plane latency and end-to-end decision making
2. How to efficiently monitor vastly geo-distributed resources?
 - Necessary for adaptive reconfigurations
 - Devise decentralized monitoring schemes
 - Piggyback on data plane
3. How to deal with inconsistent resource state at control plane?
 - Controller's world view may be stale due to failures

Concluding Remarks

- Inflection point in systems research spurred by large-scale deployment of sensors and novel situation awareness applications
- Edge/Fog emerging as a serious disruption to the Cloud status quo
- Vision for the future



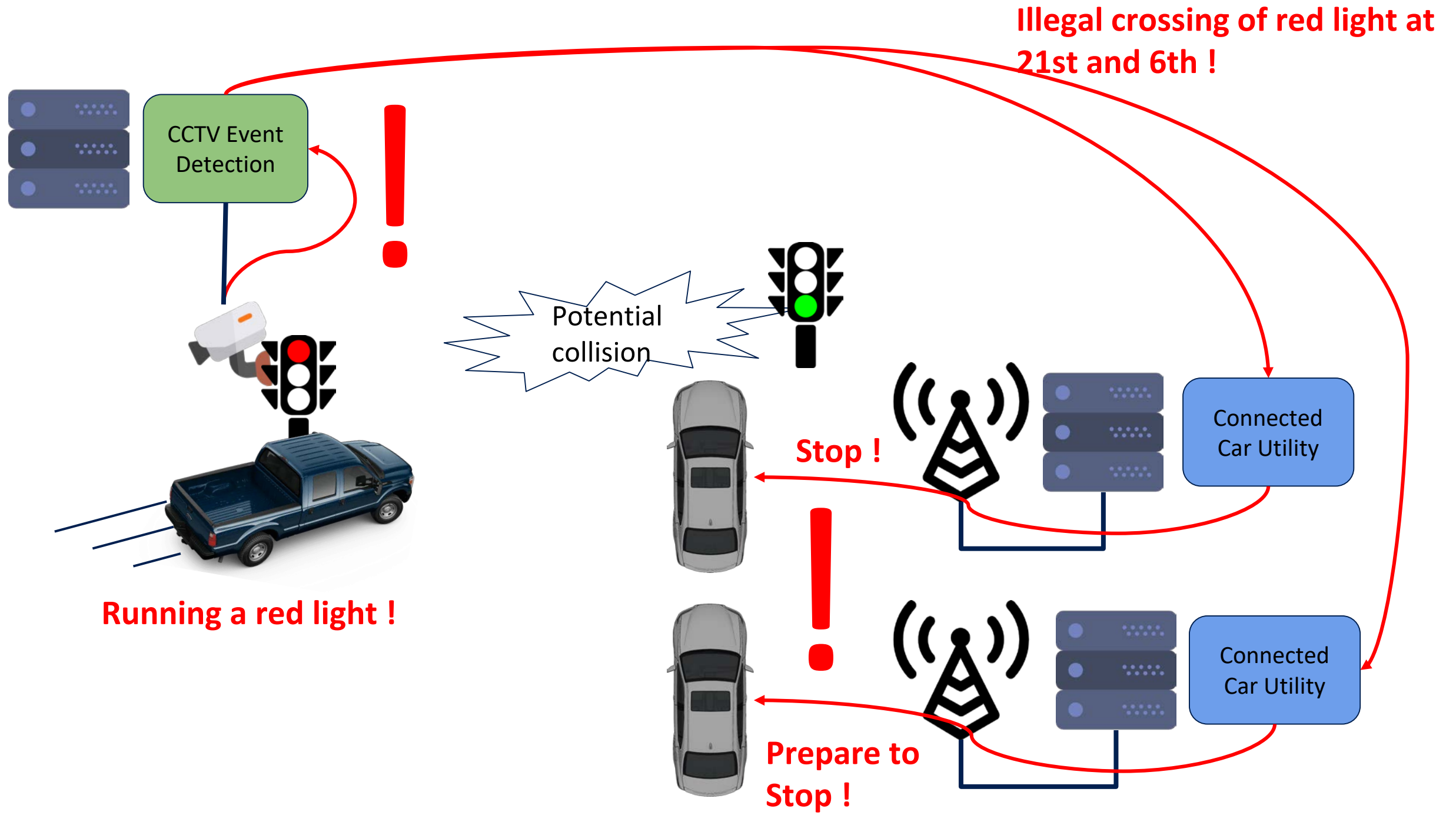
Questions?



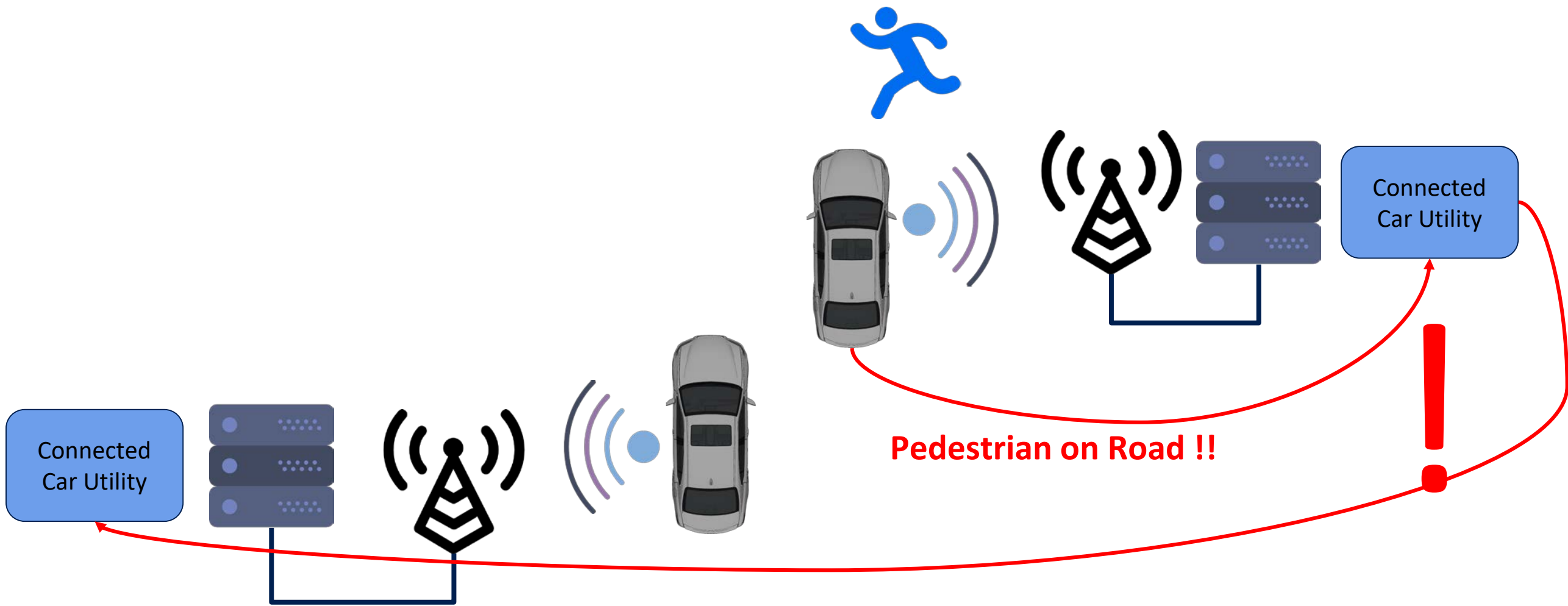
Horizontal communication

Why horizontal communication across edge nodes ?

- Can't expect multiple interacting entities to be connected to the same edge node at a time
 - Assumption : Each cell tower (eNB) has an edge-cluster
 - A vehicle connects to edge-cluster on the cell tower it's connected to
 - Cell tower (eNB) selection done locally based on best SNR
 - Two clients very close-by may be connected to different eNBs
- Allows a more flexible model , wherein low-latency messaging is provided not just to clients connected to same eNB
- In future networks, the size of base stations is going to become smaller (small cells in 5G), which would require more cross-base-station communications
- Avoiding redundancy : Nearby edge nodes share context, and making them independent would mean increased redundancy in their actions
- Load balancing : Hotspot formation is much more likely if each edge node works in isolation. P2P communication needed for better load balancing.

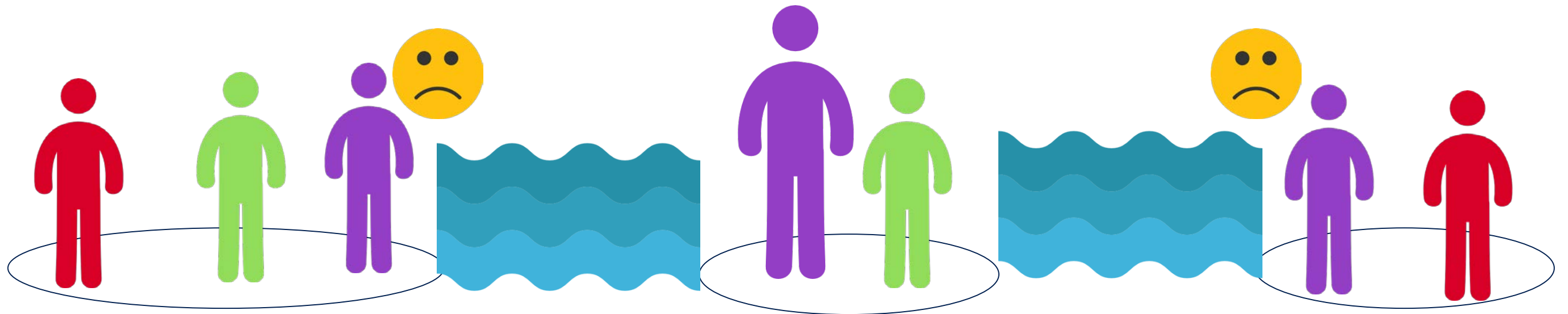


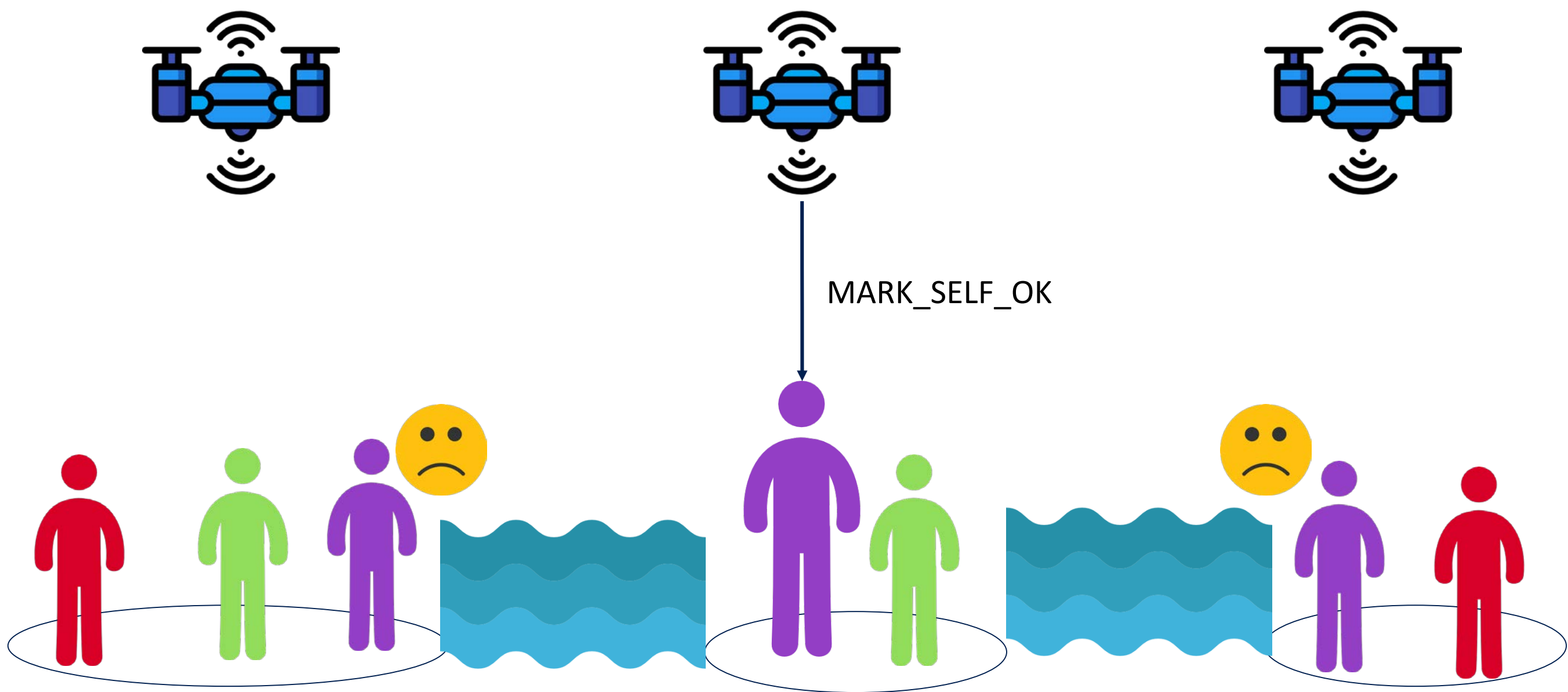
In worst case scenario, the object detection technology on each car would detect this jay-walking pedestrian. Proactive alerts are necessary to avoid such situations.



Edge without cloud

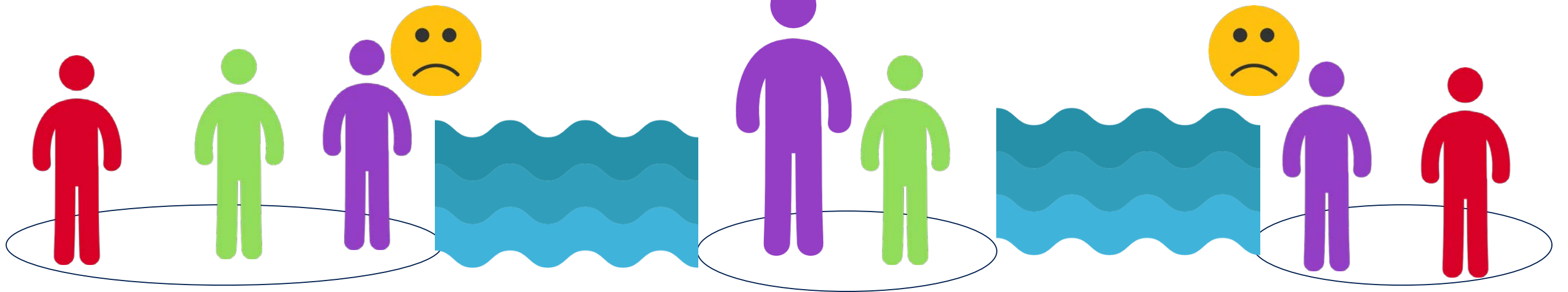
People of the same colour are 1 family. Concerned about other family members



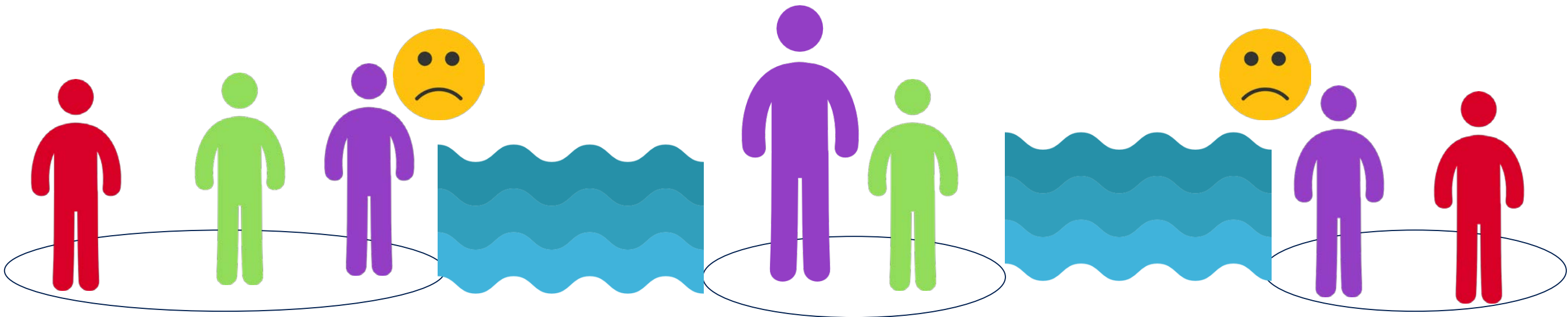
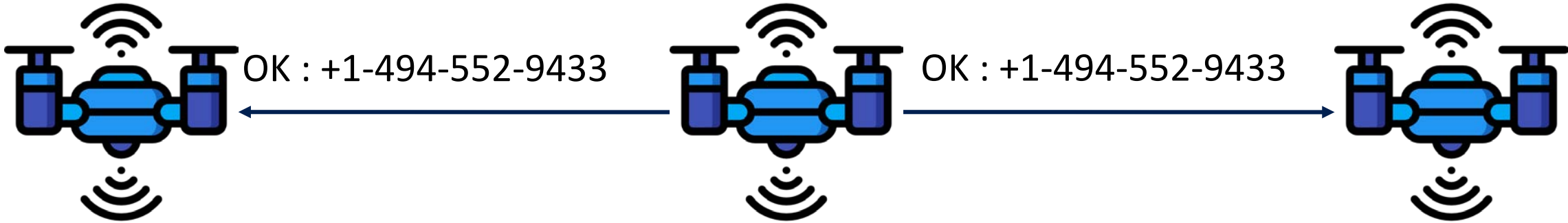


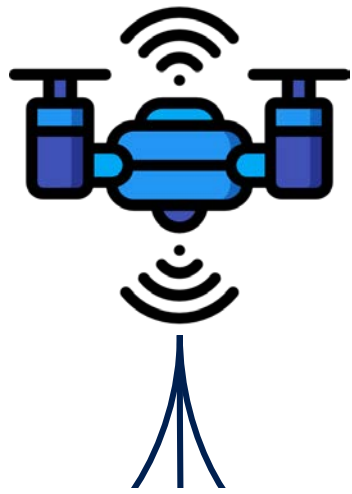


OK : +1-494-552-9433

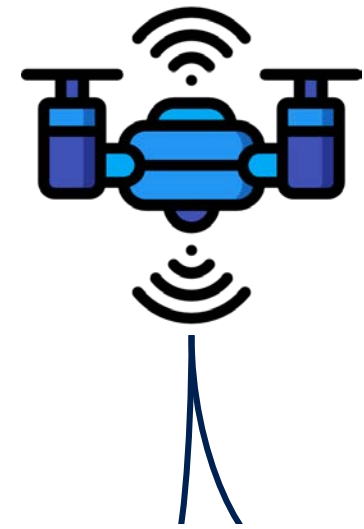


Exchange messages opportunistically

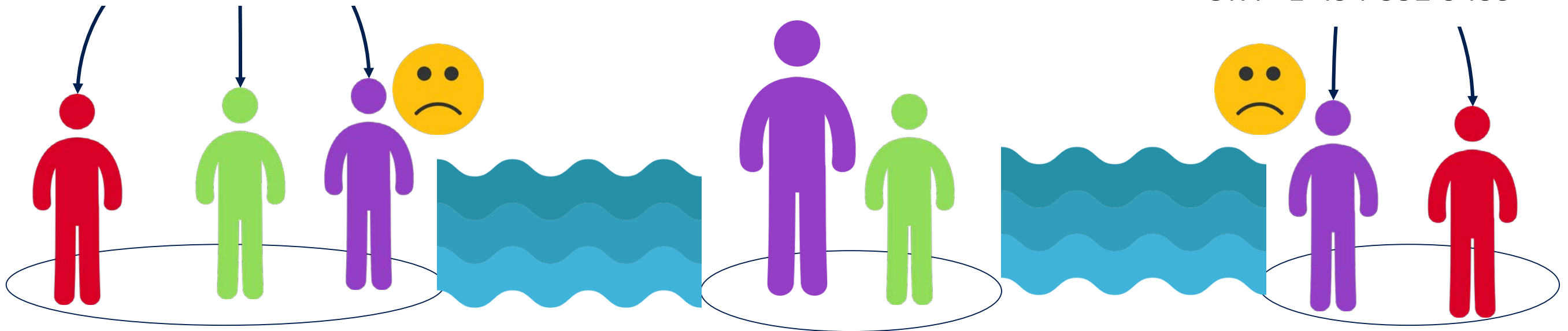


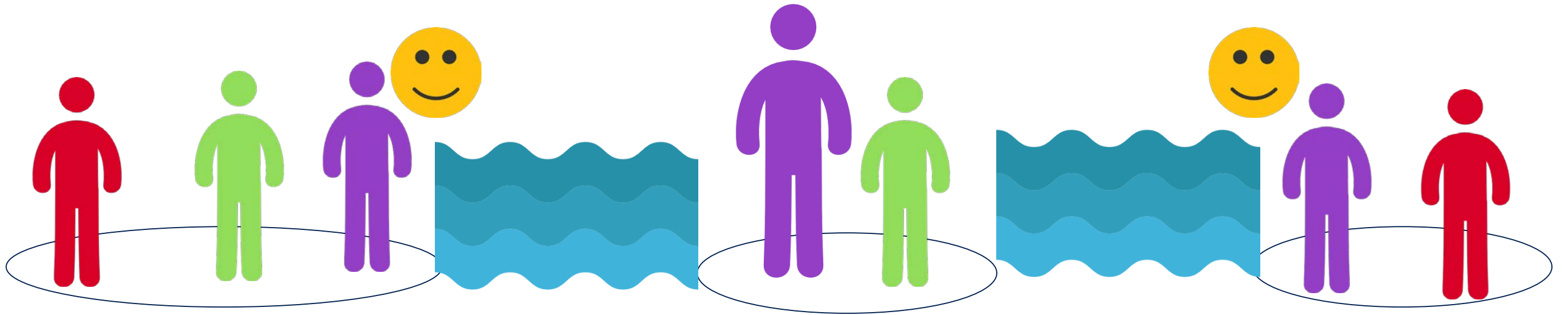
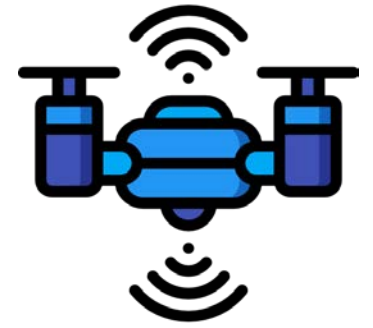


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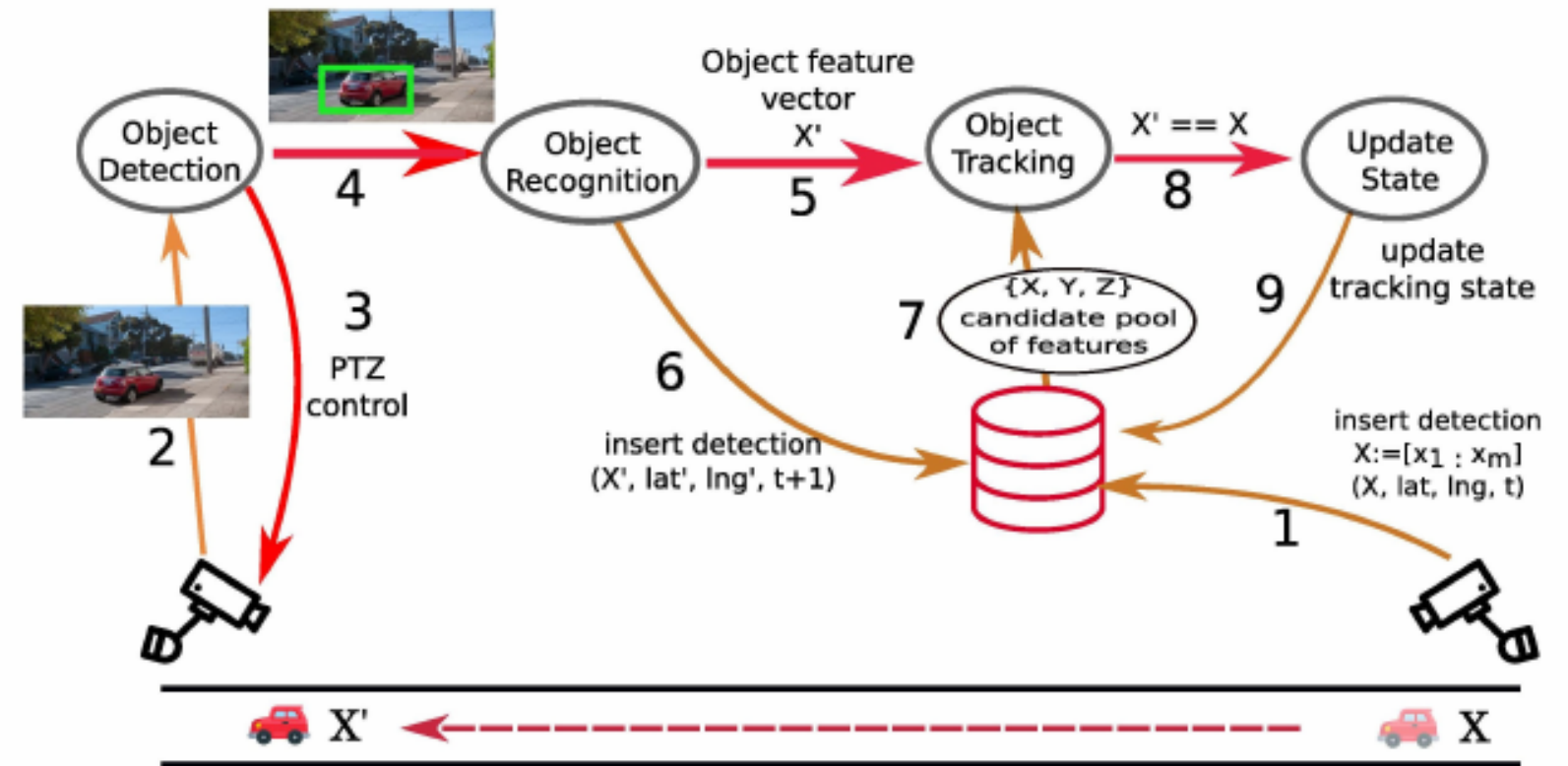
OK : +1-494-552-9433





Use case: Suspicious vehicle tracking

- Spatio-temporal range queries such as select all vehicle detections within 5km and 10 minutes to be efficient
- The distribution of workload is dependent on the distribution of vehicles in space, leading to hotspots
- For continuous operation, continuous streams of vehicle detections have to be saved in a datastore

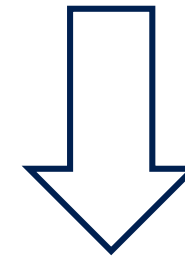


DataFog

Locality-aware distributed indexing

- Data-items are indexed based on their spatio-temporal attributes (e.g. Geohash)
- Consistent hashing for the location, timestamp and item-type attributes is used for partitioning data across nodes

```
{ "metric" : "ACV2351",  
  "location" : {  
    "latitude" : "33.42553",  
    "longitude" : "-84.74456"  
  }  
  "timestamp" : "1520123197"  
}
```

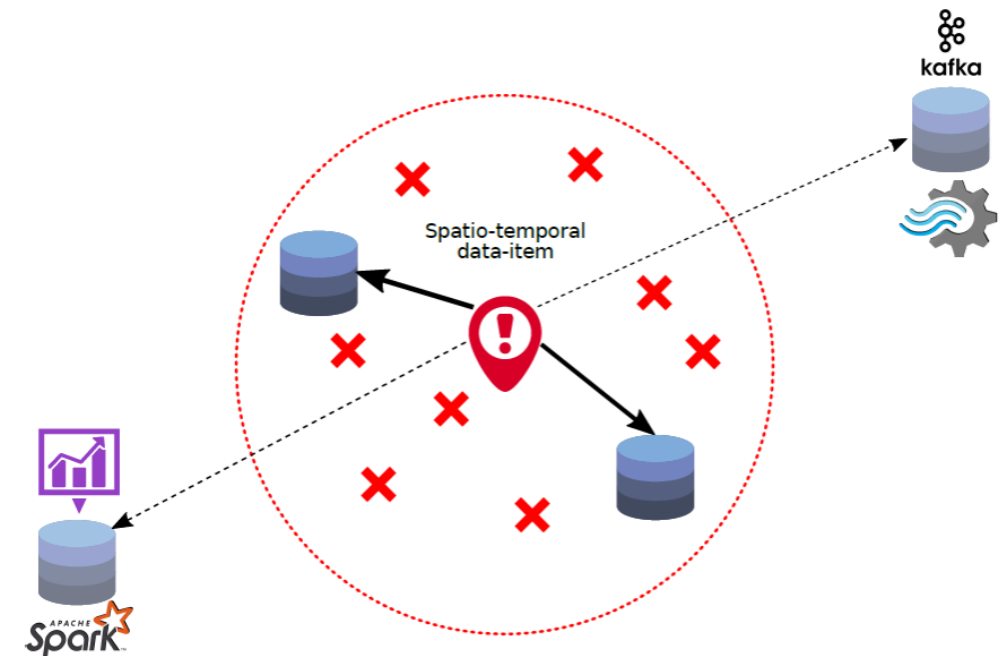
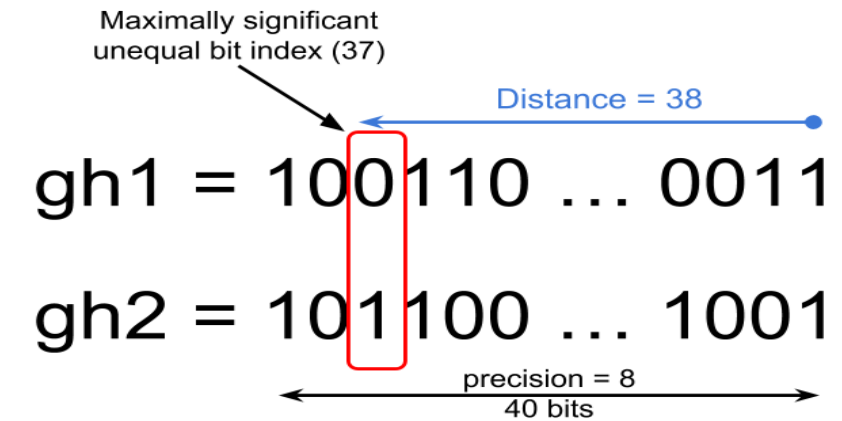


Geohash H(metric) H(timestamp)

djgw	258709251	2039412664
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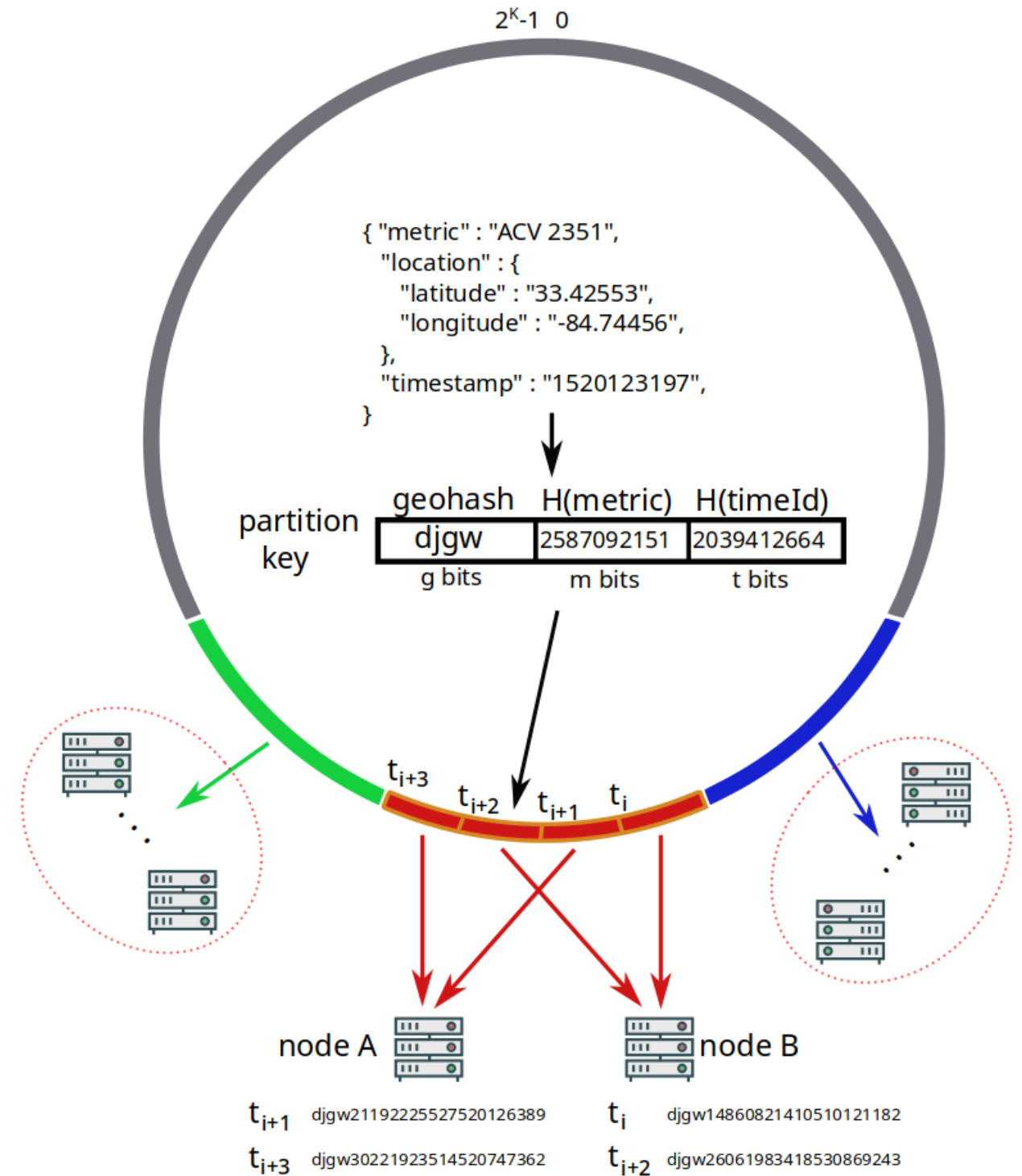
Replication Policy

- Load-balancing and fault-tolerance
- Multiple replicas on Edge nodes for low latency
- Multiple replicas on remote datacenter nodes for tolerance from geographically correlated failures



Handling workload skews

- Load-balancing region
- Partition key -> virtual node -> physical node
- Mechanisms for adapting to hotspots
 - Long-lived: launch and attach new datastore nodes to the running cluster
 - Short-lived: offload heavily loaded nodes' data items to lightly loaded nodes



Handling scarce resources at the edge

- TTL-based data eviction
 - Real-time analytics on temporal data
 - Batch-processing requires data spanning over a large period of time
- Data aggregation and compression
 - Omit redundant metadata to increase efficiency of storage utilization
 - Isomorphism of time series data

Non-closed Region and Boundary Cameras

- Create virtual cameras to connect all boundary cameras to force a closed region
- No theoretical activity upper bound for these virtual cameras
- However, in reality, vehicles active in a specified geographic region are largely "return" customers
- Archive trajectories from the virtual cameras into the cloud

Thank you

