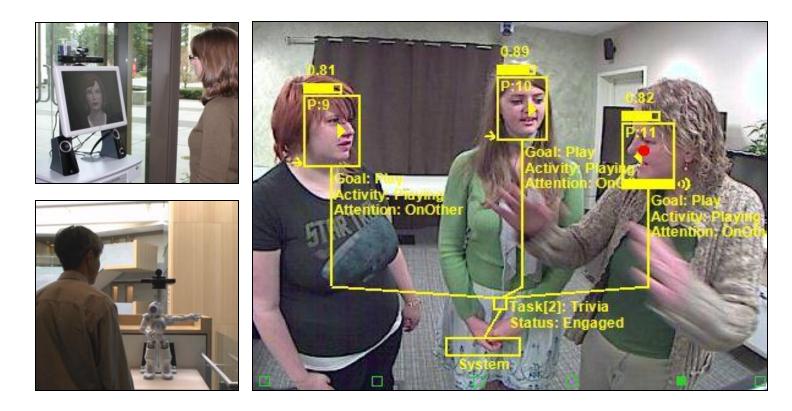
Situated Interaction in the Open World: New Systems and Challenges

Sean Andrist

with Dan Bohus, Stuart Dent, Ashley Feniello, Eric Horvitz, Mihai Jalobeanu, Ece Kamar, Nick Saw, Pat Sweeney, Andy Wilson, Zhou Yu, and more



Physically Situated AI Systems



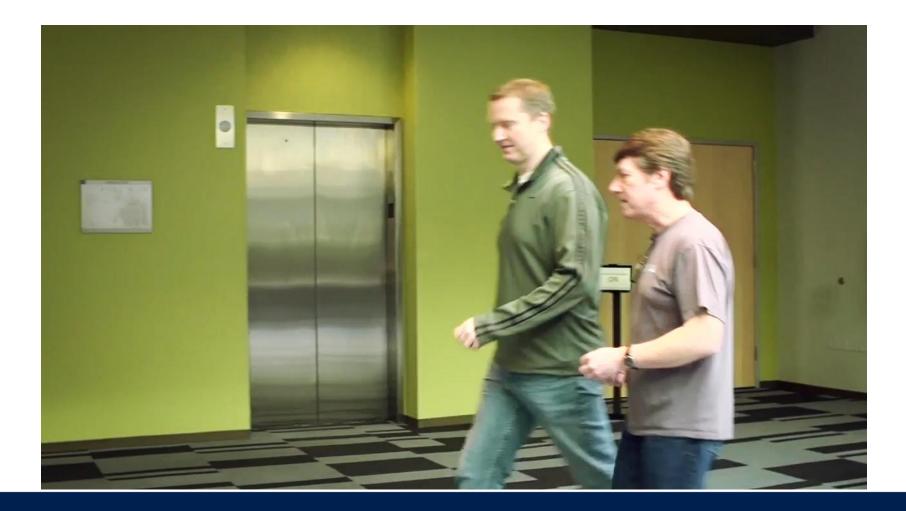
Verbal + nonverbal Embodiment Physical context Social context History

. . . .

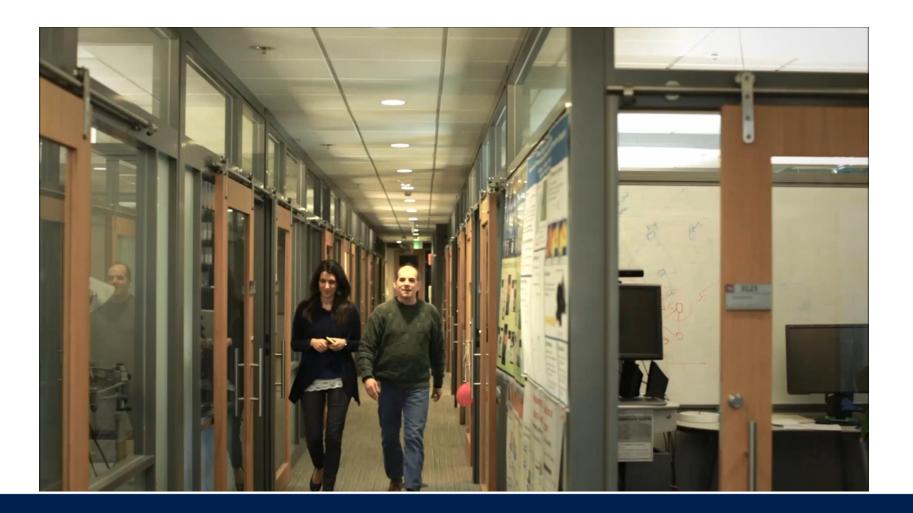


Some existing systems Research challenges Platform for situated intelligence

Smart Elevator



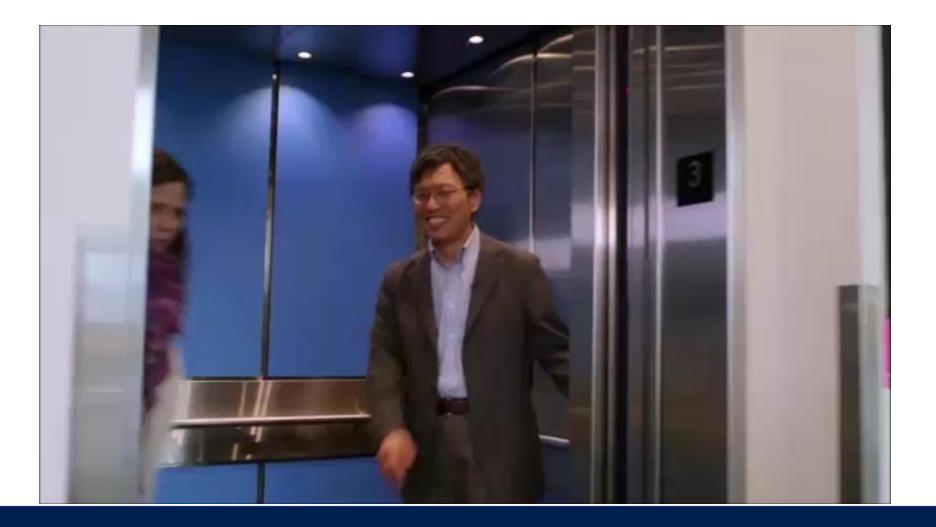
Virtual Assistant



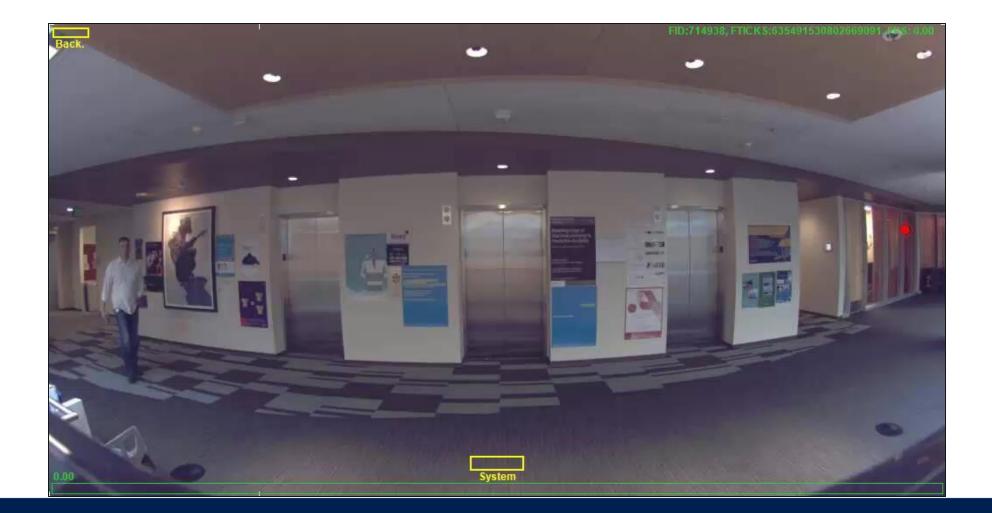
Directions Robots



Mobile Guide Robot ("PsiBot")



Challenge: Engagement

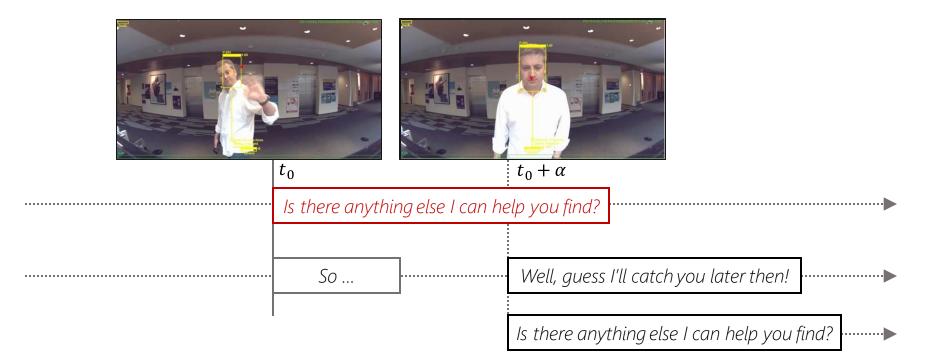




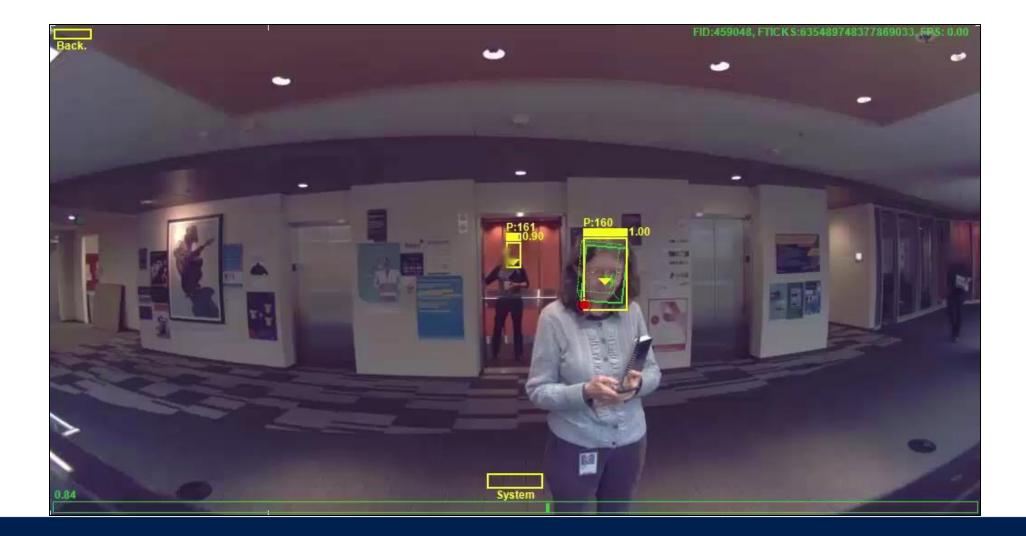
The process by which participant initiate, maintain, and break their perceived connection

Approach: Forecasting and Hesitations

Strategically use hesitations to mitigate high uncertainty



Challenge: Turn-Taking



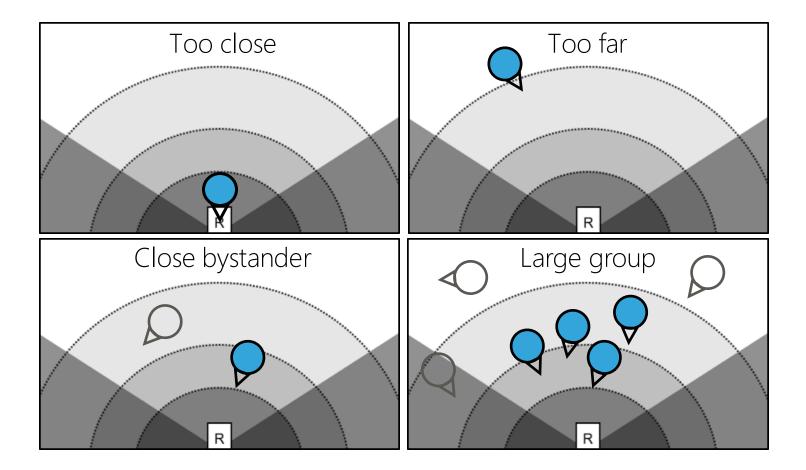
Turn-Taking

Process by which participants synchronize their verbal exchanges

Approach: Coordinate Speech and Attention



Challenge: Spatial Configurations



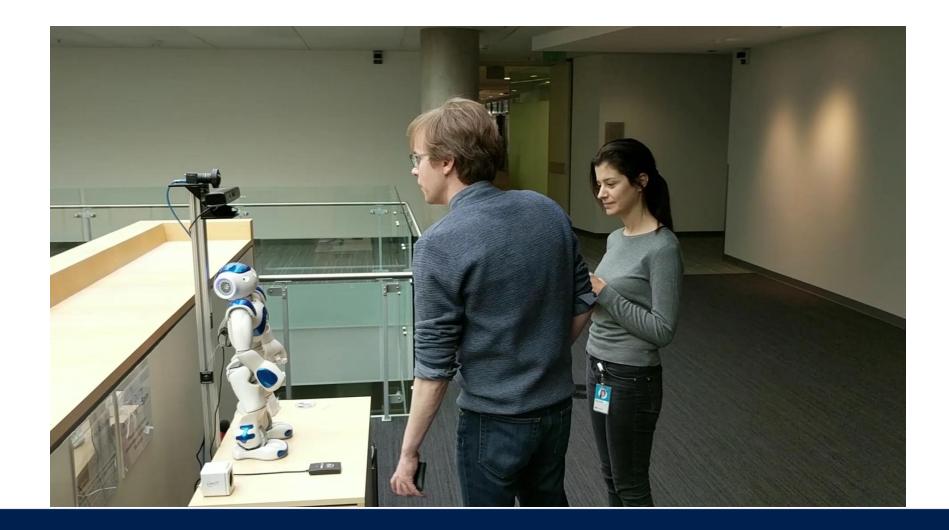
F-Formations

Spatial and orientational relationship between two or more people in a focused interaction (Kendon, 1980)

Proxemics

Organization of spatial relationships and interpersonal distances in everyday life (наш, 1963)

Approach: Scene Shaping



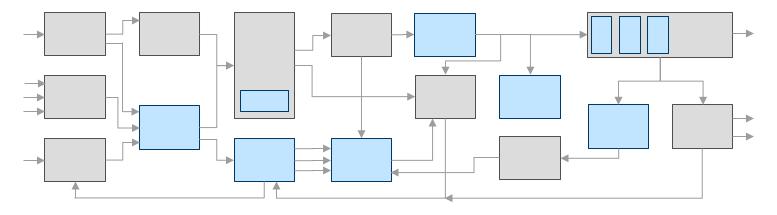
Common Themes

In-the-Wild

Problems not apparent or reproducible in lab settings Multimodal Reasoning and Fusion Forecasting

Online and self-supervised

Building/Maintaining Situated AI Systems



Microphone array capture Sound source localization Speech recognition Language understanding Infrared proximity sensors Badge sensors Face detection and tracking Head-pose tracking Facial feature tracking Face identity recognition Gender detection Attention models Engagement models Turn-taking models Behavioral control

Dialog management Natural language generation Speech synthesis Avatar synthesis Robot motion control Floor-plan models User models

Platform for Situated Intelligence (\psi)

an open, extensible framework for developing and studying situated, integrative-AI systems

Overall Architecture of \psi

Enable easy development while retaining high-performance

RUNTIME

time-aware streams | isolation | scheduling | persistence

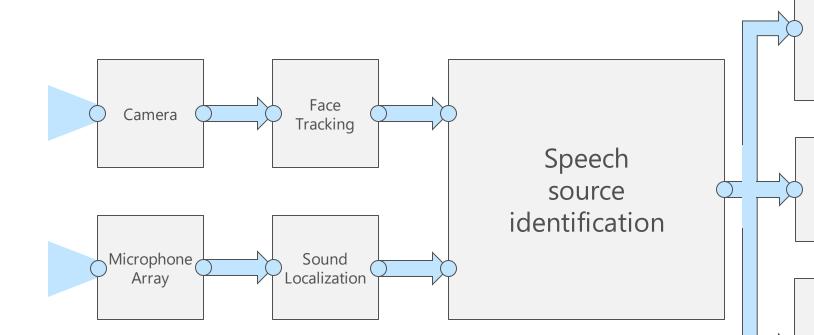
Runtime: Coordinated Pipelines

// instantiate camera and microphone
var camera = new Camera();
var microphone = new MicrophoneArray();

// instantiate speech source detector
var ssi = new SpeechSourceIdentification();

// track faces from camera and connect to
// speech source detector
camera.Out
 .TrackFaces()
 .ConnectTo(ssi.FacesInput);

// do localization and connect to speech
// source detector
microphone.Out
 .Localize()
 .ConnectTo(ssi.SourceAngleInput);



Overall Architecture of \psi

Enable a fast debugging + visualization + ML cycle

Enable easy development while retaining high-performance

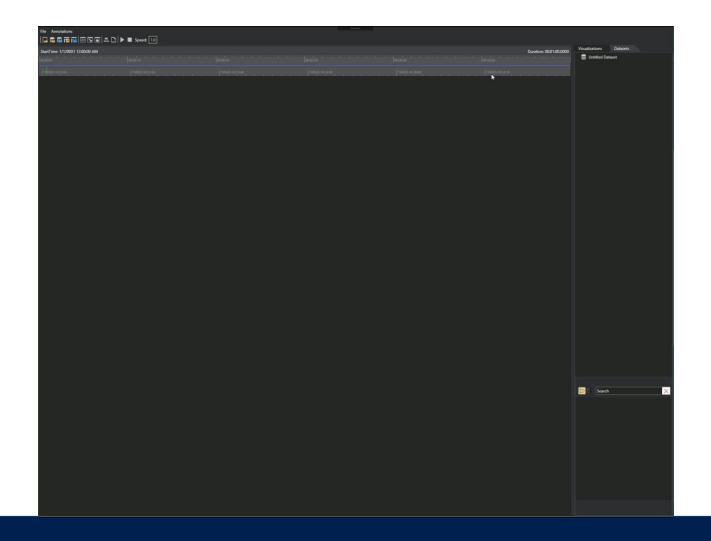
TOOLS

visualization & debugging | data processing | machine learning

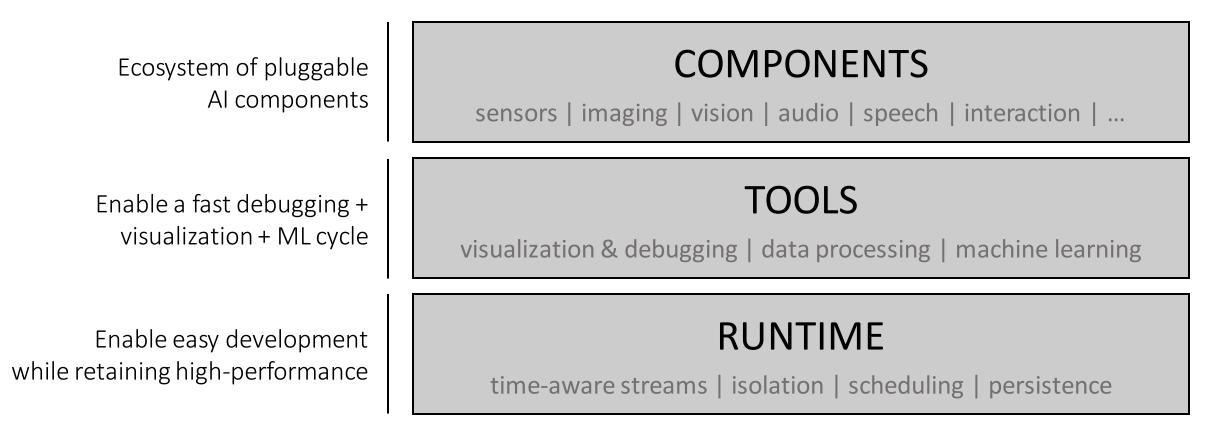
RUNTIME

time-aware streams | isolation | scheduling | persistence

Tools: Visualization



Overall Architecture of \psi



Thank You!

Perception and Interaction Group

https://www.microsoft.com/en-us/research/group/perception-and-interaction/

Situated Interaction Project

https://www.microsoft.com/en-us/research/project/situated-interaction/

Platform for Situated Intelligence (\psi)

https://www.microsoft.com/en-us/research/project/platform-situated-intelligence/