

Feature Purification: How Adversarial Training Performs Robust Deep Learning

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Abstract

Despite the great empirical success of adversarial training to defend deep learning models against adversarial perturbations, so far, it still remains rather unclear what the principles are behind the existence of adversarial perturbations, and what adversarial training does to the neural network to remove them.

In this paper, we present a principle that we call “feature purification”, where we show the existence of adversarial examples are due to the accumulation of certain “dense mixtures” in the hidden weights during the training process of a neural network; and more importantly, one of the goals of adversarial training is to remove such mixtures to “purify” hidden weights. We present both experiments on the CIFAR-10 dataset to illustrate this principle, and a **theoretical result proving** that for certain natural classification tasks, training a two-layer neural network with ReLU activation using randomly initialized gradient descent *indeed* satisfies this principle.

Technically, we give, to the best of our knowledge, the first result *proving* that the following two can hold simultaneously for training a neural network with ReLU activation. (1) Training over the original data is indeed non-robust to small adversarial perturbations of some radius. (2) Adversarial training, even with an *empirical* perturbation algorithm such as FGM, can in fact be *provably* robust against *any* perturbations of the same radius. Finally, we also prove a complexity lower bound, showing that low complexity models such as linear classifiers, low-degree polynomials, or even the neural tangent kernel for this network, *cannot* defend against perturbations of this same radius, no matter what algorithms are used to train them.

*V1 of this paper was presented at IAS on this date, and can be viewed online: <https://video.ias.edu/csdlm/2020/0316-YuanzhiLi>. We added more experiments in V1.5.

We would like to thank Sanjeev Arora for many useful feedbacks.

1 Introduction

Large scale neural networks have shown great power to learn from a training data set, and generalize to unseen data sampled from similar distributions for applications across different domains [39, 43, 50, 83]. However, recent study has discovered that these trained large models are extremely vulnerable to small “adversarial attacks” [17, 91]: It has been discovered that small perturbations to the input— often small enough to be invisible to humans— can create numerous errors in prediction. Such slightly perturbed inputs are often referred to as “adversarial examples”.

Since the original discovery of “adversarial examples”, a large body of works have been done emphasizing how to improve the robustness of the deep learning models against such perturbations [41, 59, 60, 79, 85]. One seminal approach is called the *adversarial training* [61], where one iteratively compute the adversarial perturbations for the training examples and retrain the model with these adversarial examples. This approach was also reported in [13] as the only approach that can defend carefully designed adversarial attacks.

However, despite the great empirical success on improving the robustness of neural networks over various data sets, the theory of the adversarial examples is much less developed. In particular, we found that the following fundamental questions remain largely unaddressed:

Questions

Why do adversarial examples exist when we train the neural networks using the original training data set? How can adversarial training further “robustify” the trained neural networks against these adversarial attacks?

To answer these questions, one sequence of theoretical works try to explain the existence of adversarial examples using the high dimensional nature of the input space and the over-fitting behavior due to the sample size and sample noise [29, 30, 36, 37, 63, 82, 92], and treat adversarial training from the broader view of min-max optimization [21, 61, 88, 89, 98]. However, recent observations [45] indicate that these adversarial examples can also, and arguably often, arise from *features* (those that do generalize) rather *bugs* (those that do not generalize due to effect of poor statistical concentration). Moreover, to the best of our knowledge, all of the existing works study adversarial examples either (1) applying to the case of an unstructured function f , or (2) under a structured setting involving only linear learners. These theoretical works, while shedding great lights to the study of adversarial examples, do not yet give concrete mathematical answers to the following questions regarding the specific hidden-layer structure of **neural networks**, which we refer to as “features”:

1. What are the features (i.e. the hidden weights) learned by the neural network via clean training (i.e., over the original data set)? Why are those features “non-robust”?
2. What are *differences* between the features learned by *clean training* vs *adversarial training* (i.e., over a perturbed data set consisting of adversarial examples)?
3. Why do adversarial examples for one neural network transfer to other independently trained networks?

To answer these questions, it is inevitable to study what are the features (i.e. the hidden weights) learned by a neural network during clean training. We point out theoretical studies are rather limited in this direction: Most of the works only focus on the case when the training data is spherical Gaussian or require heavy initialization using tensor decomposition [14, 18, 20, 33, 49, 52, 55, 57, 84, 86, 93, 95, 99, 105, 107], which might fail to capture the specific structure of the input; or only consider the neural tangent kernel regime, where the neural networks are linearized so the features are not learned (they stay at random initialization) [4, 6–8, 11, 12, 23, 23–

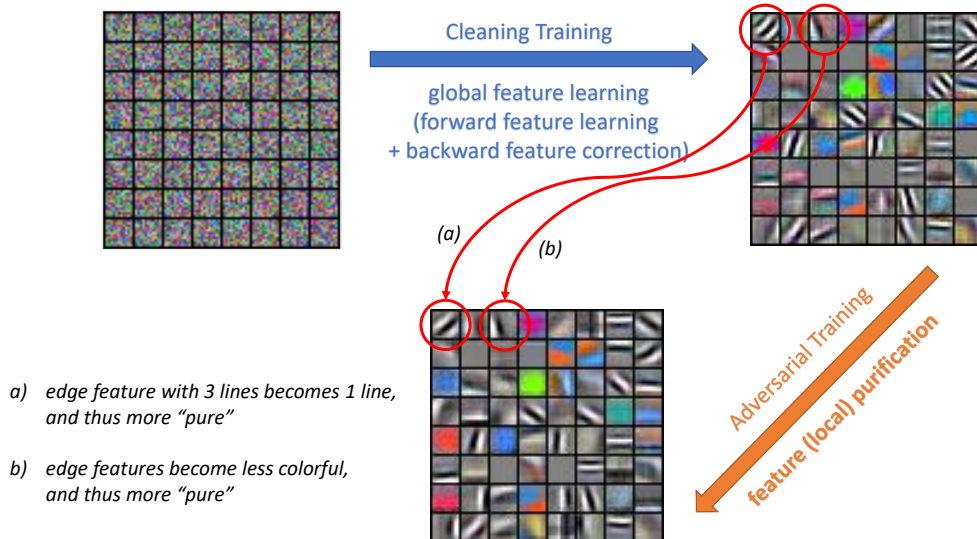


Figure 1: Feature purification in adversarial training (for the first layer of AlexNet on CIFAR-10). Another visualization of some deeper layer of ResNet can be found in Figure 5.

26, 35, 42, 47, 54, 58, 100, 108, 109].

In this paper, we present a new routine that enables us to formally study the **learned features** (i.e. the *hidden weights*) of a neural network, when the inputs are more naturally structured than being spherical Gaussians. Using this tool, we give, to the best of our knowledge, the *first theoretical result* towards answering the aforementioned fundamental questions of adversarial examples, for **neural networks** with **ReLU** activation functions. We summarize our contributions as follows:

Our theoretical results. One way to interpret our result is as follows. We **prove**, for certain binary classification data set, when we train a *two-layer ReLU neural network* using *gradient descent (GD)*, *starting from random initialization*,

1. As long as polynomially many training examples are used, and in polynomially number of iterations, the learned neural network will learn *well-generalizing features*, and the learned network will have close-to-perfect prediction accuracy for the unseen data sampled from the same distribution.
2. However, even with a weight decay regularizer to avoid over-fitting, even with *infinitely many training data*, and even when *super-polynomially many iterations* are used to train the neural network to convergence, the learned network still has near-zero robust accuracy against small norm-bounded adversarial perturbations to the data. In other words, those *provably well-generalizing features are also provably non-robust*.
3. Adversarial training, using perturbation algorithms such as fast gradient method (FGM) [37], can *provably and efficiently* make the learned neural network nearly-perfectly robust against even the worst-case norm-bounded adversarial perturbations, using a principle we refer to as “feature purification”. See Figure 1 for an illustration in experiment.

Feature purification: How adversarial training can perform robust deep learning. In this work, we also give precise, mathematical characterizations on the *difference* between learned features by clean training versus adversarial training, leading to (to our best knowledge) the first explanation of *how, the provably non-robust features after clean training can be provably “robustified” via adversarial training*. We emphasize in prior theoretical works [32, 48, 80, 106], they study

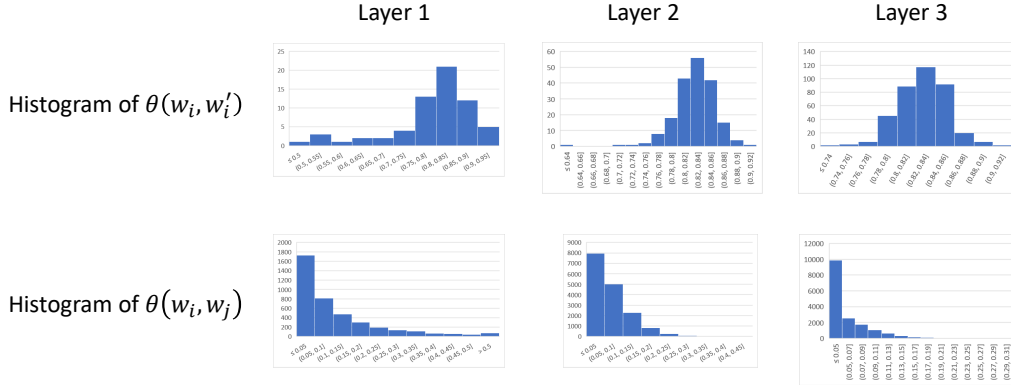


Figure 2: Measure of feature purifications, AlexNet on CIFAR-10 data set

adversarial examples in the context of *linear* models (such as linear regression, linear regression over prescribed feature mappings, or the neural tangent kernels). In those models, the features are *not* trained, so adversarial training only changes the weights associated with the linear combination of these features, but not the actual features themselves.

In our work, we have developed, to the best of knowledge, the *first theory* on how adversarial training **can actually change the features** of a neural network to improve its robustness. We call this principle *feature purification*. Let us describe the high-level idea of this principle as follows.

The Principle of Feature Purification

During adversarial training, the neural network will *neither* learn new, robust features *nor* remove existing, non-robust features learned over the original data set. Most of the works of adversarial training is done by *purifying a small part of each learned features after clean training*.

Mathematically, as a *provisional* step to measure of change of features in a network, let us use $w_i^{(0)}$ to denote the weight of the i -th neuron at initialization, use w_i to denote its weight after clean training (using $w_i^{(0)}$ as initialization), and use w'_i to denote its weight after adversarial training (using w_i as initialization). The “feature purification” principle, in math, says if we use $\theta(z, z') := \frac{\langle z, z' \rangle}{\|z\|_2 \|z'\|_2}$ as a *provisional* measure of the correlation between “features”, then (see also Figure 2)

1. for most neurons: $\theta(w_i^{(0)}, w_i), \theta(w_i^{(0)}, w'_i) = o(1)$;
2. for most neurons: $\theta(w_i, w'_i) \geq C$ for a large constant C ; and
3. for most pairs of different neurons: $\theta(w_i, w_j) = o(1)$.

Thus, this principle implies that both clean training and adversarial training discover hidden weights w, w' fundamentally different from the prescribed initialization $w^{(0)}$. However, in fact clean training has already discovered a *big portion* of the “robust features”, and adversarial training merely needs to “purify” some small part of each original feature. Our theory provides a proof to this phenomenon, and more importantly, we also give a characterization on what are the “non-robust” part of each feature that needs to be purified during adversarial training. We summarize it as follows.

Why clean training learns non-robust features? Our work gives mathematical characterizations of where the “non-robust” part of each feature comes from during clean training. As we shall discuss in more detail in Section 6.2, training algorithms such as gradient descent will, at every step, add to the current parameters a direction that is *maximally correlated with the label*

ing function on average. Our main observation is that such simple correlations will accumulate, in each neuron, a “dense mixture” which is also maximumly correlated with the *average of the training data*. However, due to a natural structure of the training examples we refer to as the **sparse coding model**, such “dense mixture” does not have high correlation with any individual natural training example. Thus, even with these “dense mixtures” in the features, the network can still generalize well on the original data set due to the low correlation of “dense mixtures” with any natural training examples. However, we observe and prove that these portions of the features are extremely vulnerable to small, adversarial perturbations to perturb the original input along the “dense mixture” directions. Therefore, one of the main goals of adversarial training, as we show, is to purify the neurons by removing such “dense mixtures”. This is one of the main principal behind **feature purification**.

Moreover, our theoretical work implies that these “dense mixtures” come from the “sparse coding” structure of the data and the gradient descent training algorithm. It is rather independent of the random initialization of the neural network at the beginning. Thus, we prove that, at least in our scenario, adversarial examples for one network do transfer to other independently trained ones. This is given in more details in Theorem 5.2 and Section 6.2.

Our contribution to computation complexity. We also prove a lower bound that, in special case of the main theorem for neural networks, even when the original data is linearly-separable, any linear classifier, any low-degree polynomial, or even the corresponding neural tangent kernel (NTK) of this two-layer neural network, *cannot* achieve meaningful robust accuracy (although they can easily achieve high clean accuracy). Together with our upper bound, we have shown that using a *higher-complexity model* (such as a two-layer neural network with ReLU activation, comparing to NTK) can in fact achieve *better* robustness against adversarial perturbations. Thus, our theory **strongly supports** the experimental finding in [37, 61], where experts have noticed that robustness against adversarial examples requires a model with higher complexity. The main intuition is that low complexity models, including the neural tangent kernel, lacks the power to *zero out* low magnitude signals to improve model robustness, as illustrated in Figure 3 and Section 3.

Our experimental contributions. We also present quite a few experimental results supporting our theory. (1) Our sparse coding model can indeed capture real-world data to certain degree. (2) Our principle of feature purification also holds for architectures such as AlexNet and ResNet. (3) Adversarial training using adversarial examples indeed purify some “dense mixtures” in practice. (4) During clean training, *how* the features can emerge from random initialization by *winning the “lottery tickets”*, as predicted by our theory. We present our experiments following each of the theorem statements accordingly. We also include a whole Section 8 for more detailed experiments.

1.1 Related works

Adversarial examples: Empirical study. Since the seminal paper [91] shows the existence of small adversarial perturbations to change the prediction of the neural networks, many empirical studies have been done to make the trained neural networks robust against perturbations [41, 59, 60, 79, 85] (and we refer to the citations therein). The recent study [13] shows that the seminal approach [61] of adversarial training is the most effective way to make the neural networks robust against adversarial perturbations.

Adversarial examples: Theoretical study. Existing theories mostly explain the existence of adversarial examples as the result of finite-sample data set over-fitting to high-dimensional learning problems [29, 30, 36, 37, 63, 82, 92]. Later, it is discovered by Ilyas et al. [45] that well-generalizing

features can also be non-robust. Other theories focus on the Fourier perspective of the robustness [97, 103], showing that adversarial training might be preventing the network from learning the high frequency signals of the input image. Our theoretical work is fundamentally different from the aspect of poor statistical concentration over finite-sample data set, and our Theorem 5.1 and Theorem 5.3 **strongly supports** [45] that a well-trained, well-generalizing neural network can still be non-robust to adversarial attacks.

Other theories about adversarial examples focus on how adversarial training might require more training data comparing to clean training [80], and might decrease clean training accuracy [76]. The works by [32, 106] focus on how adversarial training can be performed efficiently in the neural tangent kernel regime. The purpose of these results are also fundamentally different than ours.

Sparse coding. We use a data model called sparse coding, which is a popular model to model image, text and speech data [65, 73, 74, 96, 101, 102]. There are many existing theoretical works studying algorithm for sparse coding [9, 15, 40, 44, 51, 64, 81, 87, 90], however, these algorithms share little similarity to training a *neural network*.

The seminal work by Arora et al. [10] provides a neurally-plausible algorithm for learning sparse coding along with other works using alternative minimization [1, 2, 34, 53, 56]. However, all of these results require a (carefully picking) warm start, while our theory is for training a neural network starting from *random initialization*.

Threshold degree and kernel lower bound. We also provide, to the best of our knowledge, the first example when the original *classification* problem is learnable using a linear classifier but *no low-degree polynomial* can learn the problem *robustly* against small adversarial perturbations. Yet, the high-complexity neural networks can provably, efficiently and robustly learn the concept class. The lower bound for the classification accuracy using low-degree polynomials has been widely studied as the (approximate) threshold degree of a function or the sign-rank of a matrix [16, 19, 22, 38, 71, 77]. Our paper give the first example of a function with high (approximate) robust threshold degree, yet efficiently and robustly learnable by training a ReLU neural network using gradient descent.

Other related works prove lower bounds for kernel method in the regression case [3, 5]. Generally speaking, such lower bounds are about the actual (approximate) degree of the function, instead of the (approximate) threshold degree. It is well know that for general functions, the the actual degree can be arbitrary larger than the threshold degree.

2 Preliminaries

We use $\|x\|$ or $\|x\|_2$ to denote ℓ_2 norm of a vector x , and $\|x\|_p$ to denote the ℓ_p . For a matrix $\mathbf{M} \in \mathbb{R}^{d \times d}$, we use \mathbf{M}_i to denote the i -th column of \mathbf{M} , and we use $\|\mathbf{M}\|_\infty$ to denote $\max_{i \in [d]} \sum_{j \in [d]} \mathbf{M}_{i,j}$ and $\|\mathbf{M}\|_1$ to denote $\max_{j \in [d]} \sum_{i \in [d]} \mathbf{M}_{i,j}$. We use $\text{poly}(d)$ to denote $\Theta(d^C)$ when the degree C is some not-specified constant. We use the term clean training to refer to the neural network found by training over the original data set, and the term robust training to refer to the neural network found by adversarial training. We let $\text{sign}(x) = 1$ for $x \geq 0$ and $\text{sign}(x) = -1$ for $x < 0$.

Sparse coding model. We consider the training data $x \in \mathbb{R}^d$ generated from

$$x = \mathbf{M}z + \xi$$

for a dictionary $\mathbf{M} \in \mathbb{R}^{d \times D}$, where the *hidden vector* $z \in \mathbb{R}^D$ and ξ is the noise. For simplicity, we focus on $D = d$ and \mathbf{M} is a unitary matrix, although our results extend trivially to the case of $D < d$ or when \mathbf{M} is incoherent.

We assume the hidden vector z is “sparse”, in the following sense: for $k \leq d^{0.499}$, we have:

Assumption 2.1 (distribution of hidden vector z). *The coordinates of z are independent, symmetric random variables, such that $|z_i| \in \{0\} \cup [\frac{1}{\sqrt{k}}, 1]$. Moreover,*

$$\mathbb{E}[z_i^2] = \Theta\left(\frac{1}{d}\right), \quad \Pr[|z_i| = 1] = \Omega\left(\frac{1}{d}\right), \quad \Pr\left[|z_i| = \Theta\left(\frac{1}{\sqrt{k}}\right)\right] = \Omega\left(\frac{k}{d}\right)$$

The first condition is a regularity condition, which says that $\mathbb{E}[\|z\|_2^2] = \Theta(1)$. The second and third condition says that there is a non-trivial probability where z_i attains the maximum value, and a (much) larger probability that z is non-zero but has a small value (Remark: It could be the case that z_i is neither maximum nor too small, for example, $|z_i|$ can also be $k^{-0.314}$ with probability $\frac{k^{0.628}}{d}$ as well, or $k^{-0.123}$ with probability $\frac{k^{0.0888}}{d}$). The main observation is that

Fact 2.2. *Under Assumption 2.1, w.h.p., $\|z\|_0 = \Theta(k)$ is a sparse vector.*

Our model of x is known as the sparse coding model, which is widely use to model image, text and speech data [65, 73, 74, 96, 101, 102].

We study the simplest binary-classification problem, where the labeling function is linear over the hidden vector z :

$$y(x) = \text{sign}(\langle w^*, z \rangle)$$

For simplicity, we assume $\forall i \in [D], |w_i^*| = \Theta(1)$, so all the coordinates of z have relatively equal contributions. Our theorems extend to other w^* at the expense of complicating notations.

Noise model. We have allowed the inputs $x = \mathbf{M}z + \xi$ to incorporate a noise vector ξ . Our lower bounds hold even when there is no noise ($\xi = 0$). Our upper bound theorems not only apply to $\xi = 0$, but more generally to a general noise model where ξ is a gaussian noise plus a ‘‘spike noise’’:

$$\xi = \xi' + \mathbf{M}\xi''$$

Here, the gaussian noise $\xi' \sim \mathcal{N}(0, \frac{\sigma_x^2}{d}\mathbf{I})$ with $\sigma_x^2 \leq O(1)$. The spike noise ξ'' is any coordinate-wise independent, mean-zero random variable satisfying $\mathbb{E}[\xi_i''^2] \leq O\left(\frac{\sigma_x^2}{d}\right)$ for every $i \in [d]$ and $\|\xi''\|_\infty \leq \frac{1}{k^{0.501}}$, slightly smaller than the $\frac{1}{k^{0.5}}$ of the signal. Our upper bound theorems show that neural network can learn the concept class efficiently even when the ‘‘spike’’ noise is nearly theoretically the largest, and can even learn so robustly.

We point out that there are also essentially *no dependencies* among the constants in those O, Θ and Ω notations of this section, except for those obvious ones (for example $\Pr[|z_i| = 1] \leq \mathbb{E}[|z_i|^2]$). In particular, σ_x can be an arbitrarily large constant and $\Pr[|z_i| = 1]$ can be an arbitrary small constant times $1/d$.¹

Clean and robust error. The goal of clean training is to learn a model f so that $\text{sign}(f(x))$ is as close to y as possible. We define the error on the original data set (a.k.a. the *clean error*) as:

$$\mathcal{E}^c(f) = \Pr_{x,y=y(x)}[\text{sign}(f(x)) \neq y] \tag{2.1}$$

Next, we consider robust error against ℓ_p adversarial perturbations. For a value $\tau > 0$ and a norm $\|\cdot\|_p$, we define the robust error of the model f (against ℓ_p perturbation of radius τ) as:

$$\mathcal{E}^r(f) = \Pr_{x,y=y(x)}[\exists \delta : \|\delta\|_p \leq \tau : \text{sign}(f(x + \delta)) \neq y] \tag{2.2}$$

¹Actually, our theorem extends trivially to the case even when $\Pr[|z_i|] = \frac{1}{d^{1+o(1)}}$.

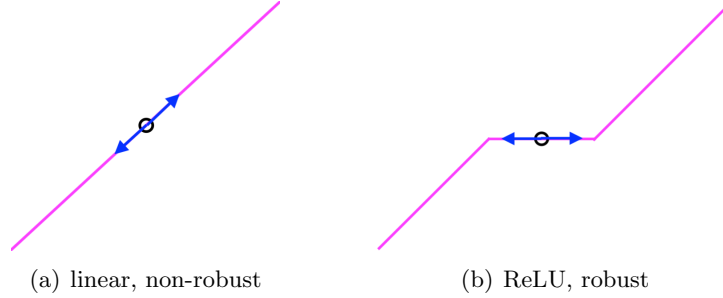


Figure 3: Higher-complexity models using a ReLU activation is more robust than a linear classifier due to the power to “zero-out” low-magnitude signals. (Our theorem is in symmetric ReLU for the sake of proof simplicity.)

3 Warmup Intuitions

Linear learners are not robust. One direct approach is to use (the sign of) a linear classifier $f(x) = \langle w^*, \mathbf{M}^\top x \rangle$ to predict the label of x . There are two issues of using such a classifier:

1. When σ_x is as large as $\Theta(1)$, such classifier can not even classify x in good *clean* accuracy. Recall $f(x) = \langle w^*, \mathbf{M}^\top x \rangle = \langle w^*, z \rangle + \langle \mathbf{M}w^*, \xi \rangle$. By our assumption, typically $|\langle w^*, z \rangle| = O(1)$ and $\langle \mathbf{M}w^*, \xi \rangle \sim \mathcal{N}(0, \Theta(\sigma_x^2))$. Thus, when $\sigma_x \geq \Theta(1)$, noise could be much larger than signal, and this linear classifier cannot be used to classify x correctly. In this case, actually no linear classifier (or even constant-degree polynomials²) can give meaningful clean accuracy.
2. Even when $\sigma_x = 0$ so the original data is perfectly linearly-classifiable, linear classifier is also not robust to small perturbations. Since typically $|\langle w^*, z \rangle| = O(1)$ and $\|w^*\|_2 = \Theta(\sqrt{d})$, one can design an adversarial perturbation $\delta = \frac{-C y \mathbf{M} w^*}{\|w^*\|_2^2}$ for a large constant C , that can change the sign of the linear classifier $f(x) = \langle w^*, \mathbf{M}^\top x \rangle$ for most inputs. Thus, this linear classifier *is not even robust* to adversarial perturbations of ℓ_2 norm $\Theta\left(\frac{1}{\sqrt{d}}\right)$. In fact, no linear classifier can be robust to such small adversarial perturbations.

High-complexity models are more robust. Another choice to learn the labeling function is to use a higher-complexity model $f(x) = \sum_{i \in [d]} w_i^* \langle \mathbf{M}_i, x \rangle \mathbb{1}_{|\langle \mathbf{M}_i, x \rangle| \geq \frac{1}{2\sqrt{k}}}$. Here, the “complexity” of f is much higher because an indicator function is used.³ Since $\langle \mathbf{M}_i, x \rangle = z_i + \langle \mathbf{M}_i, \xi \rangle$, by our noise model, we can show that as long as $z_i \neq 0$, $|\langle \mathbf{M}_i, x \rangle| \geq \frac{1}{2\sqrt{k}}$ with high probability. Thus, $f(x)$ is equal to the true labeling function $\langle w^*, z \rangle$ w.h.p. over the original data set, which is (much) more *robust to noise* comparing to a linear model $\langle w^*, \mathbf{M}^\top x \rangle$.

Moreover, this f is also more robust to ℓ_2 adversarial perturbations. By Fact 2.2, w.h.p. there are at most $O(k)$ non-zero coordinates in z , and thus there are at most $O(k)$ many $i \in [d]$ with $\mathbb{1}_{|\langle \mathbf{M}_i, x \rangle| \geq \frac{1}{2\sqrt{k}}} = 1$. Using this, one can derive that this high complexity model f has $1 - o(1)$ robust accuracy, against *any* adversarial perturbation of ℓ_2 radius $o(1/\sqrt{k})$. This is much larger than that of $o(1/\sqrt{d})$ for a linear classifier, and it is actually information theoretically optimal.

To sum up, higher-complexity models (such as those using ReLU) have the power to *zero out* low-magnitude signals to improve adversarial robustness, as illustrated in Figure 3.

²One may think that using for example degree-3 polynomial $\sum_i w_i^* \langle \mathbf{M}_i, x \rangle^3$ can reduce the level of noise, but notice due to the diversity in the value of z_i when $z_i \neq 0$, one must use something close to linear when $|z_i|$ is large. Applying Markov brothers’ inequality, one can show the low-degree polynomial must be close to a linear function.

³One concrete measure of “higher complexity” is that f cannot be well-approximated by any low (constant) degree polynomial.

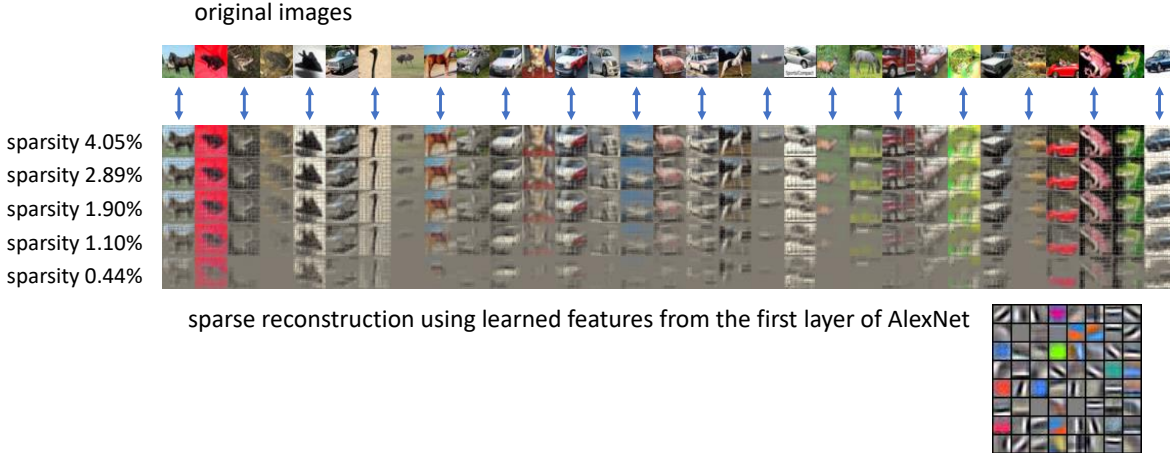


Figure 4: Reconstruct the original image using *sparse* linear combinations of the AlexNet’s features (adversarially trained). The average sparsity is only 4.05% or less. More experiments in Section 8.3.

Learning robust classifier using neural network. Motivated by the above discussions between linear vs. high-complexity models, our goal is to show that a two-layer neural networks can (after adversarial training) learn a robust function such as

$$f(x) \approx \sum_{i \in [d]} w_i^* [\text{ReLU}(\langle \mathbf{M}_i, x \rangle - b) - \text{ReLU}(-\langle \mathbf{M}_i, x \rangle - b)]$$

Here, ReLU is the ReLU activation function, and $b \approx \frac{1}{2\sqrt{k}}$. In this paper, we present a theorem stating that adversarial training of a (wlog. symmetric) two-layer neural network can *indeed* recover a neural network of this form. In other words, after adversarial training, the features learned by the hidden layer of a neural network can indeed form a *basis* of the input x where coefficients are *sparse*. We also present a theorem showing exactly why, clean training **will not** learn this robust function. We also verify experimentally that the features learned by the first layer of AlexNet (after adversarial training) indeed form a sparse basis of the images. See Figure 4.

4 Learner Network and Adversarial Training

In this paper we consider a simple, two layer (symmetric)⁴ neural network with ReLU activation.

$$f(x) = \sum_{i=1}^m a_i [\text{ReLU}(\langle w_i, x \rangle - b_i + \rho_i) - \text{ReLU}(-\langle w_i, x \rangle - b_i + \rho_i)]$$

In this way we have $f(x) = -f(-x)$. We refer to $w_i \in \mathbb{R}^d$ as the hidden weights (or features) for this network. Each $\rho_i \sim \mathcal{N}(0, \sigma_\rho^2)$ is a *smoothing* of the original ReLU, also known as the pre-activation noise. Equivalently, one can use the smoothed ReLU activation $\widetilde{\text{ReLU}}(x) = \mathbb{E}_\rho \text{ReLU}(x + \rho)$. In our paper, σ_ρ is smaller than b_i and much smaller than the typical value of $\langle w_i, x \rangle$. The main role of the pre-activation noise is simply to make the gradient of ReLU smooth, which simplifies our analysis for the sample complexity (to avoid over-fitting), as well as using certain algorithms to find the adversarial examples. In this paper, unless specially specified, we will use ρ to denote $(\rho_i)_{i \in [m]}$.

To simplify analysis, we fix $a_i = 1$ throughout the training. At initialization, we let $w_i^{(0)} \sim$

⁴We assume the neurons are symmetric (i.e., with $(w_i, -w_i)$ pairs) to simplify proofs.

$\mathcal{N}(0, \sigma_0^2 \mathbf{I})$ for $\sigma_0 = \frac{1}{\text{poly}(d)}$ and all $b_i = b^{(0)}$. We use $w_i^{(t)}$ to denote the hidden weights at time t , and use $f_t(w; x, \rho)$ to denote the network at iteration t

$$f_t(w; x, \rho) = \sum_{i=1}^m \left(\text{ReLU}(\langle w_i^{(t)}, x \rangle + \rho_i - b_i^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x \rangle + \rho_i - b_i^{(t)}) \right)$$

Given a training set $\mathcal{Z} = \{x_j, y_j\}_{j \in [N]}$ together with one sample of pre-activation noise $\rho^{(j)}$ for each (x_j, y_j) , we define

$$\begin{aligned} \mathbf{Loss}_t(w; x, y, \rho) &\stackrel{\text{def}}{=} \log(1 + e^{-y f_t(w; x, \rho)}) \\ \mathbf{Loss}_t(w) &\stackrel{\text{def}}{=} \mathbb{E}_{x, y=y(x), \rho} [\mathbf{Loss}_t(w; x, y, \rho)] & \widetilde{\mathbf{Loss}}_t(w) &\stackrel{\text{def}}{=} \frac{1}{N} \sum_{j \in [N]} [\mathbf{Loss}_t(w; x_j, y_j, \rho^{(j)})] \\ \mathbf{Obj}_t(w) &\stackrel{\text{def}}{=} \mathbf{Loss}_t(w) + \lambda \sum_{i \in [m]} \mathbf{Reg}(w_i) & \widetilde{\mathbf{Obj}}_t(w) &\stackrel{\text{def}}{=} \widetilde{\mathbf{Loss}}_t(w) + \lambda \sum_{i \in [m]} \mathbf{Reg}(w_i) \end{aligned}$$

Above, $\mathbf{Loss}_t(w; x, y, \rho)$ is the standard logistic loss, $\mathbf{Loss}_t(w)$ is the population risk and $\widetilde{\mathbf{Loss}}_t(w)$ is the empirical risk. We consider a strong, but *quite natural* regularizer to further avoid overfitting, given as $\mathbf{Reg}(w_i) \stackrel{\text{def}}{=} \left(\frac{\|w_i\|_2^2}{2} + \frac{\|w_i\|_3^3}{3} \right)$.⁵ We consider a fixed $\lambda = \frac{\log \log \log d}{d}$ for simplicity,⁶ although our result trivially extends to other (larger) values of λ .

Similar to Eq. (2.1), we defined the (clean, population) classification error at iteration t as

$$\mathcal{E}_t^c \stackrel{\text{def}}{=} \Pr_{x, y=y(x), \rho} [y \neq \text{sign}(f_t(w^{(t)}; x, \rho))] .$$

We denote

$$\ell'_t(w^{(t)}; x, y, \rho) \stackrel{\text{def}}{=} \frac{d}{ds} [\log(1 + e^s)] \Big|_{s=-y f_t(w^{(t)}; x, \rho)}$$

and observe $\mathbb{E}[\ell'_t(w^{(t)}; x, y, \rho)] \geq \Omega(\mathcal{E}_t^c)$.

We consider gradient descent training algorithm with step length $\eta > 0$, see Algorithm 1. (Our result extends to stochastic gradient descent at the expense of complicating notations.) We assume for simplicity the bias terms $b_1^{(t)} = \dots = b_m^{(t)}$ and they grow together:⁷ when near initialization, we manually increase the (negative) bias $b^{(t+1)} = b^{(t)} + \eta \mathfrak{B}$ where $\mathfrak{B} = \frac{c_b}{d}$ for some small constant $c_b > 0$ — this corresponds to the “lottery ticket winning” phase to be discussed later in Section 6.1; and whenever $b^{(t)}$ reaches $\frac{1}{k^{0.5001}}$ we set $\mathfrak{B} = 0$. We also choose pre-activation noise $\sigma_\rho^{(t)} = \frac{b^{(t)}}{\sqrt{\log d}} \cdot \Theta((\log \log \log d)^3)$ for $t \leq T_a = \frac{1}{\text{poly}(d)\eta}$, and $\sigma_\rho^{(t)} = \frac{b^{(t)}}{\log d} \cdot \Theta((\log \log \log d)^3)$ for $t > T_a$.

4.1 Adversarial training

Let us consider an arbitrary (norm-bounded) adversarial perturbation algorithm A .

Definition 4.1. *A perturbation algorithm A (a.k.a. attacker) maps the current network f (which includes hidden weights $\{w_i\}$, output weights $\{a_i\}$, bias $\{b_i\}$ and smoothing parameter σ_ρ), an input*

⁵Of course, $\frac{\|w_i\|_2^2}{2}$ is known as the weight decay regularizer, used practically everywhere for neural network training. The additional $\frac{\|w_i\|_3^3}{3}$ is an analog of the weight decay regularizer when combined with batch normalization [46].

⁶Throughout this paper, the purpose of any **log log log d factor** is to cancel out arbitrarily large constants so that we can present theorems and lemmas with simpler notations.

⁷More generally, if one also wants to train b_i then they have different values. Our analysis does extend to that case when the spike noise is large ($\sigma_x = \Omega(1)$), at the expense of complicating the proofs.

Algorithm 1 Clean Training using Gradient Descent

- 1: $b^{(0)} \leftarrow 0$ for every $i \in [m]$.
 - 2: **for** $t \in \{0, 1, 2, \dots, T_f - 1\}$ **do**
 - 3: For each $(x_j, y_j) \in \mathcal{Z}$, sample pre-activation noise $\rho^{(j)}$ i.i.d. $\sim \mathcal{N}(0, (\sigma_\rho^{(t)})^2 \mathbf{I}_{m \times m})$.
 - 4: Define empirical objective $\widetilde{\mathbf{Obj}}_t(w)$ at this iteration using $\{\rho^{(j)}\}_{j \in [N]}$.
 - 5: For each $i \in [m]$, update $w_i^{(t+1)} \leftarrow w_i^{(t)} - \eta \nabla_{w_i} \widetilde{\mathbf{Obj}}_t(w^{(t)})$
 - 6: Update $b^{(t+1)} \leftarrow b^{(t)} + \eta \mathfrak{B}$
 - 7: **end for**
-

x , a label y , and some internal random string r , to \mathbb{R}^d satisfying

$$\|A(f, x, y, r)\|_p \leq \tau .$$

for some ℓ_p norm. We say A is an ℓ_2 perturbation algorithm with radius τ if $p = 2$, and ℓ_∞ perturbation algorithm if $p = \infty$.

For simplicity, we assume A satisfies for fixed f, y, r , either $\|A(f, x, y, r)\|_p \leq \frac{1}{\text{poly}(d)}$, or $A(f, x, y, r)$ is a $\text{poly}(d)$ -Lipschitz continuous function in x .

One can verify that for our network, the fast gradient method (FGM) [37] satisfies the above properties. We formally state the adversarial training algorithm in Algorithm 2.

Algorithm 2 Adversarial Training Algorithm

- 1: Begin with a network f_{T_f} learned through clean training in Algorithm 1.
 - 2: **for** $t \in \{T_f, T_f + 1, \dots, T_f + T_g - 1\}$ **do**
 - 3: For every $(x_j, y_j) \in \mathcal{Z}$, perturb $x_j^{(adv)} \leftarrow x_j + A(f, x_j, y_j, r_j)$.
 - 4: For each $(x_j, y_j) \in \mathcal{Z}$, sample pre-activation noise $\rho^{(j)}$ i.i.d. $\sim \mathcal{N}(0, (\sigma_\rho^{(t)})^2 \mathbf{I}_{m \times m})$.
 - 5: Define empirical objective $\widetilde{\mathbf{Obj}}_t(w)$ at this iteration using $\{x_j^{(adv)}, y_j, \rho^{(j)}\}_{j \in [N]}$.
 - 6: For each $i \in [m]$, update $w_i^{(t+1)} \leftarrow w_i^{(t)} - \eta \nabla_{w_i} \widetilde{\mathbf{Obj}}_t(w^{(t)})$
 - 7: **end for**
-

The (true) robust classification error at iteration t , against arbitrary ℓ_p norm perturbation of radius τ , is given as (c.f. (2.2))

$$\mathcal{E}_t^r \stackrel{\text{def}}{=} \mathbf{Pr}_{x, y=y(x), \rho} [\exists \delta \in \mathbb{R}^d, \|\delta\|_p \leq \tau : \text{sign}(f_t(x + \delta)) \neq y]$$

In contrast, the (empirical) robust classification error against algorithm A is

$$\widehat{\mathcal{E}}_t^r \stackrel{\text{def}}{=} \mathbf{Pr}_{x, y=y(x), \rho, r} [\text{sign}(f_t(x + A(f_t, x, y, r))) \neq y]$$

Our main upper bound theorems apply to all adversarial training algorithms under Definition 4.1, via minimizing $\widehat{\mathcal{E}}^r$. To obtain true provable robustness for \mathcal{E}^r , as we shall see, one can for instance let A be the fast gradient method (FGM) [37], a widely used algorithm to find adversarial examples. In our language, FGM is simply given by:⁸

$$A(f, x, y) = \begin{cases} \arg \min_{\delta: \|\delta\|_p \leq \tau} \langle y \nabla_x f(x), \delta \rangle & \text{if } \|\nabla_x f(x)\|_q \geq \frac{1}{\text{poly}(d)}; \\ 0 & \text{otherwise.} \end{cases}$$

⁸Here, $\|\cdot\|_q$ is the dual norm of $\|\cdot\|_p$. In our case, due to the pre-activation noise, we define $\nabla_x f(x) = \nabla_x \mathbb{E}_\rho f(x; w, \rho)$. Also, we have zeroed out $A(f, x, y)$ when $\|\nabla_x f(x)\|_q$ is extremely small for the convenience of analysis, because otherwise $A(f, x, y)$ is not Lipschitz continuous at those points.

5 Statements of Main Results

5.1 Clean Training, Adversarial Training and ℓ_2 Robustness

For simplicity, in this subsection we sketch our main results for a special case $k = d^{0.36}$, although our theorems hold for a wide range of k in the full appendix.

Theorem 5.1 (clean training, sketched). *There exists an absolute constants $C, c > 0$ such that for every constant $c_0 \in (0, c]$, every d and m with $m = d^{1+c_0}$, given $N \geq \Omega(d^C)$ many training data, for every learning rate $\eta \in (0, \frac{1}{\Omega(d^C)}]$, the following holds with high probability: Define $T_{cc} := \Theta(\frac{d^{1.01}}{\eta})$.*

1. *Global feature learning: for every $t \geq T_{cc}$, (full version see Theorem C.2)*

$$\begin{aligned} \sum_{i \in [m]} \langle w_i^{(t)}, w_i^{(0)} \rangle^2 &= o(1) \times \sum_{i \in [m]} \|w_i^{(t)}\|_2^2 \cdot \|w_i^{(0)}\|_2^2 \quad \text{and} \\ \sum_{i, j \in [m]} \langle w_i^{(t)}, w_j^{(t)} \rangle^2 &= o(1) \times \left(\sum_{i \in [m]} \|w_i^{(t)}\|_2^2 \right)^2 . \end{aligned}$$

2. *Clean accuracy: for every $t \in [T_{cc}, d^{\log d}/\eta]$, (full version see Theorem D.1)*

$$\mathcal{E}_t^c = \Pr_{x, y=y(x), \rho} [y \neq \text{sign}(f_t(w^{(t)}; x, \rho))] \leq o(1) .$$

3. *Clean training is not robust: for every $t \in [T_{cc}, d^{\log d}/\eta]$, every $\tau \geq \frac{1}{k^{0.5+10c}}$, using perturbation*

$$\delta = -\tau \frac{y \mathbf{M} w^*}{\|\mathbf{M} w^*\|_2} \quad (\text{which does not depend on } f_t), \quad (\text{full version see Theorem E.1})$$

$$\mathcal{E}_t^r \geq \Pr_{x, y, \rho} [f_t(w^{(t)}; x + \delta, \rho) \neq y] = 1 - o(1) .$$

Why clean training is non-robust? Theorem 5.1 indicates that clean training has good clean accuracy but terrible robust accuracy. Such terrible robust accuracy holds even when a super-polynomially many iterations and infinitely many training examples are used to train the neural network. In the next theorem, we give a precise characterization of what are hidden weights $\{w_i\}$ are after clean training, and why they are not robust. More intuitions regarding how the “non-robust portions” of these features are actually formed during clean training can be found in Section 6.2.

Theorem 5.2 (clean training features, sketched). *For every neuron $i \in [m]$, there is a subset \mathcal{N}_i of size $|\mathcal{N}_i| = O(1)$ such that, for every $t \in [T_{cc}, d^{\log d}/\eta]$,*

$$w_i^{(t)} = \sum_{j \in \mathcal{N}_i} \alpha_{i,j} w_j^* \mathbf{M}_j + \sum_{j \notin \mathcal{N}_i} \beta_{i,j} w_j^* \mathbf{M}_j \quad (\text{full statement see Theorem C.2})$$

where each $\alpha_{i,j} \in [\frac{1}{d^c}, d^c]$ and each $|\beta_{i,j}| \leq \frac{k}{d^{1-c}}$ for some small constant $c \in [0, 0.001]$. Moreover,

$$\frac{1}{md} \sum_{i \in [m], j \in [d]} \beta_{i,j} \in \left[\frac{1}{d^c} \times \frac{k}{d}, d^c \times \frac{k}{d} \right] . \quad (\text{full statement see Lemma E.2})$$

Hence, Theorem 5.2 shows that instead of learning the “robust features” $\{\mathbf{M}_j\}_{j \in [d]}$, intuitively, ignoring the small d^c factors, imagining as if $|\mathcal{N}_i| = 1$, and assuming for simplicity all the $\beta_{i,j}$ ’s are of similar (positive) magnitude, then, clean training will learn for each neuron:

$$w_i^{(t)} \approx \Theta(1) \mathbf{M}_j + \sum_{j' \neq j} \left[\Theta \left(\frac{k}{d} \right) w_{j'}^* \mathbf{M}_{j'} \right] \quad (5.1)$$

Feature purification: mathematical reasoning. Eq. (5.1) says that, after clean training, the neural network will be able to learn a big portion of the robust feature: $\Theta(1) \mathbf{M}_j$. But, on the

other hand, it will also learn a *small “dense mixture”* $v = \sum_{j' \neq j} \left[\Theta\left(\frac{k}{d}\right) w_j^* \mathbf{M}_{j'} \right]$. In our sparse coding model, each x is of form $x = \mathbf{M}z + \xi$, where z is a sparse vector. Thus, such “dense mixture” v has *low correlation with almost all inputs x from the original distribution*. Therefore, these “dense mixtures” will have negligible effect for clean training accuracy. However, as shown in the proof of Theorem 5.1, such dense mixture is extremely vulnerable to **small but dense adversarial perturbations** of the input, making the model non-robust. We point out that, such “dense adversarial perturbation” directions do not exist in the original (clean) data.⁹ Thus, one has to rely on adversarial training to remove such “dense mixtures” to make the model robust. This is the main spirit of the principle of *feature purification*. We illustrate this in Figure 5.

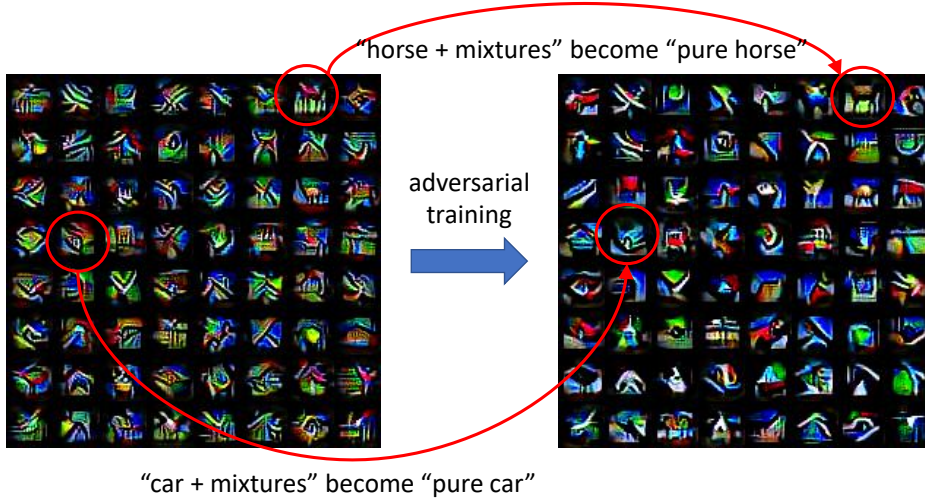


Figure 5: Experiments support our theory that adversarial training do purify “dense mixtures”, through for instance visualizing some deep layer features of ResNet on CIFAR-10 data. More experiments in Section 8.2.

Where does “dense mixture” come from? We also provide intuitions on how these “dense mixtures” are generated during clean training, see Section 6.2. At a high level, at each iteration, the gradient ∇Obj will bias towards the direction that is positively correlated with the labeling function $y = \text{sign}(\langle w^*, z \rangle)$, and since $x = \mathbf{M}z + \xi$ in our model, such direction should be $\mathbf{M}w^* = \sum_j w_j^* \mathbf{M}_j$.

Recall we have argued in Section 3, when the noise level $\sigma_x \geq \Omega(1)$ is large, this dense direction can not be used to classify y directly. Yet, our critical observation is that, especially for well-trained neural network which can “de-noise” ξ , this dense direction is actually *locally* positively correlated with the labeling function y , and thus can be accumulated in the hidden weights during the course of a **local training algorithm** such as gradient descent.¹⁰

Theorem 5.3 (adversarial training, sketched). *In the same setting as Theorem 5.1, suppose A is an ℓ_2 perturbation algorithm with radius $\tau \leq \frac{1}{k^{0.5+c}}$. Suppose we run clean training for $T_f \geq T_{cc}$ iterations followed with adversarial training for $T_g = \Theta\left(\frac{k^{2+c}}{\eta}\right)$ iterations. The following holds with high probability.*

1. Empirical robust accuracy: $\widehat{\mathcal{E}}_T = o(1)$ for $T = T_f + T_g$. (full statement see Theorem F.1)

⁹One can try to add these “dense mixtures” directly to the training data set, which we conjecture to be similar to the approach in [45]

¹⁰In contrast, if a linear classifier is used, it cannot de-noise ξ and thus such dense direction shall not be accumulated; however, no linear classifier can achieve good clean accuracy when $\sigma_x \geq \Omega(1)$ is large.

2. *Provable robust accuracy*: when A is the fast gradient method (FGM), we also have $\mathcal{E}_T^r = o(1)$.
 (full statement see Corollary F.2)

3. *Feature purification (local)*: for every $t \in [T_f, T_f + T_g - 1]$,

$$\sum_{i \in [m]} \|w_i^{(T_f)} - w_i^{(t)}\|_2^2 = o(1) \times \sum_{i \in [m]} \|w_i^{(T_f)}\|_2^2$$

(see (F.12) in the proof of Theorem F.1)

As we illustrate in Figure 6, one of the main goals of adversarial training is to remove “dense mixtures” to make the network more robust. Before adversarial training, the adversarial perturbations are “dense” in the basis of $\{\mathbf{M}_j\}_{j \in [d]}$. After adversarial training the adversarial perturbation becomes “sparse” and more aligned with inputs from the original data set.

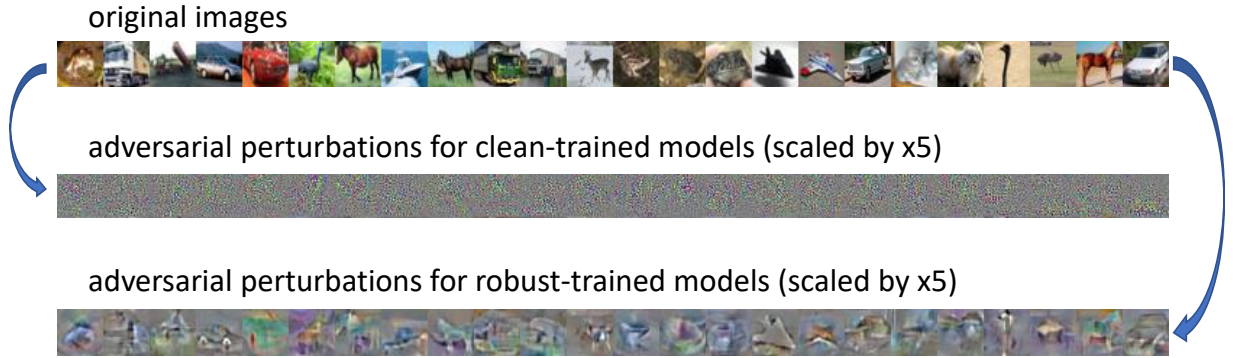


Figure 6: Adversarial examples before and after adversarial training; ResNet-32, CIFAR-10 data set. For clean-trained models, adversarial perturbations are “dense.” After robust training, the “dense mixtures” are removed and adversarial perturbations are more aligned with actual images. More experiments in Section 8.3.

5.2 ℓ_∞ Robustness and Lower Bound for Low-Complexity Models

We also have the following theorem (stated in special case for simplicity) for ℓ_∞ robustness.

Theorem 5.4 (ℓ_∞ adversarial training, sketched). *Suppose $\|\mathbf{M}\|_\infty, \|\mathbf{M}\|_1 = d^{o(1)}$. There exists constant $c_1 \in (0, c_0)$ such that, in the same setting as Theorem 5.3, except now for any $k \in [d^{c_1}, d^{0.399}]$, and A is an ℓ_∞ -perturbation algorithm with radius $\tau = \frac{1}{k^{1.75+2c_0}}$. Then, the same Theorem 5.3 and Theorem 5.1 still hold and imply*

- *clean training is not robust against ℓ_∞ perturbation with radius $\frac{1}{k^{2-c_1}}$;*
- *adversarial training is robust against any ℓ_∞ -perturbation of radius $\tau = \frac{1}{k^{1.75+2c_0}}$.*

This gives a gap because c_0, c_1 can be made arbitrarily small.

(full statements see Theorem E.1 and Theorem F.4)

We also show a lower bound that no low-degree polynomial, nor even the corresponding neural tangent kernel (NTK), can robustly learn the concept class. Recall

Definition 5.5. *The feature mapping of the neural tangent kernel for our two-layer network f is*

$$\Phi(x) = \left(x \mathbb{E}_{\rho_i} \left(\mathbf{1}_{\langle w_i, x \rangle + \rho_i \geq b_i} - \mathbf{1}_{-\langle w_i, x \rangle + \rho_i \geq b_i} \right) \right)_{i=1}^m$$

Therefore, given weights $\{v_i\}_{i \in [m]}$, the NTK function $p(x)$ is given as

$$p(x) = \sum_{i \in [m]} \langle x, v_i \rangle \mathbb{E}_{\rho_i \sim \mathcal{N}(0, \sigma_\rho^2)} (\mathbb{1}_{\langle w_i, x \rangle + \rho_i \geq b_i} - \mathbb{1}_{-\langle w_i, x \rangle + \rho_i \geq b_i})$$

In this paper we consider a wide range of NTK parameters: wlog. each $w_i \sim \mathcal{N}(0, \mathbf{I})$, $\rho_i \sim \mathcal{N}(0, \sigma_\rho^2)$ for arbitrary $\sigma_\rho \in [0, d^{o(1)}]$ and $|b_i| = d^{o(1)}$.

Our lower bound holds *even* for a most simple case when $\mathbf{M} = \mathbf{I}$ and $\sigma_x = 0$, so the original concept class is linearly separable. We prove the following:

Theorem 5.6 (lower bound). *For every constant $C > 1$, suppose $m \leq d^C$, then there is a constant $c > 0$ such that when $k = \frac{1}{d^c}$, considering ℓ_∞ perturbation with radius $\tau = \frac{1}{k^{100}}$, we have w.h.p. over the choice of w_i , for every $p(x)$ in the above definition,*

$$\mathcal{E}^r(p) \geq \frac{1 - o(1)}{2}. \quad (\text{full statement see Theorem G.1})$$

(In contrast, Theorem 5.4 says adversarial training of neural network gives robust radius $\tau = \frac{1}{k^{1.76}}$.)

Since a poly-sized NTK kernel is known to be powerful enough to incorporate any low complexity functions (such as constant-degree polynomials) [6], we have the following corollary.

Corollary 5.7 (lower bound). *In the same setting as Theorem 5.6, if $q(x)$ is a constant degree polynomial, then we also have $\mathcal{E}^r(q) \geq \frac{1 - o(1)}{2}$.*

6 Overview of the Training Process

In this section, we present an overview of the proof for the training process, using gradient descent starting from random initialization. The complete proof is deferred to Appendix.

6.1 Wining Lottery Tickets Near Random Initialization

Our proof begins by showing how the features in the neural network are emerged from the random initialization. In this phase, the loss function is not sufficiently minimized yet, so the classification accuracy remains around 50%. However, we observe that in this phase, the gradient descent process will already drive the neural network to learn a rich set of interesting features out of the random initialization. We call this process “lottery ticket winning” near random initialization, which is related to the study of [31].

Remark. This “lottery ticket winning” process is ***fundamentally different from the neural tangent kernel analysis*** (e.g. [4, 7, 8, 11, 12, 23–26, 35, 42, 47, 54, 58, 100, 109]). In this phase, although the loss is not sufficiently minimized, the activation patterns of the ReLU’s will change *dramatically*, so that they can have little correlations with the random initialization. Yet, we develop a new theoretical technique that allows us to control the change of the weights of the neurons, as we summarize below.

We derive the following property at random initialization. At iteration $t = 0$, the hidden weights are initialized as $w_i^{(0)} \sim \mathcal{N}(0, \sigma_0^2 \mathbf{I}_{d \times d})$. Using standard properties of Gaussians, we show the following critical property: as long as $m \geq d^{1.01}$, there exists small constants $c_3 > c_4 > 0$ such that

- (i) For most of the neurons $i \in [m]$, $\max_{j \in [d]} \{\langle \mathbf{M}_j, w_i^{(0)} \rangle^2\} \leq 2\sigma_0^2 \log d$.
- (ii) For at most $\frac{1}{d^{c_4}}$ fraction of of the neurons $i \in [m]$, there is a dimension $j \in [d]$ with $\langle \mathbf{M}_j, w_i^{(0)} \rangle^2 \geq 2.01\sigma_0^2 \log d$.

- (iii) For at least $\frac{1}{d^{\epsilon_3}}$ fraction of the neurons $i \in [m]$, there is one and only one $j \in [d]$ such that $\langle \mathbf{M}_j, w_i^{(0)} \rangle^2 \geq 2.02\sigma_0^2 \log d$, and all the other $j' \in [d]$ satisfies $\langle \mathbf{M}_{j'}, w_i^{(0)} \rangle^2 \leq 2.01\sigma_0^2 \log d$.

In other words, even with *very mild over-parameterization* $m \geq d^{1.01}$, by the property of random gaussian initialization, there will be some “potentially lucky neurons” in (ii), where the maximum correlation to one of the features \mathbf{M}_j is **slightly higher than usual**. Moreover, there will be some “lucky neurons” in (iii), where such “slightly higher correlation” only appears with one and only one of the target features \mathbf{M}_j .

In our proof, we denote the set of the neurons in (iii) whose correlation with \mathbf{M}_j is slightly higher than usual as the set $\mathcal{S}_{j,sure}^{(0)}$, and denote those in (ii) as $\mathcal{S}_{j,pot}^{(0)}$. We will identify the following process during the training, as given in Theorem C.1:

Lottery tickets winning process

For every $j \in [d]$, at every iteration t , if $i \in \mathcal{S}_{j,sure}^{(0)}$, then $\langle \mathbf{M}_j, w_i^{(t)} \rangle^2$ will grow faster than $\langle \mathbf{M}_{j'}, w_i^{(t)} \rangle^2$ for every t , until $\langle \mathbf{M}_j, w_i^{(t)} \rangle^2$ becomes sufficiently larger than all the other $\langle \mathbf{M}_{j'}, w_i^{(t)} \rangle^2$.

In other words, if neuron i *wins the lottery ticket* at random initialization, then eventually, it will deviate from random initialization and grow to a feature that is more close to (a scaling of) \mathbf{M}_j . Our other main observation is that if we slightly over-parameterize the network with $m \geq d^{1.001}$, then for each $j \in [d]$, $|\mathcal{S}_{j,sure}^{(0)}| \geq 1$ and $|\mathcal{S}_{j,pot}^{(0)}| \leq d^{0.01}$. Or in words, each “lottery ticket” \mathbf{M}_j will be won at least once, but at most $d^{0.01}$ times. We also illustrate the lottery ticket winning process experimentally in Figure 7.

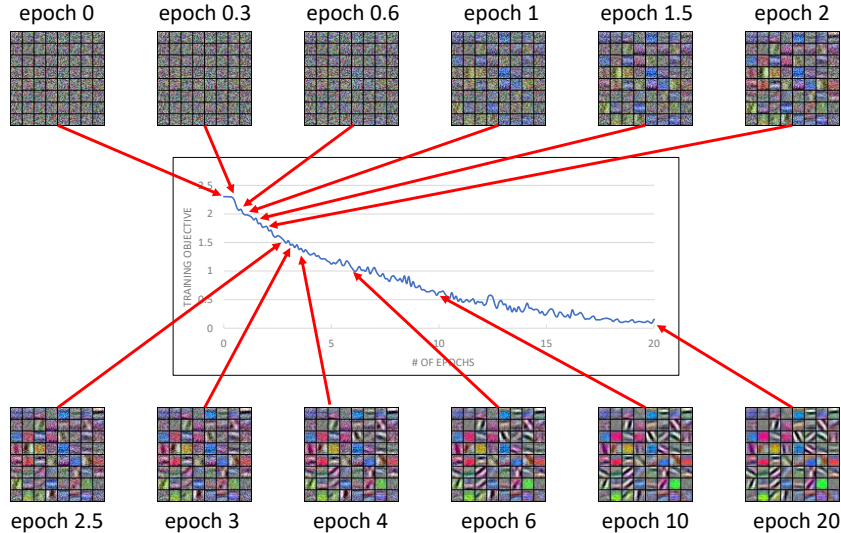


Figure 7: Lottery tickets winning process, AlexNet, CIFAR-10 data set.

6.2 The Formation of “Dense Mixtures” During Training

The next phase of our analysis begins when all the neurons already won their lottery tickets near random initialization. After that, the loss starts to decrease significantly, so the (clean) classification error starts to drop. We shall prove that in this phase, gradient descent will also accumulate, in each neuron, a small “dense mixture” that is extremely vulnerable to small but adversarial perturbations.

To show this, we maintain the following critical property as given in Theorem C.2:

If a neuron i wins the lottery ticket for feature \mathbf{M}_j near random initialization, then it will keep this “lottery ticket” throughout the training.

Or in math words, for each neuron i , after $\langle \mathbf{M}_j, w_i^{(t)} \rangle^2$ becomes sufficiently larger than all the other $\langle \mathbf{M}_{j'}, w_i^{(t)} \rangle^2$ at the first stage, it will stay much larger than other $\langle \mathbf{M}_{j'}, w_i^{(t)} \rangle^2$ for the remaining of the training process. To prove this, we introduce a careful coupling between the (directional) gradient of the neuron, and the (directional) Lipschitz continuity of the network f_t , this is given in Section C.4.2.

The vulnerable “dense mixtures”. The most critical observation in this phase is the formation of “dense mixtures”, where we show that even for the “lucky neuron” that wins the lottery ticket, the hidden weight of this neuron will look like (see Lemma E.2)

$$w_i \approx \alpha_t \left(\mathbf{M}_j + \Theta \left(\frac{k}{d} \right) \sum_{j' \neq j} w_{j'}^* \mathbf{M}_{j'} \right) \quad (6.1)$$

In other words, up to scaling, these neurons will look like $w_i \approx \mathbf{M}_j + v_i$, where v_i is a “dense mixture” $v_i = \Theta \left(\frac{k}{d} \right) \sum_{j' \neq j} w_{j'}^* \mathbf{M}_{j'}$.

The key observation is that v_i is *small and “dense”*, in the sense that it is a mixture of all the other features $\{\mathbf{M}_{j'}\}_{j' \in [d]}$, but each of the feature has a much smaller contribution comparing to the leading term \mathbf{M}_j . Recall each input $x = \mathbf{M}z + \xi$ so *with high probability*:

$$|\langle v_i, x \rangle| \leq \tilde{O} \left(\frac{k}{d} \|x\|_2 \right) \quad (6.2)$$

In the “sparse coding” regime, this value is even smaller than $\frac{1}{k}$ when $k \leq \sqrt{d}$. Thus, this “dense mixture” will not be correlated with any particular natural input data, and thus the existence of these mixtures will have negligible contribution to the output of f_t .

However, if we perturb input x along the “dense directions” $\delta \propto \sum_{j' \in [d]} \mathbf{M}_{j'}$, we can observe that:

$$|\langle v_i, \delta \rangle| = \Omega \left(\frac{k}{\sqrt{d}} \|\delta\|_2 \right)$$

Comparing this with Eq (6.2), such “dense perturbation” can change the output of the neural network f_t by *a lot*, using a small δ whose norm is much smaller than that of x . Thus, at this phase, even when the network has a good clean accuracy, it is still non-robust to all these *small yet dense adversarial perturbations*. Moreover, this perturbation direction is “universal”, in the sense that it does not depend on the randomness of the model at initialization, or the randomness we use during the training. This explains transfer attacks in practice: that is, the adversarial perturbation found in one model can also attack other models that are independently trained.

Feature purification. Since Eq. (6.2) suggests most of the original inputs have negligible correlations with each dense mixture, during clean training, gradient descent will have no incentive to remove those mixtures. Thus, we have to rely on adversarial training to *purify* those “dense mixtures” by introducing “adversarial examples”. Those examples have correlation with v_i ’s that are higher than usual. As we prove in Theorem 5.1 and illustrate in Figure 1: such “purifications”, albeit imposing only a small change to each neuron, will greatly improve the robustness of the neural network.

The formation of the “dense mixtures”. To further help the readers understand how those “dense mixtures” are formed, we sketch the proof of Theorem E.1 (which shows why clean training is provably non-robust). The main observation is that *when the “dense mixtures” are small*, the

negative gradient of the (say, population) loss with respect to each neuron w_i is approximately given by:

$$-\nabla_{w_i} \mathbf{Loss}(w^{(t)}) \approx \mathbb{E}_{x,y=y(x),\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) (\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}) \mathbf{M}z \right]$$

As a result,

$$-\langle \nabla_{w_i} \mathbf{Loss}(w^{(t)}), \mathbf{M}w^* \rangle \approx \mathbb{E}_{x,y=y(x),\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) (\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}) \langle w^*, z \rangle \right]$$

Since $y = \text{sign}(\langle w^*, z \rangle)$, we have $y \langle w^*, z \rangle \geq 0$, $\ell' \geq 0$ and the indicators are always non-negative. Therefore, $-\langle \nabla_{w_i}, \mathbf{M}w^* \rangle$ is quite positive, and during clean training, it will naturally accumulate in each neuron and thus result in non-trivial correlation with $\mathbf{M}w^*$.

We notice that this is indeed a special property of gradient descent. Consider the case when $\sigma_x^2 = \Omega(1)$, so $x = \mathbf{M}z + \xi$ with $\|\xi\|_2 = \Omega(1) = \Omega(\|\mathbf{M}z\|_2)$. With high probability, a linear classifier using direction $\mathbf{M}w^*$ **can not** be used to classify x correctly. Yet, this direction $\mathbf{M}w^*$ is still locally positively correlated with the labeling function y , **especially for well-trained, well-generalizing neural networks when the ξ can be “de-noised”**. (Stochastic) gradient descent, as a local update algorithm, only exams the local correlation between the update direction and the labeling function, and it *does not exam* whether this direction can be used in the final result. Thus, this “dense direction” $\mathbf{M}w^*$ will be accumulated step by step, leading to a “non-robust” part of the each of the features during clean training. *In fact, even if we use $w_i = \mathbf{M}_i$ as initialization as opposed to random initialization, continuing clean training will still accumulate these small but dense mixtures*. See Figure 8.

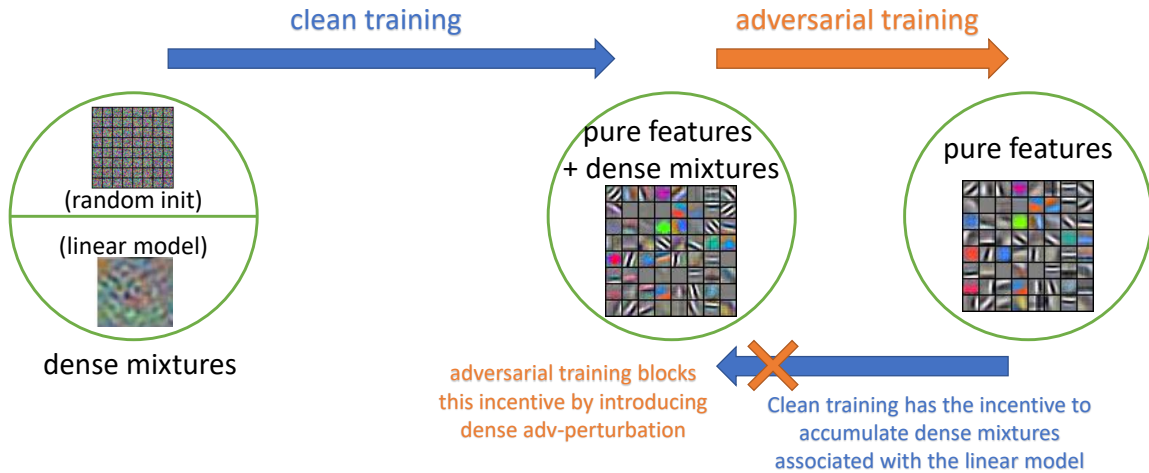


Figure 8: Overall summary of clean training, adversarial training, in the language of pure vs dense features. (Experiment based on AlexNet on CIFAR-10 dataset.)

7 Conclusion

In this paper, we made a first step towards understanding how, in principle, the features in a neural network are learned during the training process, and why after clean training, these *provably well-generalizing* features are still *provably non-robust*. Our main conclusion is that during the clean training process using (stochastic) gradient descent, the neural network will accumulate, in all features, some “dense mixture directions” that have low correlations with any natural input,

but are extremely vulnerable to (dense) adversarial perturbations. During adversarial training, such “dense mixtures” are purified to make the model more robust. Our results suggest that the non-robustness of clean training is mainly due to two reasons:

1. the inductive bias of gradient descent, and
2. the “sparse coding” structure of the data.

Both reasons are necessary in some sense. First, a robust model is also a global minimizer of the clean training objective; our theorem shows that even with proper regularization and infinite training examples to avoid over-fitting, gradient descent still has *inductive bias* towards finding a non-robust model instead of the robust one. Second, it is easy to come up with data sets— such as linear-classifier labels over well-conditioned “mixture of Gaussians” like inputs— where clean training using gradient descent directly achieves the best robust accuracy. Thus, to understand the non-robustness of neural networks, we more or less *have to* take into account the gradient descent algorithm and the structure of the inputs.

Indeed, our step is still very *provisional*. We immediately see a plethora of extensions from our work. First of all, natural images have much richer structures than sparsity; hence, those “non-robust mixtures” accumulated by clean training might also carry structural properties other than density. Moreover, we would like to extend our work to the clean and robust training of multi-layer neural networks, possibly with “hierarchical feature purification” processes. Indeed, understanding the whole picture of adversarial examples and adversarial training might require a complete understanding of deep learning.

8 Experiment Details

We perform experiments using three standard architectures, AlexNet, ResNet-14, and ResNet-32 with basic blocks, and tested on the CIFAR-10 dataset.¹¹

We discover that learning rate 0.1 is good for ResNet and 0.05 is good for AlexNet; while weight decay 0.0001 is good for ResNet and 0.0005 is good for AlexNet (this was also recommended by the git repo authors). We use standard SGD with 0.9 momentum as the training algorithm. During adversarial training, we have implemented:

- The empirical ℓ_2 perturbation algorithm (i.e., attacker) suggested by [78]. We choose two sets of parameters so that the adversarial training task is somewhat non-trivial, where the testing (empirical) accuracy is 40 ~ 50%. We denote the attackers by $\ell_2(4.6, 0.25)$ and $\ell_2(2.3, 0.12)$.¹²
- The empirical ℓ_∞ perturbation algorithm (i.e., attacker) [61], with ℓ_∞ radius 4/255 and 8/255, together with 7 steps of PGD attack. We call them $\ell_\infty(4/255)$ and $\ell_\infty(8/255)$ respectively.

We mostly focus on the $\ell_2(4.6, 0.25)$ attacker in this paper, but shall compare them in Section 8.4.

8.1 Feature Visualization of Deeper Layers

Visualizing the first layer of any trained architecture is trivial: for instance, for AlexNet, the weight tensor of the first layer is $3 \times 11 \times 11$ which gives the RGB color of 11×11 patches (and this was

¹¹We used the implementations from <https://github.com/bearpaw/pytorch-classification>. We used their default random crop and random flip as data augmentation.

¹²We use their SMOOTHADVPGD attacker with following parameters. We use $\sigma = 0.25$ which is the random Gaussian perturbation added to the input; use MTRAIN = 2 which is the number of Gaussian noise samples used per training sample, use $T_{\text{PGD}} = 4$ which is the number of PGD attack steps, and use $\varepsilon = 4.6$ which is the ℓ_2 radius for the PGD attacker. We also follow their instruction to perform 10 warmup epochs to gradually increase ε from zero to 4.6. We call this $\ell_2(4.6, 0.25)$. We have also implemented $\ell_2(2.3, 0.12)$.

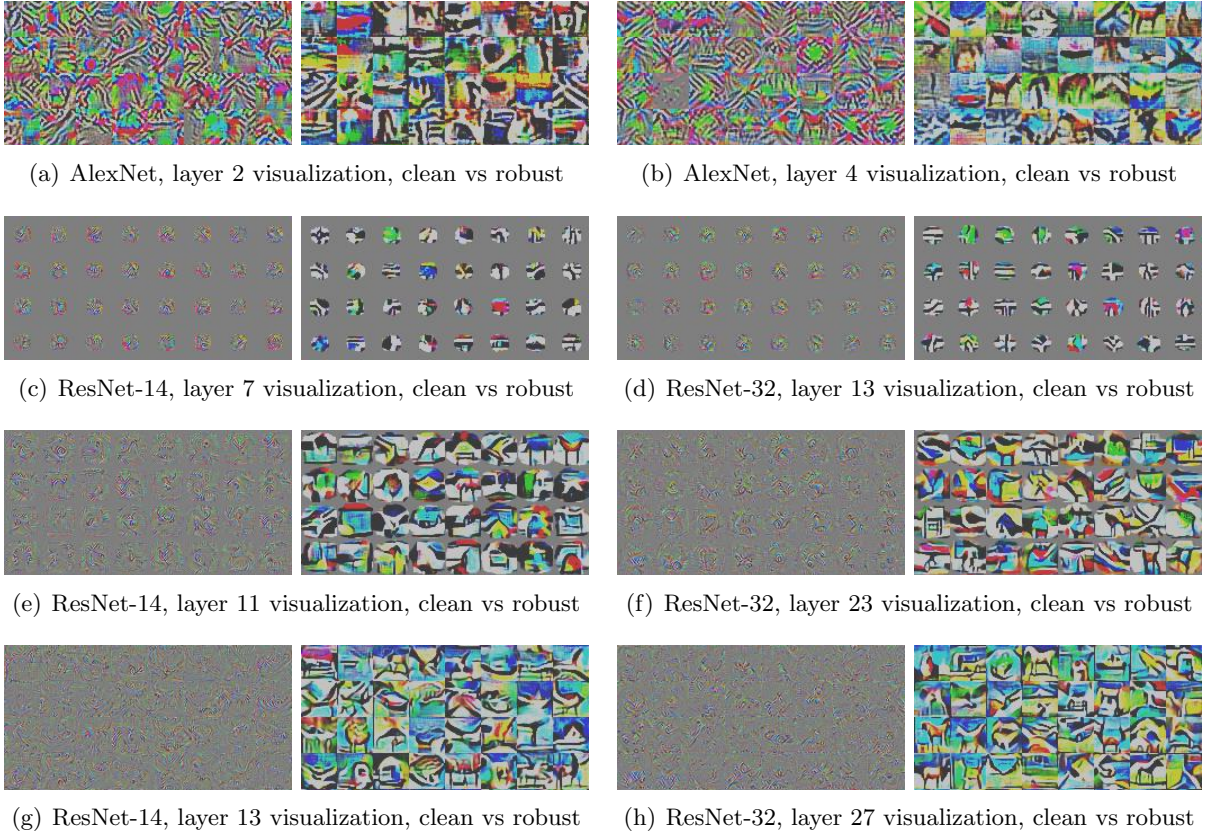


Figure 9: Visualization of deep features on cleanly-trained vs. robustly-trained models.

Take-away message: features from robustly-trained models are more “pure” and closer to the real image space. We hope that our work can be extended to a “hierarchical feature purification” for multi-layer neural networks, using the recent advance in the theory of training deep neural networks efficiently and beyond NTKs [3, 5]

precisely what we presented in Figure 1). However, such visualization can be less meaningful for ResNet because the tensors are of dimension $3 \times 3 \times 3$.

Visualizing the features presented by *deeper* convolutional layers is an active research area, dating back at least to [28]. Perhaps the most naive approach is to start from a randomly initialize image (of size $3 \times 32 \times 32$), then take a specific neuron n at some layer, and repeatedly take its gradient with respect to the image. If we keep adding this gradient to the input image, then ideally this gives us the image which “excites” n the most. Unfortunately, it is a common knowledge in this area that this naive approach does not lead to “visually meaningful” images as we go (even slightly) deeper into a network (see e.g. the left column of Figure 9).

In existing literature, researchers have tried to various ways to resolve this issue (see e.g. an extensive survey by Olah et al. [72] and the references therein). At a high level, some penalizes the image to remove high-frequency noise [62, 66, 68, 75, 94]; some searches for images that can still excite the given neuron after jittering [66, 67, 75, 94]; and some searches only in the space of “real data” by building a model (e.g. using GAN) to capture the prior [66, 69, 70].

We observe that, if the model is robustly trained, then one can directly apply the naive approach to visualize features of the deep layers, and the resulting images can be “visually very meaningful.”

See Figure 9.¹³ Our theory in fact explains this phenomenon: the “dense mixtures” accumulated during clean training is extremely harmful to the visualization effect, since they are “visually meaningless.” After robust training, such “dense mixtures” are removed so the visualization starts to align with human concepts.

Throughout this section we stick to this naive approach for visualizing features of deep layers.¹⁴

8.2 Feature Purification at Deeper Layers

Since our theoretical result shows the “feature purification” principle of a single layer, we perform the following experiment to verify this in practice, to **study the effect of “feature purification” in each layer individually**. For each of architecture $A \in \{\text{ResNet-14}, \text{ResNet-32}\}$, we select some convolutional layer ℓ . For each pair (A, ℓ) , we

- perform T epochs of adversarial training;
- freeze the weights of layers $1, 2, \dots, \ell - 1$ and re-randomize weights of layers $\ell, \ell + 1, \dots$;
- perform T epochs of clean training (by training weights of layers $\ell, \ell + 1, \dots$);
- perform T epochs of adversarial training (by training weights of layers $\ell, \ell + 1, \dots$).

Then, we visualize the features on layer ℓ

- at the end of epoch T (indicating layer ℓ is random),
- at the end of epoch $2T$ (indicating layer ℓ is clean trained), and
- at the end of epoch $3T$ (indicating layer ℓ is adversarially trained).

We present our findings in Figure 10 and Figure 11 respectively for ResNet-14 and ResNet-32.

We also point out that with this training schedule, even when the first $(\ell - 1)$ -layers are fixed to “robust features” and only the $\ell, \ell + 1, \dots$ layers are trained, after clean training, the robust accuracy is still 0%.

¹³This should not be surprising given that the “jittering” technique is known to work in practice on visualizing clean models.

¹⁴Specifically, starting from a random input image, we take 2000 gradient steps to update the image so that the given neuron at a specific layer is excited the most. To make the result image even prettier, we have slightly regularized this process by: (1) adding a weight decay factor to incentivize the image to go to RGB (128,128,128); (2) using the sign of the gradient instead of the gradient itself (similar to the ℓ_∞ attacker [61]).

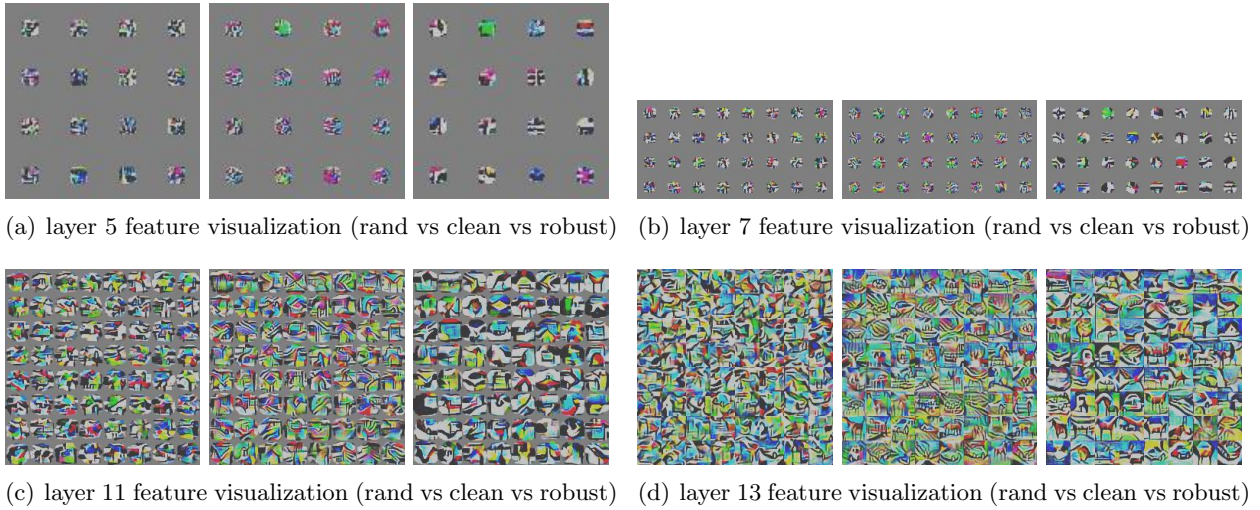


Figure 10: Visualization of the ℓ -th layer features from ResNet-14 for $\ell \in \{5, 7, 11, 13\}$.

Take-away message: feature purification happens even at deep layers of a neural network.

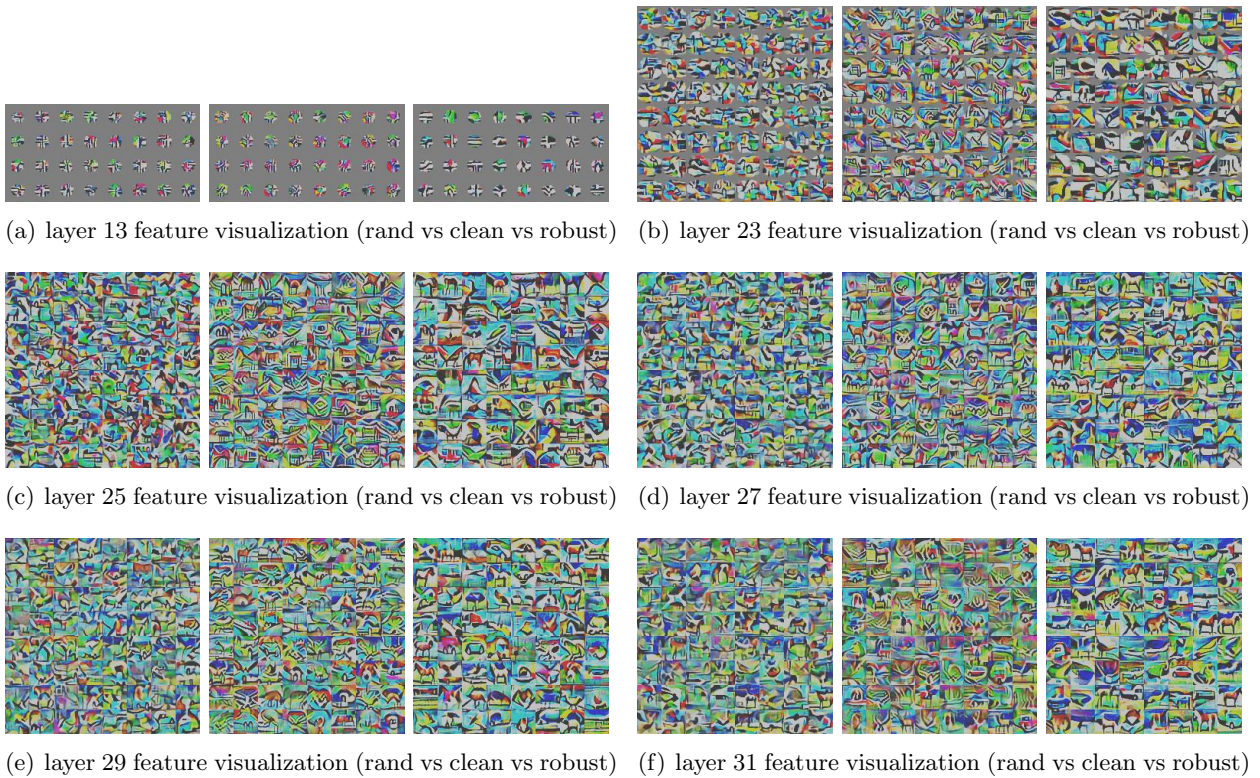


Figure 11: Visualization of the ℓ -th layer features from ResNet-32 for $\ell \in \{13, 23, 25, 27, 29, 31\}$.

For each case of ℓ , the $\ell - 1$ layers are frozen at some pre-trained robust weights, and only layers deeper than or equal to ℓ are trained. “rand” refers to layers $\geq \ell$ are randomly initialized, “clean” refers to layers $\geq \ell$ are cleanly trained, and “robust” refers to layers $\geq \ell$ are adversarially trained.

Take-away message: feature purification happens even at deep layers of a neural network.

8.3 Sparse Reconstruction of Input Data and of Adversarial Perturbation

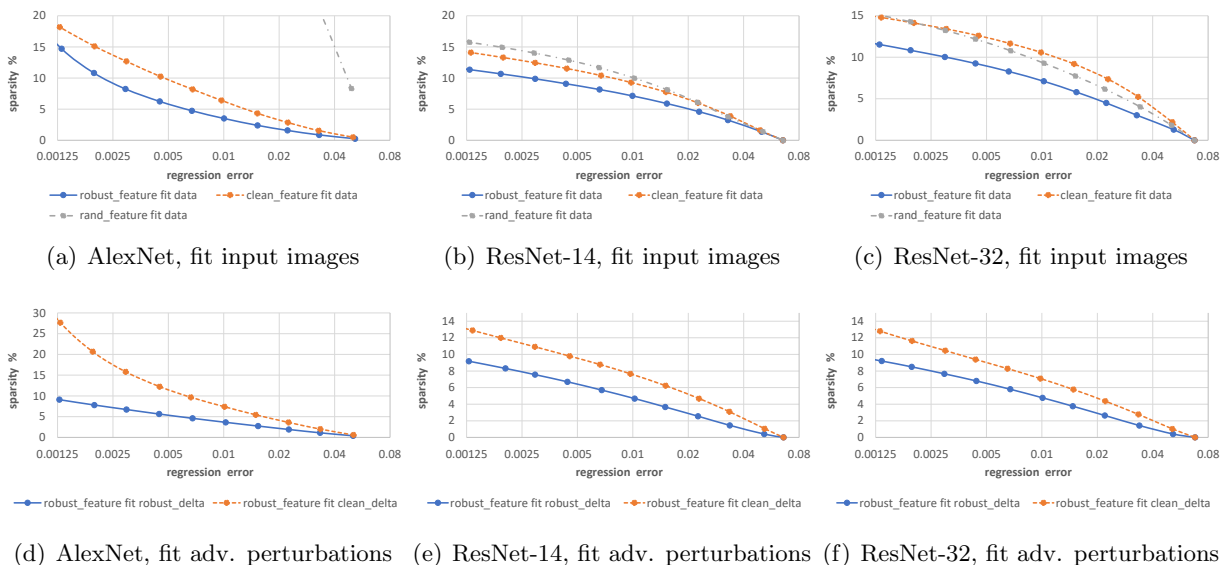


Figure 12: Sparse reconstruction of input images and of adversarial perturbations.

Take-away message for the first row: robust features can be used to reconstruct input images with better sparsity, suggesting that robust features are more pure.

Take-away message for the second row: adversarial perturbations from a clean model are more “dense” comparing to those from a robust model (and in fact robust model’s adversarial perturbations are (much) closer to real input images, see Figure 6).

Recall in Figure 4, we have shown that the input images can be sparsely reconstructed from the robust features. To better quantify this observation, we compare how sparse the input images can be reconstructed from (1) random features, (2) clean features, and (3) robust features. For each of the tasks, we use Lasso to reconstruct the 100 images, and sweep over all possible weights of the ℓ_1 regularizer (which controls how sparse the reconstruction is).¹⁵ The results are presented in the first row of Figure 12. As one can see, using clean features one can also sparsely reconstruct the input, but using robust features the reconstruction can be *even sparser*. This, to some extent, supports our theory that robust features are more “pure” than clean features.

Perhaps *more importantly*, our theory suggests that for clean-trained models, adversarial perturbations (we refer to as `clean_delta`) have “dense mixtures”; while for robust-trained models, adversarial perturbations (we refer to as `robust_delta`) are “more pure.” This was visually illustrated in Figure 6. Now, to better quantify this observation, we compare how sparse `clean_delta` and `robust_delta` can be reconstructed from robust features. See the second row of Figure 12.¹⁶ From this experiment, we confirm that in practice, adversarial perturbations on robust models are more “pure” and closer to real input images.

¹⁵Recall the Lasso objective is $\min_y \|Wy - x\|_2^2 + \lambda \|y\|_1$, where it uses Wy to reconstruct given input x , and λ is the weight of the regularizer to control how sparse y is. The convolutional version of Lasso is analogous: the matrix W becomes the “transpose” of the weight of the convolutional layer, which is for instance implemented as `nn.ConvTranspose2d` in PyTorch. In our implementation, we have shifted each input image so that it has zero mean in each of the three color channels. We have selected the first 100 images where the (trained) robust classifier gives correct labels; the plots are similar if one simply selects the first 100 training images.

¹⁶In fact, we have also re-scaled the perturbations so that they have similar mean and standard deviations comparing to real input images. This allows one to also compare the two rows of Figure 12.

Remark 8.1. We point out when comparing how sparse `clean_delta` and `robust_delta` can be reconstructed from robust features, we *did not cheat*. For instance, in principle `clean_delta` may not lie in the span of robust features and if so, it cannot be (sparsely) reconstructed from them. In our experiments (namely, the second row of Figure 12), we noticed that `clean_delta` almost lies in the span of robust features (with regression error < 0.00005 for AlexNet and $< 10^{-9}$ for ResNet).

8.4 Comparing Different Attackers

In this subsection, we demonstrate that feature purification occurs against several different attackers.

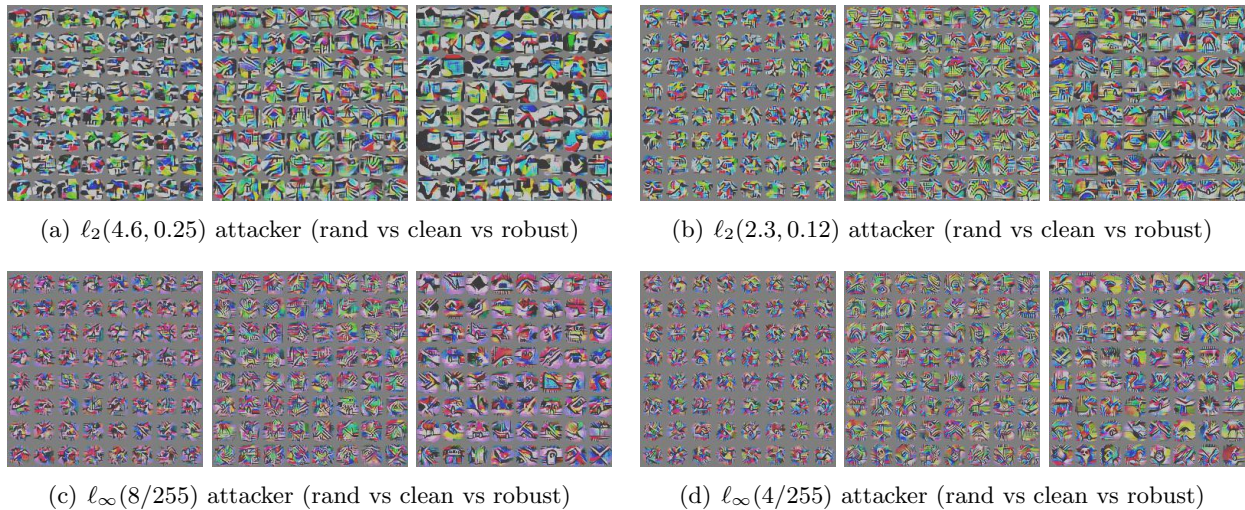


Figure 13: Visualization of the 11-th layer of ResNet-14 against different attackers.

Take-away message: feature purification happens against different attackers.

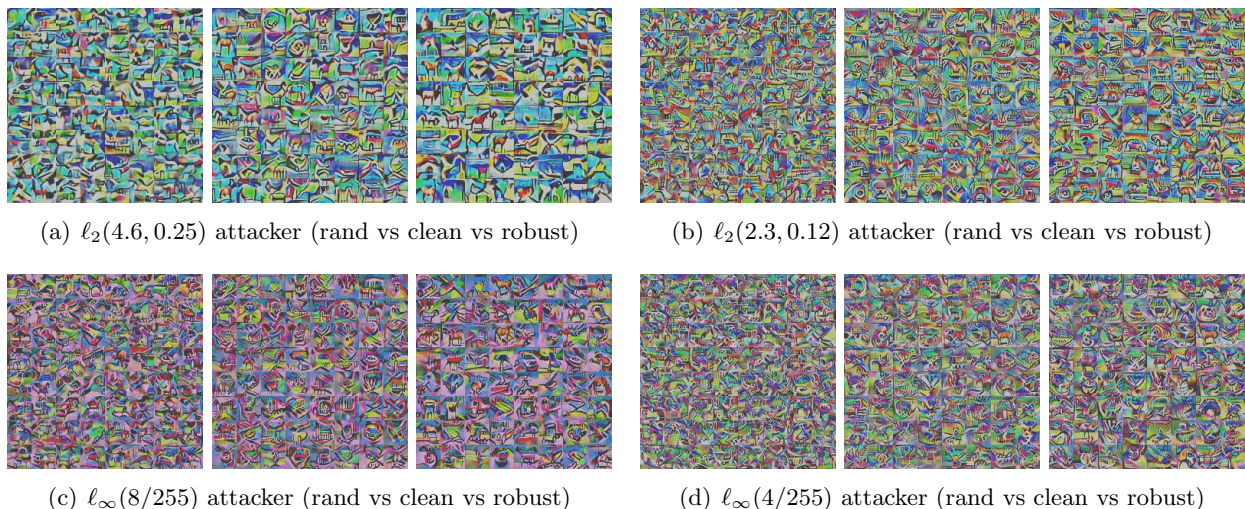


Figure 14: Visualization of the 27-th layer of ResNet-32 against different attackers.

Take-away message: feature purification happens against different attackers.

APPENDIX: COMPLETE PROOFS

We give a quick overview of the structure of our appendix sections.

In Section A, we warm up the readers by calculating the gradient of the objective, and demonstrating that polynomially many samples are sufficient for the training.

In Section B, we formally introduce $\mathcal{S}_{j,pot}^{(t)}$, the set of “potentially lucky neurons” and $\mathcal{S}_{j,sure}^{(t)}$, the set of “surely lucky neurons” at iteration t . In particular, we shall emphasize on how those notions evolve as t increases.

In Section C, we formally prove how “lucky neurons” continue to be lucky, and more importantly, for every neuron i that is lucky in direction j , why it grows faster than other unlucky directions j' , and how much faster. Specifically, Theorem C.1 corresponds to the initial “lottery-winning” phase where the accuracy remains around 50%; and Theorem C.2 corresponds to the later phase where large signals become even larger and eventually most neurons become “pure + dense mix” of the form (6.1). This is the most difficult section of this paper.

In Section D, we prove that why clean training gives good clean (testing) accuracy. It is based on the structural theorem given by Theorem C.2, and requires some non-trivial manipulations of probability theory results (such as introducing a high-probability, Bernstein form of the McDiarmid’s inequality).

In Section E, we prove that why the model obtained from clean training is non-robust. It formally shows how the “dense mixtures” become accumulated step by step during clean training.

In Section F, we prove our theorems for both ℓ_2 and ℓ_∞ adversarial training. In particular, in this section we demonstrate why practical perturbation algorithms, such as the fast gradient method (FGM), can help the (adversarial) training process “kill” those “dense mixtures.”

In Section G, we prove lower bounds for the neural tangent kernel model given by two-layer networks.

In Section H, we give missing details of some probability theory lemmas.

A Notations and Warmups

We find it perhaps a good exercise to do some simple calculations to warmup the readers with our notations, before going into the proofs.

Global Assumptions. Throughout the proof,

- We choose $m = d^{1+c_0}$ for a very small constant $c_0 \in (0, 1)$.

(One should think of $c_0 = 0.0001$ for a simple reading. Our proof generalizers to larger $m = \text{poly}(d)$ since having more neurons does not hurt performance, but we ignore the analysis so as to provide the simplest notations.)

- We assume $k < d^{(1-c_0)/2}$.
- We choose $\lambda = \frac{\log \log \log d}{d}$ for simplicity.

(The purpose of $\log \log \log d$ factor is to simplify notations, and it can be tightened to constant.)

- Whenever we write “for random x ”, “for random z ” or “for random ξ ”, we mean that they come from the distributions introduced in Section 2 with $x = \mathbf{M}z + \xi$.

Network Gradient. In every iteration t , the weights of the neurons are $w_1^{(t)}, \dots, w_m^{(t)} \in \mathbb{R}^d$. Recall the output of the neural network on input $x \in \mathbb{R}^d$ is

$$f_t(w^{(t)}; x, \rho) = \sum_{i=1}^m \text{ReLU}(\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) .$$

Fact A.1. If we denote by $\ell'_t(w^{(t)}; x, y, \rho) \stackrel{\text{def}}{=} \frac{d}{ds} [\log(1 + e^s)] |_{s=-yf_t(w^{(t)}; x, \rho)} = \frac{e^{-yf_t(w^{(t)}; x, \rho)}}{1 + e^{-yf_t(w^{(t)}; x, \rho)}}$, then

$$\begin{aligned} \nabla_{w_i} \mathbf{Loss}_t(w^{(t)}; x, y, \rho) &= -y \ell'_t(w^{(t)}; x, y, \rho) \nabla_{w_i} f_t(w^{(t)}; x, \rho) \\ &= -y \ell'_t(w^{(t)}; x, y, \rho) \left(\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \cdot x \end{aligned}$$

Let us also note that

$$\nabla \mathbf{Reg}(w_i) = (\|w_i\|_2 + 1) \cdot w_i$$

Lemma A.2. Suppose $\mathcal{Z} = \{x^{(1)}, \dots, x^{(N)}\}$ are i.i.d. samples from \mathcal{D} and $y^{(i)} = y(x^{(i)})$, and suppose $N \geq \text{poly}(d)$ for some sufficiently large polynomial. Let $f = f_t$ and suppose $b^{(t)} \leq \text{poly}(d)$ and $\sigma_\rho \geq \frac{1}{\text{poly}(d)}$. Then, for every w_1, \dots, w_N that may depend on the randomness of \mathcal{Z} and satisfies $\|w_i\| \leq \text{poly}(d)$, it satisfies

$$\begin{aligned} &\left| \frac{1}{N} \sum_{i \in [N]} \mathbb{E}_\rho [\mathbf{Loss}(w; x^{(i)}, y^{(i)}, \rho)] - \mathbb{E}_{x \sim \mathcal{D}, y=y(x), \rho} [\mathbf{Loss}(w; x, y, \rho)] \right| \leq \frac{1}{\text{poly}(d)} \\ &\left\| \frac{1}{N} \sum_{i \in [N]} \mathbb{E}_\rho [\nabla_w \mathbf{Loss}(w; x^{(i)}, y^{(i)}, \rho)] - \mathbb{E}_{x \sim \mathcal{D}, y=y(x), \rho} [\nabla_w \mathbf{Loss}(w; x, y, \rho)] \right\|_F \leq \frac{1}{\text{poly}(d)} \end{aligned}$$

In addition, suppose for every $i \in [N]$, we have an i.i.d. random sample $\rho^{(i)} \sim \mathcal{N}(0, \sigma_\rho^2 \mathbf{I})$ that is independent of \mathcal{Z} and w . Then, with probability at least $1 - e^{-\Omega(\log^2 d)}$ over ρ , we have

$$\begin{aligned} &\left| \frac{1}{N} \sum_{i \in [N]} \mathbb{E}_\rho [\mathbf{Loss}(w; x^{(i)}, y^{(i)}, \rho)] - \frac{1}{N} \sum_{i \in [N]} \mathbf{Loss}(w; x^{(i)}, y^{(i)}, \rho^{(i)}) \right| \leq \frac{1}{\text{poly}(d)} \\ &\left\| \frac{1}{N} \sum_{i \in [N]} \mathbb{E}_\rho [\nabla_w \mathbf{Loss}(w; x^{(i)}, y^{(i)}, \rho)] - \frac{1}{N} \sum_{i \in [N]} \nabla_w \mathbf{Loss}(w; x^{(i)}, y^{(i)}, \rho^{(i)}) \right\|_F \leq \frac{1}{\text{poly}(d)} \end{aligned}$$

Proof. The proof of the first part can be done by trivial VC dimension or Rademacher complexity arguments. For instance, the function $\mathbb{E}_\rho [\nabla_w \mathbf{Loss}(w; x, y, \rho)]$ is Lipschitz continuous in w with Lipschitz parameter at most $\text{poly}(d)$ (note that this relies on the fact that we take an expectation in ρ), and thus one can take an epsilon-net over all possible choices of w , and then apply a union bound over them.

The proof of the second part can be done by trivial Hoeffding bounds. \square

B Neuron Structure and Initialization Properties

We consider $m = d^{1+c_0}$ for a very small constant $c_0 \in (0, 1)$, and consider constants $c_1 > c_2$ to be chosen shortly. Let us define a few notations to characterize each neuron's behavior.

Definition B.1 (neuron characterization). Recall $w_i^{(t)}$ is the weight for the i -th neuron at iteration t . We shall choose a parameter $\sigma_w^{(t)}$ at each iteration $t \geq 0$ and define the following notions. Consider any dimension $j \in [d]$.

1. Let $\mathcal{S}_{j,\text{sure}}^{(t)} \subseteq [m]$ be those neurons $i \in [m]$ satisfying
 - $\langle w_i^{(t)}, \mathbf{M}_j \rangle^2 \geq (c_1 + c_2)(\sigma_w^{(t)})^2 \log d$,
 - $\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle^2 < (c_1 - c_2)(\sigma_w^{(t)})^2 \log d$
 - $\text{sign}(\langle w_i^{(t)}, \mathbf{M}_j \rangle) = \text{sign}(w_j^*)$.

for every $j' \neq j$,
2. Let $\mathcal{S}_{j,\text{pot}}^{(t)} \subseteq [m]$ be those neurons $i \in [m]$ satisfying
 - $\langle w_i^{(t)}, \mathbf{M}_j \rangle^2 \geq (c_1 - c_2)(\sigma_w^{(t)})^2 \log d$
3. Let $\mathcal{S}_{\text{ept}}^{(t)} \subseteq [m]$ be the set of neurons $i \in [m]$ satisfying
 - $\|w_i^{(t)}\|_2^2 \leq 2(\sigma_w^{(t)})^2 d$
 - $\langle w_i^{(t)}, \mathbf{M}_j \rangle^2 \geq (c_1 - c_2)(\sigma_w^{(t)})^2 \log d$ for at most $O(1)$ many $j \in [d]$.
 - $\langle w_i^{(t)}, \mathbf{M}_j \rangle^2 \geq 2(\sigma_w^{(t)})^2 \sqrt{\log d}$ for at most $2^{-\sqrt{\log d}} d$ many $j \in [d]$.
 - $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq \frac{\sigma_w^{(t)}}{\log d}$ for at least $\Omega(\frac{d}{\log d})$ many $j \in [d]$.

Lemma B.2 (geometry at initialization). *Suppose each $w_i^{(0)} \sim \mathcal{N}(0, \sigma_0^2 \mathbf{I})$ and suppose $\sigma_w^{(0)} = \sigma_0$. For every constants $c_0 \in (0, 1)$ and $\gamma \in (0, 0.1)$, by choosing $c_1 = 2 + 2(1 - \gamma)c_0$ and $c_2 = \gamma c_0$, we have with probability $\geq 1 - o(1/d^3)$ over the random initialization, for all $j \in [d]$:*

$$|\mathcal{S}_{j,\text{sure}}^{(0)}| = \Omega\left(d^{\frac{3}{4}c_0}\right) =: \Xi_1 \quad |\mathcal{S}_{j,\text{pot}}^{(0)}| \leq O\left(d^{2\gamma c_0}\right) =: \Xi_2 \quad \mathcal{S}_{\text{ept}}^{(0)} = [m]$$

Remark. In the rest of the paper, we shall assume Lemma B.2 holds in all upper-bound related theorems/lemmas, and for simplicity, we assume $\gamma > 0$ is some small constant so that $(\Xi_2)^{100} \leq d^{c_0}$. The notations Ξ_1 and Ξ_2 shall be used throughout the paper.

Definition B.3 (neuron characterization, continued). *Recall $b^{(t)}$ is the bias at iteration t , and let us introduce more notions.*

1. Let $\mathcal{S}_{\text{ept}+}^{(t)} \subseteq [m]$ be the set of neurons $i \in [m]$ satisfying
 - $\|w_i^{(t)}\|_2^2 \leq \frac{(\sigma_w^{(t)})^2 d}{\log^2 d}$,
 - $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq \frac{\sigma_w^{(t)}}{\log d}$ for at most $O(1)$ many $j \in [d]$.
2. Let $\mathcal{S}_{\text{ept}++}^{(t)} \subseteq [m]$ be the set of neurons $i \in [m]$ satisfying
 - $\|w_i^{(t)}\|_2^2 \leq \frac{(\sigma_w^{(t)})^2}{\beta^2}$ for $\beta \stackrel{\text{def}}{=} \frac{1}{\sqrt{k\Xi_2^{10}}}$.
3. Let $\mathcal{S}_{j,\text{pot}+}^{(t)} \subseteq [m]$ be the set of neurons $i \in [m]$ satisfying
 - $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq \frac{k}{d\beta} b^{(t)}$.
4. Let $\mathcal{S}_{j,\text{sure}+}^{(t)} \subseteq [m]$ be the set of neurons $i \in [m]$ satisfying
 - $\langle w_i^{(t)}, \mathbf{M}_j \rangle^2 \geq 4k(b^{(t)})^2$,
 - $\text{sign}(\langle w_i^{(t)}, \mathbf{M}_j \rangle) = \text{sign}(w_j^*)$.

Note that we do not have good properties on $\mathcal{S}_{\text{ept}+}^{(t)}$, $\mathcal{S}_{\text{ept}++}^{(t)}$, $\mathcal{S}_{j,\text{pot}+}^{(t)}$ or $\mathcal{S}_{j,\text{sure}+}^{(t)}$ at initialization $t = 0$; however, they will gradually begin to satisfy certain properties as the training process goes. See Section C for details.

B.1 Proof of Lemma B.2

Proof of Lemma B.2. Recall if g is standard Gaussian, then for every $t > 0$,

$$\frac{1}{\sqrt{2\pi}} \frac{t}{t^2 + 1} e^{-t^2/2} < \Pr_{g \sim \mathcal{N}(0,1)} [g > t] < \frac{1}{\sqrt{2\pi}} \frac{1}{t} e^{-t^2/2}$$

Therefore, for every $i \in [m]$ and $j \in [d]$,

- $p_1 = \Pr[\langle w_i^{(0)}, \mathbf{M}_j \rangle^2 \geq (c_1 + c_2)\sigma_0^2 \log d] = \Theta\left(\frac{1}{\log d}\right) \cdot \frac{1}{d^{(c_1+c_2)/2}} = \Theta\left(\frac{1}{\log d}\right) \cdot \frac{1}{d \cdot d^{(1-\gamma/2)c_0}}$
- $p_2 = \Pr[\langle w_i^{(0)}, \mathbf{M}_j \rangle^2 \geq (c_1 - c_2)\sigma_0^2 \log d] = \Theta\left(\frac{1}{\log d}\right) \cdot \frac{1}{d^{(c_1-c_2)/2}} = \Theta\left(\frac{1}{\log d}\right) \cdot \frac{1}{d \cdot d^{(1-3\gamma/2)c_0}}$

1. We first lower bound $|\mathcal{S}_{j, \text{sure}}^{(0)}|$. For every $i \in [m]$, with probability at least $p_1/2 \cdot (1 - p_2)^{d-1} \geq \Omega\left(\frac{1}{\log d}\right) \cdot \frac{d^{\frac{7}{2}c_0}}{m}$ it satisfies

$$\begin{aligned} \langle w_i^{(0)}, \mathbf{M}_j \rangle^2 &\geq (c_1 + c_2)\sigma_0^2 \log d, & \text{sign}(\langle w_i^{(0)}, \mathbf{M}_j \rangle) \text{sign}(w_j^*) &\geq 0 \\ \forall j' \neq j, \langle w_i^{(0)}, \mathbf{M}_{j'} \rangle^2 &\leq (c_1 - c_2)\sigma_0^2 \log d \end{aligned}$$

By concentration with respect to all m choices of $i \in [m]$, we know with probability at least $1 - o\left(\frac{1}{d^3}\right)$ it satisfies $|\mathcal{S}_{j, \text{sure}}^{(0)}| = \Omega\left(d^{\frac{7}{4}c_0}\right)$.

2. We next upper bound $|\mathcal{S}_{j, \text{pot}}^{(0)}|$. For every $i \in [m]$, with probability at most $p_2 < O\left(\frac{1}{\log d}\right) \cdot \frac{d^{\frac{3\gamma}{2}c_0}}{m}$ it satisfies

$$\langle w_i^{(0)}, \mathbf{M}_j \rangle^2 \geq (c_1 - c_2)\sigma_0^2 \log d$$

By concentration with respect to all m choices of i , we know with probability at least $1 - o\left(\frac{1}{d^3}\right)$ it satisfies $|\mathcal{S}_{j, \text{pot}}^{(0)}| = O(d^{2\gamma c_0})$.

3. As for $\mathcal{S}_{\text{ept}}^{(0)}$, we first note that for every $i \in [m]$, by chi-square distribution's tail bound, with probability at least $1 - o(1/d^3)$ it satisfies $\|w_i^{(0)}\|_2^2 \in \left[\frac{\sigma_0^2 d}{2}, 2\sigma_0^2 d\right]$.

For every $i \in [m]$, the probability of existing $q = 20/c_0$ different

$$j_1, \dots, j_q \in [d] : \text{s.t. } \forall r \in [q] : \langle w_i^{(0)}, \mathbf{M}_{j_r} \rangle^2 \geq (c_1 - c_2)\sigma_0^2 \log d$$

is at most $d^q \cdot (p_2)^q \leq d^{-q \cdot \frac{c_0}{2}} \leq \frac{1}{d^{4m}}$. Union bounding over all possible $i \in [m]$ gives the proof that, with probability at least $1 - 1/d^4$, for all but at most $q = O(1)$ values of $j \in [d]$, it satisfies $\langle w_i^{(0)}, \mathbf{M}_j \rangle^2 < (c_1 - c_2)(\sigma_w^{(t)})^2 \log d$.

For every $i \in [m]$ and $j \in [d]$, with probability at least $1 - e^{-\sqrt{\log d}}$ it satisfies $\langle w_i^{(0)}, \mathbf{M}_j \rangle^2 \leq \sigma_0^2 \sqrt{\log d}$. Therefore, with probability at least $1 - o(1/d^3)$, there are $d(1 - 2^{-\sqrt{\log d}})$ indices $j \in [d]$ satisfying $\langle w_i^{(0)}, \mathbf{M}_j \rangle^2 \leq \sigma_0^2 \sqrt{\log d}$.

For every $i \in [m]$ and $j \in [d]$, with probability at least $\frac{1}{40000\sqrt{\log d}}$ it satisfies $|\langle w_i^{(0)}, \mathbf{M}_j \rangle| \leq \frac{\sigma_0}{10000\sqrt{\log d}}$. Therefore, with probability at least $1 - o(1/d^3)$, there are $\frac{1}{100000\sqrt{\log d}}$ indices $j \in [d]$ satisfying $|\langle w_i^{(0)}, \mathbf{M}_j \rangle| \leq \frac{\sigma_0}{10000\sqrt{\log d}}$. \square

C Neuron Structure Change During Training

For analysis purpose, we consider two phases during training. In Phase I, the neurons have moved so little so that the accuracy remains 50% for binary classification; however, some neurons shall

start to win lottery and form “singleton” structures. We summarize this as the following theorem.

Theorem C.1 (phase I). *Suppose the high-probability initialization event in Lemma B.2 holds. Suppose $\eta, \sigma_0 \in (0, \frac{1}{\text{poly}(d)})$ and $N \geq \text{poly}(d)$. With probability at least $1 - e^{-\Omega(\log^2 d)}$, the following holds for all $t \leq T_b \stackrel{\text{def}}{=} \Theta\left(\frac{d^2 \sigma_0}{k\eta}\right)$*

1. $\mathcal{S}_{j,\text{sure}}^{(0)} \subseteq \mathcal{S}_{j,\text{sure}}^{(t)}$ for every $j \in [d]$.
2. $\mathcal{S}_{j,\text{pot}}^{(0)} \supseteq \mathcal{S}_{j,\text{pot}}^{(t)}$ for every $j \in [d]$.
3. $\mathcal{S}_{\text{ept}}^{(t)} = [m]$
4. $\mathcal{S}_{\text{ept}+}^{(t)} = [m]$ for every $t \geq T_a \stackrel{\text{def}}{=} \Theta\left(\frac{d\sigma_0 \log^{2.5} d}{\eta}\right)$.
5. $\mathcal{S}_{\text{ept}++}^{(t)} = [m]$ and $\mathcal{S}_{j,\text{pot}}^{(0)} \supseteq \mathcal{S}_{j,\text{pot}+}^{(t)}$ for every $j \in [d]$ at this iteration $t = T_b$.

In Phase II, the neurons start to move much more so that the network output becomes more meaningful; in phase II, the “singleton” neurons become even more singleton.

Theorem C.2 (phase II). *In the same setting as Theorem C.1, with probability at least $1 - e^{-\Omega(\log^2 d)}$, the following holds for all $t \in [T_b, d^{\mathcal{O}(\log d)}/\eta]$.*

1. $\mathcal{S}_{\text{ept}++}^{(t)} = \mathcal{S}_{\text{ept}+}^{(t)} = [m]$.
2. $\mathcal{S}_{j,\text{sure}}^{(0)} \subseteq \mathcal{S}_{j,\text{sure}}^{(t)}$ for every $j \in [d]$.
3. $\mathcal{S}_{j,\text{pot}}^{(0)} \supseteq \mathcal{S}_{j,\text{pot}+}^{(t)} \supseteq \mathcal{S}_{j,\text{pot}}^{(t)}$ for every $j \in [d]$.
4. $\mathcal{S}_{j,\text{sure}}^{(0)} \subseteq \mathcal{S}_{j,\text{sure}+}^{(t)}$ for every $j \in [d]$, as long as $t \geq T_e \stackrel{\text{def}}{=} \Theta\left(\frac{d}{\eta \Xi_2 \log d}\right)$.

C.1 Auxiliary Lemma 1: Geometry of Crossing Boundary

We present a lemma to bound the size of the pre-activation signal.

Lemma C.3 (pre-activation signal size). *For every $t \geq 0$, every $i \in [m]$, every $\lambda \geq 0$, every $j \in [d]$:*

(a) *If $i \in \mathcal{S}_{\text{ept}}^{(t)}$ then*

$$\Pr_{z,\xi} \left[\left\langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \right\rangle^2 \geq \lambda^2 (\sigma_w^{(t)})^2 \right] \leq e^{-\Omega\left(\frac{\lambda}{\log^{1/4} d}\right)} + e^{-\log^{1/4} d}$$

(b) *If $i \in \mathcal{S}_{\text{ept}+}^{(t)}$ then*

$$\Pr_{z,\xi} \left[\left\langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \right\rangle^2 \geq \lambda^2 (\sigma_w^{(t)})^2 \right] \leq e^{-\Omega(\lambda \log d)} + e^{-\Omega(\lambda^2 \log d)} + O\left(\frac{k}{d}\right)$$

Proof of Lemma C.3a. Let \mathcal{E} be the event where there exists $j' \in [d]$ with $|z_{j'}| \geq \frac{1}{\log^2 d}$ and $\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle^2 \geq 2(\sigma_w^{(t)})^2 \sqrt{\log d}$. Since $\mathbb{E}[z_{j'}^2] = O\left(\frac{1}{d}\right)$, we know that $\Pr \left[|z_{j'}| \geq \frac{1}{\log^2 d} \right] \leq O\left(\frac{\log^4 d}{d}\right)$.

By the definition of $\mathcal{S}_{\text{ept}}^{(t)}$ and union bound, we know

$$\Pr[\mathcal{E}] \leq O\left(\frac{\log^4 d}{d}\right) \times 2^{-\sqrt{\log d} d} \leq e^{-\log^{1/4} d}$$

Let \mathcal{F} be the event where there exists $j' \in [d]$ with $z_{j'} \neq 0$ and $\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle^2 \geq \Omega((\sigma_w^{(t)})^2 \log d)$. Again, by the definition of $\mathcal{S}_{ept}^{(t)}$, we know that

$$\Pr[\mathcal{F}] \leq O\left(\frac{k}{d}\right) \leq e^{-\log^{1/4} d}$$

Thus, when neither \mathcal{E} or \mathcal{F} happens, we have for every $j' \in [d]$:

$$\langle w_i^{(t)}, \mathbf{M}_{j'} z_{j'} \rangle^2 \leq \min \left\{ 2(\sigma_w^{(t)})^2 \sqrt{\log d} \cdot 1, O((\sigma_w^{(t)})^2 \log d) \cdot \frac{1}{\log^4 d} \right\} \leq 2(\sigma_w^{(t)})^2 \sqrt{\log d}$$

At the same time, we also have

$$\sum_{j' \in [d]} \mathbb{E}_{z_{j'}} \langle w_i^{(t)}, \mathbf{M}_{j'} z_{j'} \rangle^2 \leq \sum_{j' \in [d]} O\left(\frac{1}{d}\right) \langle w_i^{(t)}, \mathbf{M}_{j'} \rangle^2 \leq O((\sigma_w^{(t)})^2)$$

Apply Bernstein concentration bound we complete the proof that

$$\Pr_{z, \xi} \left[\left\langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} \right\rangle^2 \geq \frac{\lambda^2}{2} (\sigma_w^{(t)})^2 \right] \leq e^{-\Omega\left(\frac{\lambda}{\log^{1/4} d}\right)} + e^{-\log^{1/4} d}$$

Finally, for the ξ part, let us recall $\langle w_i^{(t)}, \xi \rangle$ variable with variance at most $O\left(\frac{\|w_i^{(t)}\|^2 \sigma_x^2}{d}\right) \leq O((\sigma_w^{(t)})^2)$ and each $|\langle w_i^{(t)}, \mathbf{M}_j \rangle \langle \mathbf{M}_j, \xi \rangle| \leq \frac{\sigma_w^{(t)}}{\log^2 d}$ w.h.p. Using Bernstein concentration of random variables, we finish the proof. \square

Proof of Lemma C.3b. Let \mathcal{F} be the event where there exists $j' \in [d]$ with $z_{j'} \neq 0$ and $|\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle| \geq \Omega\left(\frac{\sigma_w^{(t)}}{\log d}\right)$. By the definition of $\mathcal{S}_{ept+}^{(t)}$, we know that

$$\Pr[\mathcal{F}] \leq O\left(\frac{k}{d}\right)$$

When \mathcal{F} does not happen, we have for every $j' \in [d]$: $|\langle w_i^{(t)}, \mathbf{M}_{j'} z_{j'} \rangle| \leq O\left(\frac{\sigma_w^{(t)}}{\log d}\right)$ and at the same time

$$\sum_{j' \in [d]} \mathbb{E}_{z_{j'}} \langle w_i^{(t)}, \mathbf{M}_{j'} z_{j'} \rangle^2 \leq \sum_{j' \in [d]} O\left(\frac{1}{d}\right) \langle w_i^{(t)}, \mathbf{M}_{j'} \rangle^2 \leq O\left(\frac{(\sigma_w^{(t)})^2}{\log d}\right)$$

Apply Bernstein concentration bound we complete the proof that

$$\Pr_{z, \xi} \left[\left\langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} \right\rangle^2 \geq \frac{\lambda^2}{2} (\sigma_w^{(t)})^2 \right] \leq e^{-\Omega(\lambda \log d)} + e^{-\Omega(\lambda^2 \log d)} + O\left(\frac{k}{d}\right)$$

Finally, for the ξ part, let us recall $\langle w_i^{(t)}, \xi \rangle$ is a random variable with variance at most $O\left(\frac{\|w_i^{(t)}\|^2 \sigma_x^2}{d}\right) \leq O\left(\frac{(\sigma_w^{(t)})^2}{\log^2 d}\right)$. Using the Bernstein concentration bound, we finish the proof. \square

C.2 Auxiliary Lemma 2: A Critical Lemma for Gradient Bound

In this section we present a critical lemma that shall be used multiple times to bound the gradient in many of the following sections. Recall $\frac{c_2}{c_1} \in (0, 0.1)$ is a constant from Lemma B.2.

Lemma C.4 (critical). *Let $Y(z, S_1): \mathbb{R} \times \mathbb{R}^p \rightarrow [-1, 1]$ be a center symmetric function, meaning $Y(z, S_1) = Y(-z, -S_1)$. Let $S_1 \in \mathbb{R}^p$ and $S_2 \in \mathbb{R}$ be random variables, where (S_1, S_2) is symmetrically distributed, meaning (S_1, S_2) distributes the same as $(-S_1, -S_2)$.*

For every $\alpha > 0$, suppose $\rho \sim \mathcal{N}(0, \sigma_\rho^2)$, define quantity

$$\Delta := \mathbb{E}_{S_1, S_2, \rho} [Y(1, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} - Y(-1, S_1) \mathbf{1}_{-\alpha+S_2+\rho \geq b}]$$

and define parameters $V := \mathbb{E}[(S_2)^2]$ and $L := \mathbb{E}_{S_1}[|Y(1, S_1) - Y(0, S_1)|]$. Then,

(a) it always satisfies $|\Delta| \leq O\left(\frac{\sqrt{V}}{\sigma_\rho} + L\right)$

(b) if $Y(z, S_1)$ is a monotonically non-decreasing in $z \in \mathbb{R}$ for every $S_1 \in \mathbb{R}^p$, then $\Delta \geq -\Omega\left(\frac{\sqrt{V}}{\sigma_\rho}\right)$. Furthermore, suppose we can write $S_1 = (S'_1, S''_1)$ and $S_2 = S'_2 + S''_2$ for (S'_1, S'_2) and (S''_1, S''_2) being independent (although S'_1, S'_2 may be dependent, and S''_1, S''_2 may be dependent). Then, we have

(c) if $\alpha \leq b(1 - \frac{c_2}{2c_1})$, then $|\Delta| \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma\right) \left(\min\{1, O(\frac{\alpha}{\sigma_\rho})\} + L_y\right) + \Gamma_y$

where the parameters

- $\Gamma := \mathbf{Pr}\left[|S_2| \geq \frac{c_2}{10c_1} \cdot b\right]$ and $\Gamma_y := \mathbf{Pr}\left[|S''_2| \geq \frac{c_2}{10c_1} \cdot b\right]$
- $L_y := \max_{S'_1} \left\{ \mathbb{E}_{S''_1} [|Y(1, S'_1, S''_1) - Y(0, S'_1, S''_1)|] \right\} \leq 1$

Proof of Lemma C.4. We first focus on $Y(1, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b}$, and write

$$Y(1, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} = Y(0, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} + (Y(1, S_1) - Y(0, S_1)) \mathbf{1}_{\alpha+S_2+\rho \geq b} \quad (\text{C.1})$$

$$= Y(0, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} \pm |Y(1, S_1) - Y(0, S_1)| \mathbf{1}_{\alpha+S_2+\rho \geq b} \quad (\text{C.2})$$

Focusing on the term $Y(0, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b}$, by the symmetric properties of Y and (S_1, S_2) , we have

$$\begin{aligned} |\mathbb{E}[Y(0, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b}]| &= \frac{1}{2} |\mathbb{E}[Y(0, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} + Y(0, -S_1) \mathbf{1}_{\alpha-S_2+\rho \geq b}]| \\ &= \frac{1}{2} |\mathbb{E}[Y(0, S_1) (\mathbf{1}_{\alpha+S_2+\rho \geq b} - \mathbf{1}_{\alpha-S_2+\rho \geq b})]| \\ &\leq \mathbf{Pr}[\mathbf{1}_{\alpha+S_2+\rho \geq b} \neq \mathbf{1}_{\alpha-S_2+\rho \geq b}] \\ &\leq \mathbf{Pr}[\rho \in [b - \alpha - S_2, b - \alpha + S_2]] \\ &= O\left(\frac{\mathbb{E}[|S_2|]}{\sigma_\rho}\right) = O\left(\frac{\sqrt{\mathbb{E}[S_2^2]}}{\sigma_\rho}\right) = O\left(\frac{\sqrt{V}}{\sigma_\rho}\right) \end{aligned} \quad (\text{C.3})$$

Putting (C.3) into (C.2), applying the bound $L = \mathbb{E}_{S_1}[|Y(1, S_1) - Y(0, S_1)|]$, and repeating the same analysis for $Y(-1, S_1) \mathbf{1}_{-\alpha+S_2+\rho \geq b}$ gives

$$|\Delta| \leq O\left(\frac{\sqrt{V}}{\sigma_\rho} + L\right).$$

This proves Lemma C.4a. When $Y(z, S_1)$ is a monotone non-decreasing in $z \in \mathbb{R}$, we have

$$\begin{aligned} Y(1, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} &\geq Y(0, S_1) \mathbf{1}_{\alpha+S_2+\rho \geq b} \\ Y(-1, S_1) \mathbf{1}_{-\alpha+S_2+\rho \geq b} &\leq Y(0, S_1) \mathbf{1}_{-\alpha+S_2+\rho \geq b} \end{aligned}$$

so we can go back to (C.1) (and repeating for $Y(-1, S_1)$) to derive that

$$\Delta \geq -\Omega\left(\frac{\sqrt{V}}{\sigma_\rho}\right)$$

This proves Lemma C.4b. Finally, when $\alpha \leq b(1 - \frac{c_2}{2c_1})$, we can bound Δ differently

$$\begin{aligned} |\Delta| &\leq 2 \mathbf{Pr}[\mathbf{1}_{\alpha+S_2+\rho \geq b} \neq \mathbf{1}_{-\alpha+S_2+\rho \geq b}] + \mathbb{E}[|Y(1, S_1) - Y(-1, S_1)| \cdot \mathbf{1}_{\alpha+S_2+\rho \geq b}] \\ &= 2 \mathbf{Pr}[\rho \in [b - S_2 - \alpha, b - S_2 + \alpha]] + \mathbb{E}[|Y(1, S_1) - Y(-1, S_1)| \cdot \mathbf{1}_{\alpha+S_2+\rho \geq b}] \end{aligned} \quad (\text{C.4})$$

To bound the first term in (C.4) we consider two cases.:

- when $|S_2| \leq \frac{b}{4}$, we have $\Pr_\rho[\rho \in [b - S_2 - \alpha, b - S_2 + \alpha]] \leq \min\{1, \frac{\alpha}{\sigma_\rho}\} e^{-\Omega(b^2/\sigma_\rho^2)}$;
- when $|S_2| \geq \frac{b}{4}$ (happening w.p. $\leq \Gamma$), we have $\Pr_\rho[\rho \in [b - S_2 - \alpha, b - S_2 + \alpha]] \leq \min\{1, O(\frac{\alpha}{\sigma_\rho})\}$.

Putting together, we know that

$$\Pr[\rho \in [b - S_2 - \alpha, b - S_2 + \alpha]] \leq \min\{1, \frac{\alpha}{\sigma_\rho}\} \cdot (e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma) \quad (\text{C.5})$$

To bound the second term in (C.4), first recall $S_1 = (S'_1, S''_1)$ and $S_2 = S'_2 + S''_2$, so we can write

$$\begin{aligned} & \mathbb{E} \left[|Y(1, S'_1, S''_1) - Y(-1, S'_1, S''_1)| \cdot \mathbb{1}_{\alpha + S'_2 + S''_2 + \rho \geq b} \right] \\ & \leq \mathbb{E} \left[|Y(1, S'_1, S''_1) - Y(-1, S'_1, S''_1)| \cdot (\mathbb{1}_{|\alpha + S'_2 + \rho| \geq (1 - \frac{c_2}{10c_1}) \cdot b} + \mathbb{1}_{|S''_2| \geq \frac{c_2}{10c_1} \cdot b}) \right] \\ & \leq \mathbb{E} \left[|Y(1, S'_1, S''_1) - Y(-1, S'_1, S''_1)| \cdot \mathbb{1}_{|\alpha + S'_2 + \rho| \geq (1 - \frac{c_2}{10c_1}) \cdot b} \right] + \Gamma_y \end{aligned} \quad (\text{C.6})$$

To bound the first term in (C.6), we can take expectation over S''_1 and use the bound L_y to derive

$$\mathbb{E} \left[|Y(1, S'_1, S''_1) - Y(-1, S'_1, S''_1)| \cdot \mathbb{1}_{|\alpha + S'_2 + \rho| \geq (1 - \frac{c_2}{10c_1}) \cdot b} \right] \leq L_y \Pr \left[|\alpha + S'_2 + \rho| \geq (1 - \frac{c_2}{10c_1}) \cdot b \right]$$

but since $\alpha \leq (1 - \frac{c_2}{2c_1}) \cdot b$ and $S'_2 = S_2 - S''_2$, we can further bound

$$\begin{aligned} \Pr \left[|\alpha + S'_2 + \rho| \geq (1 - \frac{c_2}{10c_1}) \cdot b \right] & \leq \Pr \left[|S''_2| \geq \frac{c_2}{10c_1} \cdot b \right] + \Pr \left[|S_2| \geq \frac{c_2}{10c_1} \cdot b \right] + \Pr \left[\rho \geq \frac{c_2}{10c_1} \cdot b \right] \\ & \leq \Gamma_y + \Gamma + e^{-\Omega(b^2/\sigma_\rho^2)} \end{aligned}$$

Putting these back to (C.6), we have

$$\mathbb{E} \left[|Y(1, S'_1, S''_1) - Y(-1, S'_1, S''_1)| \mathbb{1}_{\alpha + S'_2 + S''_2 + \rho \geq b} \right] \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma + \Gamma_y \right) L_y + \Gamma_y \quad (\text{C.7})$$

Putting (C.5) and (C.7) back to (C.4), we conclude the when $\alpha \leq b(1 - \frac{c_2}{2c_1})$, we have

$$|\Delta| \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma \right) \left(O\left(\frac{\alpha}{\sigma_\rho}\right) + L_y \right) + \Gamma_y \quad \square$$

C.3 Phase I: Winning lottery tickets near initialization

In Phase I, we have two sub-phases:

- In Phase I.1, we pick $b^{(t)} = \sqrt{c_1} \sigma_w^{(t)} \sqrt{\log d}$ and $\sigma_\rho^{(t)} = \sigma_w^{(t)} (\log \log \log d)^3$
We grow $b^{(t+1)} = b^{(t)} + \frac{C\eta}{d}$ for $T_a = \Theta\left(\frac{d\sigma_0 \log^{2.5} d}{\eta}\right)$ iterations.
- In Phase I.2, we pick $b^{(t)} = \sqrt{c_1} \sigma_w^{(t)} \sqrt{\log d}$ and $\sigma_\rho^{(t)} = \sigma_w^{(t)} \cdot \frac{(\log \log \log d)^3}{\sqrt{\log d}}$
We grow $b^{(t+1)} = b^{(t)} + \frac{C\eta}{d}$ for $T_b = \Theta\left(\frac{d^2 \sigma_0}{k\eta}\right)$ iterations.

C.3.1 Activation Probability

Recall $x = \sum_j \mathbf{M}_j z_j + \xi$. Recall also $\frac{c_2}{c_1} \in (0, 0.1)$ is a constant from Lemma B.2.

Lemma C.5 (activation probability). *We define Γ_t to be any value such that*

- $\Pr_x \left[\left| \langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq \Gamma_t$ for every $i \in [m]$ and $j \in [d]$;

- $\Pr_x \left[\left| \langle w_i^{(t)}, x \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq \Gamma_t$ for every $i \in [m]$
- $\Pr_x \left[\left| \rho_i \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq \Gamma_t$ for every $i \in [m]$

We define $\Gamma_{t,y}$ to be any value such that

- for every $i \in [m]$ and $j \in [d]$, there exists $\Lambda \subseteq [d] \setminus \{j\}$ with $|\Lambda| \geq \Omega\left(\frac{d}{\sqrt{\log d}}\right)$ satisfying
$$\Pr_x \left[\left| \langle w_i^{(t)}, \sum_{j' \in \Lambda} \mathbf{M}_{j'} z_{j'} \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq \Gamma_{t,y}$$

Then,

- If we are in Phase I.1 and $\mathcal{S}_{ept}^{(t)} = [m]$, then we can choose $\Gamma_t = e^{-\Omega(\log^{1/4} d)}$ and $\Gamma_{t,y} = \frac{1}{d^{10}}$.
- If we are in Phase I.2 and $\mathcal{S}_{ept+}^{(t)} = [m]$, then we can choose $\Gamma_t = O\left(\frac{k}{d}\right)$ and $\Gamma_{t,y} = \frac{1}{d^{10}}$.

Proof. Recall $b^{(t)} = \Theta(\sigma_w^{(t)} \sqrt{\log d})$. Applying Lemma C.3a and Lemma C.3b we immediately have

- If $\mathcal{S}_{ept}^{(t)} = [m]$, then $\Pr_x \left[\left| \langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq e^{-\Omega(\log^{1/4} d)}$;
- If $\mathcal{S}_{ept+}^{(t)} = [m]$, then $\Pr_x \left[\left| \langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq O\left(\frac{k}{d}\right)$.

Now, recall $x = \sum_{j' \in [d]} \mathbf{M}_{j'} z_{j'} + \xi$ so it differs from $\sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi$ only by one term. Therefore, we have the same bound on $\Pr_x \left[\left| \langle w_i^{(t)}, x \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right]$ by modifying the statements of Lemma C.3a and Lemma C.3b (without changing the proofs) to include this missing term.

- If $\mathcal{S}_{ept}^{(t)} = [m]$, $\Pr_{x,\rho} \left[\left| \langle w_i^{(t)}, x \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq e^{-\Omega(\log^{1/4} d)}$
- If $\mathcal{S}_{ept+}^{(t)} = [m]$, $\Pr_{x,\rho} \left[\left| \langle w_i^{(t)}, x \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq O\left(\frac{k}{d}\right)$

At the same time, using $\rho_i \sim \mathcal{N}(0, (\sigma_\rho^{(t)})^2)$, we also have

- In Phase I.1, because $\sigma_\rho^{(t)} = \Theta\left(\frac{\sigma_w^{(t)} (\log \log \log d)^3}{\sqrt{\log d}}\right) b^{(t)}$, we have $\Pr_\rho \left[\left| \rho_i \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \ll e^{-\Omega(\log^{1/4} d)}$
- In Phase I.2, because $\sigma_\rho^{(t)} = \Theta\left(\frac{\sigma_w^{(t)} (\log \log \log d)^3}{\log d}\right) b^{(t)}$, we have $\Pr_\rho \left[\left| \rho_i \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \ll O\left(\frac{k}{d}\right)$

As for the bound on $\Gamma_{t,y}$, for every $i \in [m]$, $j \in [d]$, let $\Lambda \subseteq [d] \setminus \{j\}$ be the subset containing all $j' \in [d] \setminus \{j\}$ with $|\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle| \leq q \stackrel{\text{def}}{=} \frac{\sigma_w^{(t)}}{\log d}$. By the assumption $\mathcal{S}_{ept}^{(t)} = [m]$, we know $|\Lambda| \geq \Omega(d/\log d)$.

Since $|\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle| \leq q$, $\mathbb{E}[z_j^2] = \Theta(1/d)$ and $|z_j| \leq 1$, by Bernstein's inequality, we have

$$\Pr_x \left[\left| \langle w_i^{(t)}, \sum_{j' \in \Lambda} \mathbf{M}_{j'} z_{j'} \rangle \right| \geq \frac{c_2}{10c_1} b^{(t)} \right] \leq e^{-\Omega\left(\frac{(b^{(t)})^2}{q^2 |\Lambda| / d + q \cdot b^{(t)}}\right)} \leq e^{-\Omega(\log^{1.5} d)}. \quad \square$$

C.3.2 Growth Lemmas

Our first lemma here shall be used to (lower) bound how $\langle w_i^{(t)}, \mathbf{M}_j \rangle$ (i.e., the weight with respect to neuron i in direction \mathbf{M}_j) grows for those $i \in \mathcal{S}_{j,sure}$.

Lemma C.6 (signal growth). *Suppose we (1) either are in Phase I.1 with $\mathcal{S}_{ept}^{(t)} = [m]$, (2) or are in Phase I.2 with $\mathcal{S}_{ept+}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \in \mathcal{S}_{j,sure}^{(t)}$, as long as $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| = O(b^{(t)} \log \log d)$, the following holds:*

$$\mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \right] = \Theta\left(\frac{1}{d}\right)$$

Proof of Lemma C.6. Recall that $i \in \mathcal{S}_{j, \text{sure}}^{(t)}$ means $\text{sign}(\langle w_i^{(t)}, \mathbf{M}_j \rangle) = \text{sign}(w_j^*)$. Without loss of generality, let us assume $\text{sign}(\langle w_i^{(t)}, \mathbf{M}_j \rangle) = \text{sign}(w_j^*) = 1$.

First consider the case when $|z_j| = 1$. Since $j \in \mathcal{S}_{j, \text{sure}}^{(t)}$, we have $\langle w_i^{(t)}, \mathbf{M}_j \rangle \geq b^{(t)} \sqrt{1 + \frac{c_2}{c_1}}$ so applying Lemma C.5,

$$\begin{aligned} \Pr[\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \mid z_j = 1] &\geq 1 - 2\Gamma_t = 1 - o(1) \\ \Pr[\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \mid z_j = -1] &\leq 2\Gamma_t = o(1) \end{aligned}$$

Moreover, a simple calculation using $|w_j^*| = \Theta(1)$ gives us $\mathbb{E}_{x,y}[y \mid z_j = 1] = \Theta(1)$ (can be proven by Lemma H.1) and therefore

$$\mathbb{E}_{x,y,\rho} \left[y \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \mid |z_j| = 1 \right] = \Theta(1)$$

For all other non-zero value $|z_j| = s > 0$, we have $s \geq \frac{1}{\sqrt{k}}$ and wish to apply Lemma C.4 to bound

$$\Delta_s := \mathbb{E}_{x,y,\rho} \left[y \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \text{sign}(z_j)} \mid |z_j| = s \right]$$

In Phase I.1, to apply Lemma C.4, we choose parameters as follows:

- $Y = y$, $S_1 = \sum_{j' \neq j} w_{j'}^* z_{j'}$, $S_2 = \langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \rangle$, $\alpha = \langle w_i^{(t)}, \mathbf{M}_j \rangle \cdot s > 0$, $\rho = \rho_i$,
- $V = \mathbb{E}[S_2^2] = O((\sigma_w^{(t)})^2)$, $L = \Theta(s)$ (using Lemma H.1), $\Gamma = \Gamma_t$ (using Lemma C.5),
- let Λ be the subset defined in Lemma C.5, then we can let $S_1'' = (z_j)_{j \in \Lambda}$ and $S_2'' = \langle w_i^{(t)}, \sum_{j' \in \Lambda} \mathbf{M}_{j'} z_{j'} \rangle$
- we have $\Gamma_y = \Gamma_{t,y} = \frac{1}{d^{10}}$ (from Lemma C.5) and

$$\begin{aligned} L_y &= \max_{z_{j'} \text{ for } j' \in [d] \setminus \{j\} \setminus \Lambda} \left\{ \mathbb{E}_{z_{j'} \text{ for } j' \in \Lambda} [\text{sign}(w_j^* z_j + S_1) - \text{sign}(S_1)] \right\} \\ &\leq \max_{z_{j'} \text{ for } j' \in [d] \setminus \{j\} \setminus \Lambda} \left\{ \Pr_{z_{j'} \text{ for } j' \in \Lambda} [S_1'' \in [-S_1' - |w_j^* z_j|, -S_1' + |w_j^* z_j|]] \right\} \\ &\stackrel{\textcircled{1}}{\leq} O\left(\frac{s}{\sqrt{|\Lambda|/d}} + \frac{1}{\sqrt{|\Lambda|k/d}}\right) \leq O\left(s + \frac{1}{\sqrt{k}}\right) \sqrt{\log d} \leq O(s \cdot \sqrt{\log d}) \end{aligned}$$

where inequality $\textcircled{1}$ uses Lemma H.1a and $|\Lambda| \geq \Omega(\frac{d}{\log d})$ from Lemma C.5.

Hence, invoking Lemma C.4, we have

- $\Delta_s \geq -\frac{\sigma_w^{(t)}}{\sigma_\rho^{(t)}} \geq -\frac{O(1)}{(\log \log \log d)^3}$ and $|\Delta_s| \leq \frac{\sigma_w^{(t)}}{\sigma_\rho^{(t)}} + s \leq \frac{O(1)}{(\log \log \log d)^3} + s$ when $s = \Omega\left(\frac{1}{\log \log \log d}\right)$
- $|\Delta_s| \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma_t\right) \left(O\left(\frac{\alpha}{\sigma_\rho}\right) + L_y\right) + \Gamma_{t,y} \leq e^{-\Omega(\log^{1/4} d)} \cdot s$ when $s = O\left(\frac{1}{\log \log \log d}\right)$ (which implies $\alpha < \frac{b^{(t)}}{4}$)

Notice that $\mathbb{E}[z_j^2] = O(1/d)$, which implies that

$$\Pr \left[|z_j| = \Omega\left(\frac{1}{\log \log \log d}\right) \right] = O\left(\frac{(\log \log \log d)^2}{d}\right)$$

This together gives us the bound that

$$-O\left(\frac{1}{d \cdot \log \log \log d}\right) \leq \mathbb{E}_{x,y,\rho} \left[y \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \mid |z_j| < 1 \right] \leq O\left(\frac{1}{d}\right)$$

In Phase I.2, the analysis is similar with different parameters: in particular,

- $V = \mathbb{E}[S_2^2] = O\left(\frac{(\sigma_w^{(t)})^2}{\log d}\right)$ which is tighter,

Therefore, we have

- $\Delta_s \geq -\frac{\sigma_w^{(t)}}{\sigma_\rho^{(t)}\sqrt{\log d}} \geq -\frac{O(1)}{(\log \log \log d)^3}$ and $|\Delta_s| \leq \frac{\sigma_w^{(t)}}{\sigma_\rho^{(t)}\sqrt{\log d}} + s \leq \frac{O(1)}{(\log \log \log d)^3} + s$ when $s = \Omega\left(\frac{1}{\log \log \log d}\right)$
 - $|\Delta_s| \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma_t\right) \left(O\left(\frac{\alpha}{\sigma_\rho}\right) + L_y\right) + \Gamma_{t,y} \leq O\left(\frac{ks \log d}{d}\right)$ when $s = O\left(\frac{1}{\log \log \log d}\right)$ (which implies $\alpha < \frac{b^{(t)}}{4}$).
- (This uses $\Gamma_t = O(k/d)$ and $\frac{\alpha}{\sigma_\rho} \leq o(s \log d)$.)

Taking expectation over z_j as before, and using $k < d^{(1-c_0)/2}$ finishes the proof. \square

Our next lemma shall be used to upper bound how $\langle w_i^{(t)}, \mathbf{M}_j \rangle$ can grow for every $i \in [m]$.

Lemma C.7 (maximum growth). *Suppose we (1) either are in Phase I.1 with $\mathcal{S}_{ept}^{(t)} = [m]$, (2) or are in Phase I.2 with $\mathcal{S}_{ept+}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \in [m]$, the following holds:*

$$\left| \mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \right] \right| = O\left(\frac{1}{d}\right).$$

Proof. Proof is analogous to that of Lemma C.6, and the reason we no longer need the requirement $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| = O(b^{(t)} \log \log \log d)$ is because, when invoking Lemma C.4, it suffices for us to apply Lemma C.4a for every non-zero values of z (as opposed to only those $z = \Omega\left(\frac{1}{\log \log \log d}\right)$) which no longer requires $\alpha \leq b$. \square

Our next lemma shall be used to upper bound how $\langle w_i^{(t)}, \mathbf{M}_j \rangle$ can grow for every $i \in [m] \setminus \mathcal{S}_{j,pot}^{(t)}$.

Lemma C.8 (non-signal growth). *Suppose we (1) either are in Phase I.1 with $\mathcal{S}_{ept}^{(t)} = [m]$, (2) or are in Phase I.2 with $\mathcal{S}_{ept+}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \in [m] \setminus \mathcal{S}_{j,pot}^{(t)}$, the following holds:*

$$\left| \mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \right] \right| = O\left(\frac{\Gamma_t \cdot \log d}{d}\right)$$

where Γ_t is given from Lemma C.5.

Proof of Lemma C.8. Suppose $|z_j| = s$ and without loss of generality $\langle w_i^{(t)}, \mathbf{M}_j \rangle \geq 0$. We choose $\alpha = \langle w_i^{(t)}, \mathbf{M}_j \rangle \cdot s$ as before. Then, we have $\alpha \leq \sqrt{c_1 - c_2} \sigma_w^{(t)} \sqrt{\log d} = b^{(t)} \sqrt{1 - \frac{c_2}{c_1}} \leq b^{(t)} \left(1 - \frac{c_2}{2c_1}\right)$ always holds.

Therefore, using the same notation as the proof of Lemma C.6, we always have the bound

$$|\Delta_s| \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma_t\right) \left(O\left(\frac{\alpha}{\sigma_\rho}\right) + L_y\right) + \Gamma_{t,y}$$

Plugging in the parameters we finish the proof. \square

Our final lemma shall be used to upper bound how $\langle w_i^{(t)}, \mathbf{M}_j \rangle$ can grow with respect to the noise ξ in the input.

Lemma C.9 (noise growth). *For every $i \in [m]$, every $j \in [d]$, the following holds:*

$$\left| \mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] \right| = O\left(\Gamma_t \frac{\sigma_x^2}{d \sigma_\rho^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle|\right)$$

Proof of Lemma C.9. We can define $\alpha = |\langle \mathbf{M}_j, \xi \rangle|$ and study

$$\Delta_s := \mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \text{sign}(\langle \xi, \mathbf{M}_j \rangle) \mid |\langle \xi, \mathbf{M}_j \rangle| = \alpha \right] \quad (\text{C.8})$$

This time we have $L = L_y = 0$, $\Gamma_y = 0$, $V = \mathbb{E}[S_2^2] = O((\sigma_w^{(t)})^2)$, so applying Lemma C.4 we have,

- when $\alpha \leq b^{(t)}/4$, $|\Delta_s| \leq \frac{|\langle w_i^{(t)}, \mathbf{M}_j \rangle| |\langle \mathbf{M}_j, \xi \rangle|}{\|\mathbf{M}_j\|_2 \sigma_\rho^{(t)}} \cdot \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma_t \right)$;
- when $\alpha > b^{(t)}/4$ (which happens with exponentially small prob.), $|\Delta_s| \leq O\left(\frac{\sigma_w^{(t)}}{\sigma_\rho}\right)$.

Together, using the fact that $\mathbb{E}[|\Delta_s|] \leq \sqrt{\mathbb{E}[\Delta_s^2]}$ we have:

$$\left| \mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] \right| = O\left(\Gamma_t \frac{\sigma_x^2}{d \sigma_\rho^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \right)$$

□

C.3.3 Proof of Theorem C.1

Suppose in Lemma C.6 the hidden constant is $20C$ for the lower bound, that is,

$$\mathbb{E}_{x,y,\rho} \left[y \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] \geq \frac{20C}{d}$$

Proof of Theorem C.1. Let us prove by induction with respect to t . Suppose the properties all hold at $t = 0$. Recall from Fact A.1, for iteration t , for every neuron $i \in [m]$,

$$\nabla_{w_i} \mathbf{Loss}_t(w^{(t)}; x, y, \rho) = -y \ell'_t(w^{(t)}; x, y, \rho) \left(\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \cdot x \ .$$

Using the bound on $\|w_i^{(t)}\|_2$ (from $\mathcal{S}_{ept}^{(t)} = [m]$) and the fact $\sigma_0 \leq \frac{1}{\text{poly}(d)}$, we know $\ell'_t(w^{(t)}; x, y, \rho) = \frac{1}{2} \pm \frac{1}{\text{poly}(d)}$. Also, recall also from Lemma A.2 that

$$\mathbb{E}_{x \sim \mathcal{D}, y=y(x), \rho} \left[\nabla_{w_i} \mathbf{Loss}_t(w^{(t)}; x, y, \rho) \right] = \nabla_{w_i} \widetilde{\mathbf{Loss}}_t(w^{(t)}) \pm \frac{1}{\text{poly}(d)} \ .$$

Together, we have a clean formulation for our gradient update rule:

$$w_i^{(t+1)} = w_i^{(t)} (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) + \mathbb{E}_{x,y=y(x), \rho} \left[y \left(\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \cdot x \right] \pm \frac{\eta}{\text{poly}(d)} \ .$$

and as a result for every $j \in [d]$

$$\begin{aligned} \langle w_i^{(t+1)}, \mathbf{M}_j \rangle &= \langle w_i^{(t)}, \mathbf{M}_j \rangle (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) \pm \frac{\eta}{\text{poly}(d)} \\ &\quad + \mathbb{E}_{x,y=y(x), \rho} \left[y \left(\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \cdot (z_j + \langle \xi, \mathbf{M}_j \rangle) \right] \ . \end{aligned} \quad (\text{C.9})$$

We now prove each statement separately (and note our proofs apply both to Phase I.1 and I.2).

1. For every $i \notin \mathcal{S}_{j,pot}^{(t)}$, by substituting Lemma C.8 and Lemma C.9 into (C.9), we have

$$\langle w_i^{(t+1)} - w_i^{(t)}, \mathbf{M}_j \rangle \leq \frac{\eta \cdot e^{-\Omega(\log^{1/4} d)}}{d} \ll \sqrt{c_1 - c_2} (\sigma_w^{(t+1)} - \sigma_w^{(t)}) \sqrt{\log d} \quad (\text{C.10})$$

so we also have $\langle w_i^{(t+1)}, \mathbf{M}_j \rangle < \sqrt{c_1 - c_2} \sigma_w^{(t+1)} \sqrt{\log d}$ and thus $i \notin \mathcal{S}_{j,pot}^{(t+1)}$.

2. For every $i \in \mathcal{S}_{j, \text{sure}}^{(t)}$, suppose $\text{wlog } \langle w_i^{(t)}, \mathbf{M}_j \rangle$ is positive. Then, either $\langle w_i^{(t)}, \mathbf{M}_j \rangle > \Omega(b^{(t)} \log \log \log d)$ in such a case we still have $\langle w_i^{(t+1)}, \mathbf{M}_j \rangle \geq \sqrt{c_1 + c_2 \sigma_w^{(t+1)}} \sqrt{\log d}$. Otherwise, if $\langle w_i^{(t)}, \mathbf{M}_j \rangle \leq \Omega(b^{(t)} \log \log \log d)$ then by substituting Lemma C.6 and Lemma C.9 into (C.9), we have (using $\sigma_0 \leq \frac{1}{\text{poly}(d)}$ and $\lambda \leq \frac{\log d}{d}$)

$$\langle w_i^{(t+1)}, \mathbf{M}_j \rangle \geq (1 - \eta\lambda) \langle w_i^{(t)}, \mathbf{M}_j \rangle + \frac{20C\eta}{d} \geq \langle w_i^{(t)}, \mathbf{M}_j \rangle + \sqrt{c_1 + c_2} (\sigma_w^{(t+1)} - \sigma_w^{(t)}) \sqrt{\log d}$$

so by induction we also have $\langle w_i^{(t+1)}, \mathbf{M}_j \rangle \geq \sqrt{c_1 + c_2} \sigma_w^{(t+1)} \sqrt{\log d}$. Combining this with $\mathcal{S}_{j, \text{pot}}^{(0)} \supseteq \mathcal{S}_{j, \text{pot}}^{(t+1)}$, we conclude that $i \in \mathcal{S}_{j, \text{sure}}^{(t+1)}$.

3. To check $\mathcal{S}_{\text{ept}}^{(t+1)} = [m]$, we need to verify four things:

- $\langle w_i^{(t)}, \mathbf{M}_j \rangle^2 \geq (c_1 - c_2) (\sigma_w^{(t)})^2 \log d$ for at most $O(1)$ many $j \in [d]$.
This is so because $\mathcal{S}_{\text{ept}}^{(0)} = [m]$ and $\mathcal{S}_{j, \text{pot}}^{(0)} \supseteq \mathcal{S}_{j, \text{pot}}^{(t+1)}$.
- $\langle w_i^{(t+1)}, \mathbf{M}_j \rangle^2 \geq 2(\sigma_w^{(t+1)})^2 \sqrt{\log d}$ for at most $2^{-\sqrt{\log d}} d$ many $j \in [d]$.
This can be derived from (C.10) in the same way.
- $|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq \frac{\sigma_w^{(t+1)}}{\log d}$ for at least $\Omega(\frac{d}{\log d})$ many $j \in [d]$.
This can be derived from (C.10) in the same way.
- $\|w_i^{(t)}\|_2^2 \leq 2(\sigma_w^{(t)})^2 d$

For every $i \in [m]$, suppose $\text{wlog } \langle w_i^{(t)}, \mathbf{M}_j \rangle$ is positive. Then, by substituting Lemma C.7 and Lemma C.9 into (C.9), we have

$$\langle w_i^{(t+1)} - w_i^{(t)}, \mathbf{M}_j \rangle \leq O\left(\frac{\eta}{d}\right)$$

Applying this formula for $t + 1$ times, we derive that

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq O\left(\frac{\eta(t+1)}{d}\right) + |\langle w_i^{(0)}, \mathbf{M}_j \rangle| \quad (\text{C.11})$$

and therefore applying this together with (C.10),

$$\begin{aligned} \|w_i^{(t+1)}\|_2^2 &= \sum_{j: i \in \mathcal{S}_{j, \text{pot}}^{(0)}} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle|^2 + \sum_{j: i \notin \mathcal{S}_{j, \text{pot}}^{(0)}} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle|^2 \\ &\stackrel{\textcircled{1}}{\leq} 1.5 \|w_i^{(0)}\|_2^2 + O(1) \cdot \left(\frac{\eta(t+1)}{d}\right)^2 + d \cdot \left(\frac{\eta(t+1)}{d}\right)^2 \cdot e^{-\Omega(\log^{1/4} d)} \leq 2(\sigma_w^{(t+1)})^2 d \end{aligned}$$

(Above, inequality $\textcircled{1}$ uses that there are at most $O(1)$ indices $j \in [d]$ such that $i \in \mathcal{S}_{j, \text{pot}}^{(0)}$.)

4. Finally, to check $\mathcal{S}_{\text{ept}+}^{(t+1)} = [m]$ for $t \geq T_a = \Theta(\frac{d\sigma_0 \log^{2.5} d}{\eta})$, we first derive that

$$\sigma_w^{(t+1)} = \sigma_0 + \Theta\left(\frac{\eta}{d\sqrt{\log d}}\right) \cdot (t+1) \geq \sigma_0 \cdot \Omega(\log^2 d) .$$

- For every $i \notin \mathcal{S}_{j, \text{pot}}^{(t+1)}$, (C.10) gives

$$\begin{aligned} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| &\leq |\langle w_i^{(0)}, \mathbf{M}_j \rangle| + \frac{e^{-\Omega(\log^{1/4} d)}}{d} \cdot \eta(t+1) \\ &\leq O(\sigma_0 \sqrt{\log d}) + \frac{e^{-\Omega(\log^{1/4} d)}}{d} \cdot \eta(t+1) \leq O\left(\frac{\sigma_w^{(t+1)}}{\log^{1.5} d}\right) \end{aligned}$$

In particular, this together with $\mathcal{S}_{ept}^{(0)} = [m]$ ensures that for every $i \in [m]$, $|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \geq \frac{\sigma_w^{(t+1)}}{\log d}$ for at most $O(1)$ many $j \in [d]$.

- For any $i \in \mathcal{S}_{j,pot}^{(0)}$, using (C.11) we have

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq |\langle w_i^{(0)}, \mathbf{M}_j \rangle| + O\left(\frac{\eta(t+1)}{d}\right) \leq O(\sigma_0 \sqrt{\log d}) + O\left(\frac{\eta(t+1)}{d}\right) = \Theta(\sigma_w^{(t+1)} \sqrt{\log d}) \quad (\text{C.12})$$

Using this together with the previous item, as well as $|\mathcal{S}_{j,pot}^{(0)}| \leq O(1)$, we have $\|w_i^{(t+1)}\|^2 \leq O\left(\frac{(\sigma_w^{(t+1)})^2 d}{\log^3 d}\right)$.

Putting them together we have $\mathcal{S}_{ept+}^{(t+1)} = [m]$ for every $t \geq T_a$.

5. After $t = T_b$ iterations, we have $\sigma_w^{(t)} = \Theta(\sigma_0 + \frac{\eta}{d\sqrt{\log d}} \cdot T_b)$, for every $i \notin \mathcal{S}_{j,pot}^{(0)}$, by Lemma C.8 and Lemma C.9

$$|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq |\langle w_i^{(T_a)}, \mathbf{M}_j \rangle| + \frac{O(k/d) \cdot \sqrt{\log d}}{d} \cdot \eta(T_b - T_a) \leq O(\sigma_w^{(t)} \cdot \frac{k \log d}{d})$$

Combining this with (C.11), we immediately have

$$\begin{aligned} \|w_i^{(t)}\|^2 &= \sum_{j: i \in \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle|^2 + \sum_{j: i \notin \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle|^2 \\ &\leq (\sigma_w^{(t)})^2 \cdot O\left(\frac{k^2 \log^2 d}{d} + \log d\right) \end{aligned}$$

This implies $\mathcal{S}_{ept++}^{(t)} = [m]$ and $\mathcal{S}_{j,pot}^{(0)} \supseteq \mathcal{S}_{j,pot+}^{(t)}$ at this iteration t . □

C.4 Phase II: Signal Growth After Winning Lottery

In phase II we make the following parameter choices.

- In Phase II, we pick $b^{(t)} = \sqrt{c_1} \sigma_w^{(t)} \sqrt{\log d}$ and $\sigma_\rho^{(t)} = \sigma_w^{(t)} \cdot \frac{(\log \log \log d)^3}{\sqrt{\log d}}$

We grow $b^{(t+1)} = b^{(t)} + \frac{C\eta}{d}$ as before for each iteration, but stop growing $b^{(t)}$ when it reaches a threshold $b^{(t)} = \beta \Xi_2^2$.

We first introduce a notation on a (high-probability) version of the coordinate Lipschitz continuity.

Definition C.10 (coordinate Lipschitzness). *At every iteration t , for every $j \in [d]$, we define $L_{t,j} > e^{-\Omega(\log^2 d)}$ to be the smallest value such that w.p. at least $1 - e^{-\Omega(\log^2 d)}$ over the choice of $\{z_{j'}\}_{j' \neq j}$ and ξ , for every $z \in [-1, 1]$ and $z = (z_1, \dots, z_{j-1}, z, z_{j+1}, \dots, z_d)$, $z' = (z_1, \dots, z_{j-1}, 0, z_{j+1}, \dots, z_d)$, $x = \mathbf{M}z + \xi$ and $x' = \mathbf{M}z' + \xi$:*

$$|f_t(x) - f_t(x')| \leq L_{t,j} |z|.$$

C.4.1 Growth Lemmas

In this subsection, we provide new growth lemmas Lemma C.11, Lemma C.12, Lemma C.13, Lemma C.14 that are specific to Phase II, to replace the user of the old growth lemmas Lemma C.6, Lemma C.7, Lemma C.8, Lemma C.9 from Phase I.

Lemma C.11 (signal growth II). *Suppose we $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \in \mathcal{S}_{j, \text{sure}}^{(t)}$, the following holds:*

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \right] = \Theta \left(\frac{1}{d} \right) \pm O \left(\frac{L_{t,j}}{d} + \frac{\sqrt{k} \sigma_\rho^{(t)} \log d}{d} + \frac{\sqrt{k}}{\beta d^{3/2}} \right)$$

Proof of Lemma C.11. First, without loss of generality, assuming that $\text{sign}(\langle w_i^{(t)}, \mathbf{M}_j \rangle) = \text{sign}(w_j^*) = 1$. Let us define $z' = (z_1, \dots, z_{j-1}, 0, z_{j+1}, \dots, z_d)$ and $x' = \mathbf{M}z' + \xi$. Define

$$\begin{aligned} f_{t,i}(w^{(t)}; x, \rho) &\stackrel{\text{def}}{=} \sum_{j \neq i} \left(\text{ReLU}(\langle w_j^{(t)}, x \rangle + \rho_j + b_j^{(t)}) - \text{ReLU}(-\langle w_j^{(t)}, x \rangle + \rho_j + b_j^{(t)}) \right) \\ &\quad + \left(\text{ReLU}(\langle w_i^{(t)}, x \rangle + b_i^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x \rangle + b_i^{(t)}) \right) \\ \ell'_{t,i}(w^{(t)}; x, y, \rho) &\stackrel{\text{def}}{=} \frac{d}{ds} [\log(1 + e^s)] \Big|_{s=-y f_{t,i}(w^{(t)}; x, \rho)} \end{aligned}$$

Now, since $\frac{e^s}{1+e^s}$ is an $O(1)$ -Lipschitz function in s , we know that w.p. at least $1 - e^{-\Omega(\log^2 d)}$

$$|\ell'_t(w^{(t)}; x, y, \rho) - \ell'_{t,i}(w^{(t)}; x', y, \rho)| = O(L_{t,j} \cdot |z_j| + \sigma_\rho^{(t)} \log d)$$

and this implies that

$$\begin{aligned} &\left| \mathbb{E}_{x,y,\rho} \left[y (\ell'_t(w^{(t)}; x, y, \rho) - \ell'_{t,i}(w^{(t)}; x', y, \rho)) \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \right] \right| \\ &\leq O \left(L_{t,j} \mathbb{E}[z_j^2] + \sigma_\rho^{(t)} \log d \cdot \mathbb{E}[|z_j|] \right) + e^{-\Omega(\log^2 d)} \\ &= O \left(\frac{L_{t,j}}{d} + \frac{\sigma_\rho^{(t)} \log d \cdot \sqrt{k}}{d} \right) + e^{-\Omega(\log^2 d)} \end{aligned}$$

so we only need to bound $\mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \right]$.

Let us first focus on the case that $|z_j| = 1$. As before, since $j \in \mathcal{S}_{j, \text{sure}}^{(t)}$, we have $\langle w_i^{(t)}, \mathbf{M}_j \rangle \geq b^{(t)} \sqrt{1 + \frac{c_2}{c_1}}$ so applying Lemma C.5,

$$\begin{aligned} \Pr[\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \mid z_j = 1] &\geq 1 - 2\Gamma_t = 1 - o(1) \\ \Pr[\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \mid z_j = -1] &\leq 2\Gamma_t = o(1) \end{aligned}$$

This means

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} z_j} \mid |z_j| = 1 \right] \geq \frac{1}{2} \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mid z_j = 1 \right] - o(1)$$

Now recall $y(z_j, z) = \text{sign}(w_j^* z_j + \langle w^*, z \rangle)$.

- When $|\langle w^*, z \rangle| > |w_j^*|$, then we know that $y(z_j, z)$ and $y(z_j, -z)$ have different signs, but $\ell'_{t,i}(w^{(t)}; x', y, \rho) = \ell'_{t,i}(w^{(t)}; -x', -y, \rho)$ remains the same if we flip z to $-z$. By symmetry, we have

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mid z_j = 1 \wedge |\langle w^*, z \rangle| > |w_j^*| \right] = 0$$

- Suppose otherwise $|\langle w^*, z \rangle| \leq |w_j^*|$. Since $|w_j^*| = \Theta(1)$, by Lemma H.1, this event happens with at least constant probability. When it happens, we have $y(z_j, z) = y(z_j, -z) = +1$, but

$\ell'_{t,i}(w^{(t)}; x', y, \rho) + \ell'_{t,i}(w^{(t)}; -x', y, \rho) = 1$. Therefore,

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbf{1}_{z_j = 1 \wedge |\langle w^*, z \rangle| \leq |w_j^*|} \right] \geq \frac{1}{2}$$

Together, we have

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \mid |z_j| = 1 \right] = \Omega(1) \quad (\text{C.13})$$

Next, conditioning on $|z_j| = s$ for some $0 < s < 1$, we can apply Lemma C.4 with $Y = y \ell'_{t,i}(w^{(t)}; x', y, \rho)$ on $s = \text{sign}(z_j)$, $\alpha = \langle w_i^{(t)}, \mathbf{M}_j \rangle z_j$, $S_1 = z$, $S_2 = \sum_{j' \neq j} \langle w_i^{(t)}, \mathbf{M}_{j'} \rangle z_{j'}$ and $\rho = \rho_i$. Since $\ell'_{t,i}(w^{(t)}; x', y, \rho) \geq 0$, we can conclude that Y is a monotone non-decreasing function of α . One can verify that $L = O(s)$ using Lemma H.1. Moreover, since $i \in \mathcal{S}_{ept++}^{(t)}$, we have $\frac{\mathbb{E}[S_2^2]}{(\sigma_\rho^{(t)})^2} \leq \frac{1}{d\beta^2}$.

Let us denote by

$$\Delta_s := \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \text{sign}(z_j) \mid |z_j| = s \right]$$

so according to Lemma C.4 we have

$$\Omega \left(\frac{1}{\beta \sqrt{d}} \right) \leq \Delta_s = O \left(\frac{1}{\beta \sqrt{d}} + s \right)$$

This implies, using $\mathbb{E}[|z_j|] \leq \frac{\sqrt{k}}{d}$, that

$$\begin{aligned} \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \cdot \mathbf{1}_{|z_j| < 1} \right] &\leq \mathbb{E}[\Delta_{z_j} \cdot |z_j| \cdot \mathbf{1}_{|z_j| < 1}] \leq O \left(\frac{\mathbb{E}[|z_j|]}{\beta \sqrt{d}} + \frac{1}{d} \right) \leq O \left(\frac{\sqrt{k}}{\beta d^{1.5}} + \frac{1}{d} \right) \\ \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x', y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \cdot \mathbf{1}_{|z_j| < 1} \right] &\geq \mathbb{E}[\Delta_{z_j} |z_j| \cdot \mathbf{1}_{|z_j| < 1}] \geq -\Omega \left(\frac{\mathbb{E}[|z_j|]}{\beta \sqrt{d}} \right) \geq -\Omega \left(\frac{\sqrt{k}}{\beta d^{1.5}} \right) \end{aligned}$$

Combining this with (C.13), and using $\Pr[|z_j| = 1] \geq \Omega(1/d)$ finishes the proof. \square

Similarly, we have the following Lemma

Lemma C.12 (maximum growth II). *Suppose we $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \in [m]$, the following holds:*

$$\left| \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] \right| = O \left(\frac{1 + L_{t,j}}{d} + \frac{\sqrt{k} \sigma_\rho^{(t)} \log d}{d} + \frac{\sqrt{k}}{\beta d^{3/2}} \right)$$

Lemma C.13 (non-signal growth II). *Suppose we $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \notin \mathcal{S}_{j,pot}^{(t)}$ and $i \in [m]$, the following holds:*

$$\left| \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] \right| \leq \Gamma_t \cdot O \left(\frac{\log d + L_{t,j}}{d} + \frac{\sqrt{k} \sigma_\rho^{(t)} \log d}{d} \right)$$

Proof of Lemma C.13. In the same notation as the proof of Lemma C.11, we have

$$\begin{aligned} &\left| \mathbb{E}_{x,y,\rho} \left[y (\ell'_{t,i}(w^{(t)}; x, y, \rho) - \ell'_{t,i}(x', y)) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] \right| \\ &\leq O \left(L_{t,j} \mathbb{E}[z_j^2 \cdot \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}] + \sigma_\rho^{(t)} \log d \cdot \mathbb{E}[|z_j| \cdot \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}] \right) + e^{-\Omega(\log^2 d)} \\ &\leq \Gamma_t O \left(\frac{L_{t,j}}{d} + \frac{\sigma_\rho^{(t)} \log d \cdot \sqrt{k}}{d} \right) + e^{-\Omega(\log^2 d)} \end{aligned}$$

where the last inequality uses Lemma C.5 and the fact $i \notin \mathcal{S}_{j,pot}^{(t)}$ (which, as before, implies if we choose $\alpha = \langle w_i^{(t)}, \mathbf{M}_j \rangle \cdot z$ then $\alpha^2 \leq (c_1 - c_2)(\sigma_w^{(t)})^2 \log d \leq (\frac{b^{(t)}}{4})^2$).

Thus, we only need to bound

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(x', y) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right].$$

Conditioning on $|z_j| = s$ for some $0 < s \leq 1$, we can apply Lemma C.4 again with $Y = y \ell'_{t,i}(x', y)$ on $s = \text{sign}(z_j)$, $\alpha = \langle w_i^{(t)}, \mathbf{M}_j \rangle z_j$, $S_1 = z$, $S_2 = \sum_{j' \neq j} \langle w_i^{(t)}, \mathbf{M}_{j'} \rangle z_{j'}$ and $\rho = \rho_i$. This time, we use $\Gamma_y = \frac{1}{d^{10}}$ and $L_y \leq O(z \cdot \log^{1/4} d)$. Define

$$\Delta_s := \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(x', y) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \text{sign}(z_j) \mid |z_j| = s \right]$$

Since $\alpha < \frac{b^{(t)}}{4}$, Lemma C.4 tells us

$$|\Delta_s| \leq \left(e^{-\Omega(b^2/\sigma_\rho^2)} + \Gamma_t \right) \left(O\left(\frac{\alpha}{\sigma_\rho}\right) + L_y \right) + \Gamma_y \leq O(\Gamma_t \log d) \cdot z$$

and therefore

$$\left| \mathbb{E}_{x,y,\rho} \left[y \ell'_{t,i}(x', y) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] \right| = |\mathbb{E}[\Delta_{z_j} | z_j]| \leq O(\Gamma_t \log d) \cdot \mathbb{E}[z_j^2] = O\left(\frac{\Gamma_t \log d}{d}\right)$$

Combining this with (C.13), and using $\Pr[|z_j| = 1] \geq \Omega(1/d)$ finishes the proof. \square

Finally, we derive a more fine-grind bound for the noise:

Lemma C.14 (noise growth II). *Suppose we $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$. Then, for every $j \in [d]$,*

(a) *for every $j \in [d]$,*

$$\left| \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] \right| = O\left(\frac{\Gamma_t}{d \sigma_\rho^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \sigma_x^2 + \frac{\Gamma_t L_{t,j} \sigma_x^2}{d} + e^{-\Omega(\log^2 d)} \right)$$

(b) *suppose also $\mathcal{S}_{j,pot}^{(0)} \supseteq \mathcal{S}_{j,pot+}^{(t)}$ for every $j \in [d]$, then*

$$\sum_{j \in [d]} \left| \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] \right| \leq O\left(\frac{k^3 \Xi_2^4}{d^2} \sigma_x^2 + e^{-\Omega(\log^2 d)} \right)$$

Proof of Lemma C.14. We can first decompose the noise ξ into

$$\xi = (\mathbf{I} - \mathbf{M}_j \mathbf{M}_j^\top) \xi + \langle \mathbf{M}_j, \xi \rangle \mathbf{M}_j =: \xi'_j + \langle \mathbf{M}_j, \xi \rangle \mathbf{M}_j.$$

Let us define $x'_j = \mathbf{M}z + \xi'_j$.

- On one hand we have with probability at least $1 - \Gamma_t$, $|\langle w_i^{(t)}, x'_j \rangle| \leq \frac{b^{(t)}}{10}$ (using a variant of Lemma C.5). Using the randomness of $\langle \xi, \mathbf{M}_j \rangle$ and ρ_i we also have with probability at least $1 - e^{-\Omega(\log^2 d)}$ it satisfies $|\langle w_i^{(t)}, \mathbf{M}_j \rangle \cdot \langle \mathbf{M}_j, \xi \rangle| + |\rho_i| \leq \frac{b^{(t)}}{10}$. Therefore, with probability at least $1 - \Gamma_t - e^{-\Omega(\log^2 d)}$, we have $\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} = \mathbf{1}_{\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}}$.
- Otherwise, in the event that $|\langle w_i^{(t)}, x'_j \rangle| \geq \frac{b^{(t)}}{10}$, using the randomness of ρ_i , we have that

$$\Pr_{\rho_i} \left[\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \neq \mathbf{1}_{\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}} \right] \leq O\left(\frac{\mathbb{E} \left[\left| \langle \xi, \mathbf{M}_j \rangle \langle w_i^{(t)}, \mathbf{M}_j \rangle \right| \right]}{\sigma_\rho^{(t)}} \right)$$

Together, we have

$$\begin{aligned} & \left| \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \left(\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} - \mathbf{1}_{\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}} \right) \langle \xi, \mathbf{M}_j \rangle \right] \right| \\ & \leq O \left(\Gamma_t \frac{\mathbb{E} \left[\langle \xi, \mathbf{M}_j \rangle^2 \langle w_i^{(t)}, \mathbf{M}_j \rangle \right]}{\sigma_\rho^{(t)}} \right) = O \left(\frac{\Gamma_t}{d \sigma_\rho^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \sigma_x^2 \right) \end{aligned} \quad (\text{C.14})$$

Using the coordinate Lipschitzness, we also have

$$\begin{aligned} & \left| \mathbb{E}_{x,y,\rho} \left[y \left(\ell'_t(w^{(t)}; x, y, \rho) - \ell'_t(x'_j, y) \right) \mathbf{1}_{\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] \right| \\ & \leq L_{t,j} \mathbb{E}[\langle \xi, \mathbf{M}_j \rangle^2] \Pr[\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}] = O \left(\frac{\Gamma_t L_{t,j} \sigma_x^2}{d} \right) \end{aligned} \quad (\text{C.15})$$

Finally, we have $\mathbb{E}_{x,y,\rho} \left[y \ell'_t(x'_j, y) \mathbf{1}_{\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] = 0$. We can thus combine (C.14) and (C.15) to complete the proof of Lemma C.14a.

Next, we want to prove Lemma C.14b. We have: denote

$$q_{i'} = \left(\mathbf{1}_{\langle w_{i'}^{(t)}, \mathbf{M}_z \rangle + \rho_{i'} + b_{i'}^{(t)} \geq -|b^{(t)}|/10} + \mathbf{1}_{-\langle w_{i'}^{(t)}, \mathbf{M}_z \rangle + \rho_{i'} + b_{i'}^{(t)} \geq -|b^{(t)}|/10} \right)$$

Since w.p. at least $1 - e^{-\Omega(\log^2 d)}$, $|\langle w_{i'}^{(t)}, \xi \rangle| \leq \frac{|b^{(t)}|}{10}$, in this case, we know that

$$\begin{aligned} & \sum_{j \in [d]} |\ell'_t(w^{(t)}; x, y, \rho) - \ell'_t(x'_j, y)| |\langle \xi, \mathbf{M}_j \rangle| \\ & \leq \sum_{j \in [d]} \langle \mathbf{M}_j, \xi \rangle^2 \cdot \sum_{i' \in [m]} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| \cdot (\mathbf{1}_{\langle w_{i'}^{(t)}, x \rangle + \rho_{i'} + b_{i'}^{(t)} \geq 0} + \mathbf{1}_{-\langle w_{i'}^{(t)}, x \rangle + \rho_{i'} + b_{i'}^{(t)} \geq 0}) \\ & \leq \sum_{j \in [d]} \langle \mathbf{M}_j, \xi \rangle^2 \cdot \sum_{i' \in [m]} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| \cdot q_{i'} \end{aligned}$$

Note also we have:

$$\begin{aligned} \sum_{j \in [d]} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| & \leq O(1) \cdot \|w_{i'}^{(t)}\|_2 + \sum_{j: i' \notin \mathcal{S}_{j, \text{pot}+}} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| \\ & \leq O(1) \cdot \frac{\sigma_w^{(t)}}{\beta} + d \cdot \frac{k}{d\beta} b^{(t)} \leq 2 \frac{k}{\beta} \cdot b^{(t)} \end{aligned}$$

By Lemma C.16, we have that

$$\begin{aligned} & \sum_{j \in [d]} \left| \mathbb{E}_{x,y,\rho} \left[y \left(\ell'_t(w^{(t)}; x, y, \rho) - \ell'_t(x'_j, y) \right) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \langle \xi, \mathbf{M}_j \rangle \right] \right| \\ & \leq e^{-\Omega(\log^2 d)} + \sum_{j \in [d]} \mathbb{E}_{x,y,\rho} \left[\left| \left(\ell'_t(w^{(t)}; x, y, \rho) - \ell'_t(x'_j, y) \right) \langle \xi, \mathbf{M}_j \rangle \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right| \right] \\ & \leq e^{-\Omega(\log^2 d)} + \sum_{j \in [d]} \mathbb{E}_{x,y,\rho} \left[\left| \left(\ell'_t(w^{(t)}; x, y, \rho) - \ell'_t(x'_j, y) \right) \langle \xi, \mathbf{M}_j \rangle \right| q_i \right] \\ & \leq e^{-\Omega(\log^2 d)} + \sum_{j \in [d]} \mathbb{E}_{x,y,\rho} \left[\langle \mathbf{M}_j, \xi \rangle^2 \cdot \sum_{i' \in [m]} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| \cdot q_{i'} q_i \right] \quad \dots \text{ taking expectation w.r.t. } \xi \text{ first.} \end{aligned}$$

$$\begin{aligned}
&\leq e^{-\Omega(\log^2 d)} + O\left(\frac{\sigma_x^2}{d}\right) \cdot \sum_{j \in [d]} \mathbb{E}_{x,y,\rho} \left[\sum_{i' \in [m]} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| \cdot q_{i'} q_i \right] \\
&\leq O\left(\frac{\sigma_x^2}{d}\right) \cdot O\left(\frac{k}{\beta} b^{(t)} \cdot k \Xi_2\right) \cdot O\left(\frac{k}{d}\right) + e^{-\Omega(\log^2 d)} \leq O\left(\frac{k^3 \Xi_2^4}{d^2} \sigma_x^2 + e^{-\Omega(\log^2 d)}\right) \quad (\text{C.16})
\end{aligned}$$

Next, similar to the (C.14), we also have

$$\begin{aligned}
&\sum_{j \in [d]} \left| \mathbb{E}_{x,y,\rho} \left[y \ell'_t(x'_j, y) \left(\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} - \mathbf{1}_{\langle w_i^{(t)}, x'_j \rangle + \rho_i \geq b^{(t)}} \right) \langle \xi, \mathbf{M}_j \rangle \right] \right| \\
&\leq \sum_{j \in [d]} O\left(\frac{\Gamma_t}{d \sigma_\rho^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \sigma_x^2\right) \leq O\left(\frac{k}{d^2 \sigma_\rho^{(t)}} \sigma_x^2\right) \cdot \sum_{j \in [d]} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq O\left(\frac{k^2 \log d}{d^2 \beta} \sigma_x^2\right) \quad (\text{C.17})
\end{aligned}$$

Combining (C.16) and (C.17) we finish the proof of Lemma C.14b. \square

C.4.2 Growth Coupling

We also have the following lemma which says, essentially, that all those neurons $i \in [m]$ satisfying $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 2\sqrt{kb}^{(t)}$ for the same j , grows roughly in the same direction that is *independent* of i .

Lemma C.15 (growth coupling). *Suppose at iteration t , $\mathcal{S}_{ept+}^{(t)} = [m]$. Then, for every $j \in [d]$, every $i \in [m]$ such that $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 2\sqrt{kb}^{(t)}$, we have:*

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \left(\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) z_j \right] = \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) z_j \right] \pm O\left(\frac{k^{3/2}}{d^2}\right)$$

Proof of Lemma C.15. We first focus on the case when $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 2\sqrt{kb}^{(t)}$ is positive, and the reverse case is analogous. Conditional on $|z_j| = s > 0$, we know that $s \geq \frac{1}{\sqrt{k}}$. Thus, when $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 2\sqrt{kb}^{(t)}$, $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| s \geq 2b^{(t)}$. Now, using $\mathcal{S}_{ept+}^{(t)} = [m]$ and Lemma C.5, we can conclude that

- when $z_j > 0$, $\Pr[\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \mid z_j = s] \geq 1 - O\left(\frac{k}{d}\right)$;
- when $z_j < 0$, $\Pr[\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)} \mid z_j = -s] \leq O\left(\frac{k}{d}\right)$.

Thus, we can obtain

$$\begin{aligned}
\mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] &= \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) z_j \mathbf{1}_{z_j > 0} \right] \pm O\left(\frac{k}{d}\right) \times \mathbb{E} |z_j| \\
&= \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) z_j \mathbf{1}_{z_j > 0} \right] \pm O\left(\frac{k^{3/2}}{d^2}\right)
\end{aligned}$$

In the symmetric case, we also have

$$\mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} z_j \right] = \mathbb{E}_{x,y,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) z_j \mathbf{1}_{z_j < 0} \right] \pm O\left(\frac{k^{3/2}}{d^2}\right) \quad \square$$

C.4.3 Activation Probabilities

Lemma C.16 (activation after ept+). *Suppose $\mathcal{S}_{ept+}^{(t)} = [m]$ and $\mathcal{S}_{j,pot}^{(0)} \supseteq \mathcal{S}_{j,pot+}^{(t)}$ for every $j \in [d]$. Then, with probability at least $1 - e^{-\Omega(\log^2 d)}$,*

- $\left| \left\{ i \in [m] \text{ s.t. } |\langle w_i^{(t)}, x \rangle| \geq \frac{b^{(t)}}{10} \right\} \right| \leq O(k\Xi_2)$.
- $\left| \left\langle w_i^{(t)}, \sum_{j \in [d]: i \notin \mathcal{S}_{j, \text{pot}+}^{(t)}} \mathbf{M}_j z_j + \xi \right\rangle \right| \leq \frac{b^{(t)}}{10}$ for every $i \in [m]$.

Proof. For every $i \in [m]$ and $j \in [d]$ with $i \notin \mathcal{S}_{j, \text{pot}+}^{(t)}$, we have $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq \frac{k}{d\beta} b^{(t)}$. Therefore, by Bernstein's inequality (similar to Lemma C.3b), we know with probability at least $1 - e^{-\Omega(\log^2 d)}$, for every $i \in [m]$,

$$\left| \left\langle w_i^{(t)}, \sum_{j \in [d]: i \notin \mathcal{S}_{j, \text{pot}+}^{(t)}} \mathbf{M}_j z_j + \xi \right\rangle \right| \leq \frac{b^{(t)}}{10} \quad (\text{C.18})$$

With probability at least $1 - e^{-\Omega(\log^2 d)}$ it satisfies $\sum_{j \in [d]} \mathbf{1}_{z_j \neq 0} \leq O(k)$ (since each $z_j \neq 0$ with probability at most $O(\frac{k}{d})$). Therefore, denoting by $\Lambda = \bigcup_{j \in [d]: z_j \neq 0} \mathcal{S}_{j, \text{pot}+}^{(t)}$, we have $|\Lambda| \leq O(k\Xi_2)$ (since every $|\mathcal{S}_{j, \text{pot}+}^{(t)}| \leq \Xi_2$). Now, for any $i \in [m] \setminus \Lambda$, inequality (C.18) immediately gives

$$\left| \langle w_i^{(t)}, x \rangle \right| \leq \frac{b^{(t)}}{10} .$$

Therefore, the number of $i \in [m]$ satisfying $\left| \langle w_i^{(t)}, x \rangle \right| \geq \frac{b^{(t)}}{10}$ cannot be more than $O(k\Xi_2)$. \square

C.4.4 Coordinate Lipschitzness Bound

Lemma C.17 (coordinate Lipschitzness). *For every $j \in [d]$, let us define $\gamma_j^{(t)} = \sum_{i \in \mathcal{S}_{j, \text{pot}+}^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle|$.*

Then, suppose $\mathcal{S}_{\text{ept}+}^{(t)} = [m]$ and suppose $\mathcal{S}_{j, \text{pot}}^{(0)} \supseteq \mathcal{S}_{j, \text{pot}+}^{(t)}$, we have

$$L_{t,j} \leq \gamma_j^{(t)} + O\left(\frac{k}{\sqrt{d}}\right) \leq \gamma_j^{(t)} + O\left(\frac{1}{\Xi_3^2}\right)$$

Proof of Lemma C.17. Clearly we have

$$L_{t,j} \leq \sum_{i \in \mathcal{S}_{j, \text{pot}+}^{(0)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| + \sum_{i \notin \mathcal{S}_{j, \text{pot}+}^{(0)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \cdot (\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq 0.9b_i^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq 0.9b_i^{(t)}})$$

By Lemma C.16 and the randomness of ρ_i , we know with probability at least $1 - e^{-\Omega(\log^2 d)}$, the number of activate neurons $i \notin \mathcal{S}_{j, \text{pot}+}^{(t)}$ —meaning $\langle w_i^{(t)}, x \rangle + \rho_i \geq 0.9b_i^{(t)}$ or $-\langle w_i^{(t)}, x \rangle + \rho_i \geq 0.9b_i^{(t)}$ —is at most $O(k\Xi_2)$. On the other hand, when $i \notin \mathcal{S}_{j, \text{pot}+}^{(t)}$, we know that

$$|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq \frac{k}{d\beta} b^{(t)} \leq \frac{k\Xi_2^2}{d}$$

Therefore, together, the total contribution from these active neurons with $i \notin \mathcal{S}_{j, \text{pot}+}^{(t)}$ is at most $\frac{k\Xi_2^2}{d} \cdot O(k\Xi_2) < O(\frac{k^2\Xi_3^2}{d}) < O(\frac{1}{\Xi_3^2})$. This completes the proof. \square

C.4.5 Regularization

Following the same argument as (C.9) from phase I, we know at any iteration t , as long as $\mathcal{S}_{\text{ept}+}^{(t)} = [m]$,

$$\begin{aligned} \langle w_i^{(t+1)}, \mathbf{M}_j \rangle &= \langle w_i^{(t)}, \mathbf{M}_j \rangle (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) \pm \frac{\eta}{\text{poly}(d)} \\ &+ \mathbb{E}_{x, y=y(x), \rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) \sum_{i=1}^m \left(\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \cdot (z_j + \langle \xi, \mathbf{M}_j \rangle) \right]. \end{aligned} \quad (\text{C.19})$$

In this and the next subsection, we shall repeatedly apply growth lemmas to (C.19). Before doing so, let us note $\sigma_\rho^{(t)} = o(b^{(t)} \log d) \leq o(\beta \Xi_2^2 \log d)$, so using our parameter choice of β and using $k \leq d^{1-c_0}$,

$$\frac{\sqrt{k} \sigma_\rho^{(t)} \log d}{d} + \frac{\sqrt{k}}{\beta d^{3/2}} = o\left(\frac{\sqrt{k} \beta \Xi_2^2 \log^2 d}{d}\right) + \frac{\sqrt{k}}{\beta d^{3/2}} = o\left(\frac{1}{d}\right) \quad (\text{C.20})$$

This means, when applying the aforementioned growth lemmas Lemma C.11, Lemma C.12, Lemma C.13, the additional terms $\frac{\sqrt{k} \sigma_\rho^{(t)} \log d}{d}$ and $\frac{\sqrt{k}}{\beta d^{3/2}}$ are negligible.

We also have the following regularity lemma:

Lemma C.18 (regularity). *For every $T \leq d^{O(\log d)}/\eta$, suppose $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$ and $\mathcal{S}_{j,pot}^{(0)} \supseteq \mathcal{S}_{j,pot+}^{(t)}$ hold for every $t \leq T$ and $j \in [d]$. Then, we have for every $t \leq T$, with probability at least $1 - e^{-\Omega(\log^2 d)}$,*

$$\forall j \in [d], \forall i \in [m]: \quad L_{t,j} \leq O(\Xi_2^2), \quad \|w_i^{(t)}\|_2 \leq O(\Xi_2^2), \quad |f_t(x)| \leq O(\Xi_2^2 \log d).$$

Proof of Lemma C.18. By substituting Lemma C.12, Lemma C.14a and (C.20) into (C.19), we have for every $j \in [d]$:

$$\begin{aligned} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| &\leq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - \eta\lambda \|w_i^{(t)}\|_2) + \eta O\left(\frac{1 + L_{t,j}}{d}\right) \\ &\leq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \left(1 - \eta\lambda |\langle w_i^{(t)}, \mathbf{M}_j \rangle|\right) + \eta O\left(\frac{1 + L_{t,j}}{d}\right) \end{aligned}$$

Summing up over all $i \in \mathcal{S}_{j,pot}^{(0)}$, and using Cauchy-Schwarz inequality together with $|\mathcal{S}_{j,pot}^{(0)}| \leq \Xi_2$, we have

$$\sum_{i \in \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq \sum_{i \in \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| - \frac{\eta\lambda}{\Xi_2} \left(\sum_{i \in \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \right)^2 + \eta O\left(\frac{1 + L_{t,j}}{d}\right) \cdot \Xi_2$$

Combining this with $L_{t,j} \leq \sum_{i \in \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| + O(\frac{1}{\Xi_2^3})$ from Lemma C.17 and our choice $\lambda \geq \frac{1}{d}$, we have (for every $j \in [d]$ and $t \leq T$),

$$\sum_{i \in \mathcal{S}_{j,pot}^{(0)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq O(\Xi_2^2)$$

This also implies $L_{t,j} \leq O(\Xi_2^2)$ as well as

$$\|w_i^{(t)}\|^2 = \sum_{j: i \in \mathcal{S}_{j,pot+}^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle|^2 + \sum_{j: i \notin \mathcal{S}_{j,pot+}^{(t)}} |\langle w_i^{(t)}, \mathbf{M}_j \rangle|^2 \leq O(\Xi_2^4) + O\left(\frac{k^2}{d\beta^2} (b^{(t)})^2\right) \leq O(\Xi_2^4).$$

Finally, for the objective value, we wish use $L_{t,j} \leq O(\Xi_2^2)$ and apply a high-probability Bernstein variant of the McDiarmid's inequality (see Lemma H.3).

Specifically, consider random z, ξ, ρ . For notation simplicity, let us write $\xi = \sum_{j \in [d]} \mathbf{M}_j \xi_j$ for i.i.d. random $\xi_j \sim \mathcal{N}(0, \frac{\sigma_\xi^2}{d})$.

Now, for every $j \in [m]$, suppose we change z_j to z'_j and ξ_j to ξ'_j with the same distribution. Then, with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$|f_t(z, \xi, \rho) - f_t(z_{-j}, z'_j, \xi_{-j}, \xi'_j, \rho)| \leq L_{t,j} \cdot (|z_j| + |z'_j| + |\xi_j| + |\xi'_j|)$$

This implies with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$\mathbb{E}_{z_j, z'_j} |f_t(z, \xi, \rho) - f_t(z_{-j}, z'_j, \xi, \rho)|^2 \leq O(L_{t,j}^2) \cdot \frac{1}{d}$$

Therefore, we can apply Lemma H.3 to derive that with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$|f_t(x, \rho) - \mathbb{E}_{z, \xi} [f_t(x, \rho)]| \leq O(\Xi_2^2 \log d)$$

Finally, noticing that for every ρ , by symmetry $\mathbb{E}_{z, \xi} [f_t(x, \rho)] = 0$. This finishes the bound on the objective value. \square

We also prove this Lemma, which gives a lower bound on the loss:

Lemma C.19 (loss lower bound). *In every iteration t , define $L_{\max} := \max_{j \in [d]} \{L_{t,j}\}$ and suppose $L_{\max} \leq O(\Xi_2^2)$. Then we have:*

$$\mathbb{E}_{x, \rho} [\ell'_t(w^{(t)}; x, y, \rho)] = \Omega \left(\min \left\{ 1, \frac{1}{L_{\max}^2 \log^2 d} \right\} \right)$$

Proof of Lemma C.19. Let $\alpha \in [\frac{1}{(\Xi_2)^5}, 1]$ be a fixed value to be chosen later, and $\mathcal{S}_0 \subseteq [d]$ be an arbitrary subset of size $|\mathcal{S}_0| = \alpha d$. Consider a randomly sampled vector z and let $x = \mathbf{M}z + \xi$ be the corresponding input. We construct another z' that is generated from the following process

1. Let $\mathcal{S}_{re,z} \subseteq \mathcal{S}_0$ be the set consisting of all $i \in \mathcal{S}_0$ with $|z_i| = \Theta\left(\frac{1}{\sqrt{k}}\right)$.
2. For all $i \notin \mathcal{S}_{re,z}$, pick $z'_i = z_i$.
3. For all $i \in \mathcal{S}_{re,z}$, pick $z'_i = z_i$ or $z'_i = -z_i$ each with probability 0.5, independently at random.

Obviously, z' has the same distribution as z . Now, let us define $x' = \mathbf{M}z' + \xi$, $y' = \text{sign}(\langle w^*, z' \rangle)$.

Since $|\mathcal{S}_0| = \alpha d$, recalling the distribution property that $\Pr \left[|z_i| = \Theta\left(\frac{1}{\sqrt{k}}\right) \right] = \Omega\left(\frac{k}{d}\right)$, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$ over the choice of z , $|\mathcal{S}_{re,z}| = \Theta(\alpha k)$. We call this event $\mathcal{E}_1(z)$.

Let us denote by $b_i = \frac{z'_i}{z_i} \in \{-1, 1\}$ for every $i \in \mathcal{S}_{re,z}$. We can therefore write $f_t(w^{(t)}; x', \rho) = f(z, b, \xi, \rho)$ to emphasize that the randomness comes from z, b, ξ, ρ . Using the definition of coordinate Lipschitzness, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$ over z, ξ, ρ , it satisfies

$$\forall k \in \mathcal{S}_{re,z}, \forall b \in \{-1, 1\}^{\mathcal{S}_{re,z}}, \forall b'_k \in \{-1, +1\}: |f(z, b, \xi, \rho) - f(z, (b_{-k}, b_k), \xi, \rho)| \leq O\left(\frac{L_{\max}}{\sqrt{k}}\right)$$

Let $\mathcal{E}_2(z, \xi, \rho)$ denote the event where the above statement holds.

Now, conditioning on $\mathcal{E}_1(z)$ and $\mathcal{E}_2(z, \xi, \rho)$ both hold, we can apply standard MiDiarmid's inequality (see Lemma H.2) over the randomness of b , and derive that with probability at least $1 - e^{-\Omega(\log^2 d)}$ over b ,

$$\left| f(z, b, \xi, \rho) - \mathbb{E}_b [f(z, b, \xi, \rho)] \right| \leq O(L_{\max} \sqrt{\alpha} \log d)$$

Let $\mathcal{E}_3(b|z, \xi, \rho)$ denote the (conditional) event where the above statement holds.

In sum, by combining $\mathcal{E}_1, \mathcal{E}_2, \mathcal{E}_3$, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$ over z, z', ξ, ρ , it satisfies

$$\left| f_t(w^{(t)}; x', \rho) - \mathbb{E}_{z'} \left[f_t(w^{(t)}; x', \rho) \mid z, \xi, \rho \right] \right| \leq O(L_{\max} \sqrt{\alpha} \log d) .$$

As a simple corollary, if we generate another copy z'' in the same way as z' , and denote by $x'' = \mathbf{M}z'' + \xi$, then with probability at least $1 - e^{-\Omega(\log^2 d)}$ over z, z', z'', ξ, ρ , it satisfies

$$\left| f_t(w^{(t)}; x', \rho) - f_t(w^{(t)}; x'', \rho) \right| \leq O(L_{\max} \sqrt{\alpha} \log d) . \quad (\text{C.21})$$

Now, let us denote by $y' = \text{sign}(\langle w^*, z' \rangle)$ and $y'' = \text{sign}(\langle w^*, z'' \rangle)$ and compare them. Let us write

$$A = \sum_{i \in [d] \setminus \mathcal{S}_{re,z}} w_i^* z_i , \quad B = \sum_{i \in \mathcal{S}_{re,z}} w_i^* z'_i , \quad C = \sum_{i \in \mathcal{S}_{re,z}} w_i^* z''_i .$$

Thus, we have $y' = \text{sign}(A + B)$ and $y'' = \text{sign}(A + C)$.

First using a minor variant of Lemma H.1b, we have¹⁷

$$\Pr [A \in [0, \sqrt{\alpha}]] \geq \Omega(\sqrt{\alpha})$$

Denote this event by $\mathcal{E}_4(z)$.

Next, conditioning on any fixed z which satisfies $\mathcal{E}_1(z)$ and $\mathcal{E}_4(z)$, we know that B and C become *independent*, each controlled by $|\mathcal{S}_{re,z}| = \Theta(\alpha k)$ random Bernoulli variables. Therefore, we can apply a Wasserstein distance version of the central limit theorem (that can be derived from [104], full statement see [6, Appendix A.2]) to derive that, for a Gaussian variable $g \sim (0, V^2)$ where $V^2 = \sum_{j \in \mathcal{S}_{re,z}} (z_j)^2 = \Theta(\alpha)$, the Wasserstein distance:

$$\mathcal{W}_2(B, g) \leq O\left(\frac{\log k}{\sqrt{k}}\right) \quad \text{and} \quad \mathcal{W}_2(C, g) \leq O\left(\frac{\log k}{\sqrt{k}}\right)$$

This means with probability at least $\Omega(1)$, it satisfies $B \in [0, \sqrt{\alpha}]$ and $C \leq -5\sqrt{\alpha}$.

To sum up, we know with probability at least $\Omega(\sqrt{\alpha})$, it satisfies $A, B \in [0, \sqrt{\alpha}]$ and $C \leq -5\sqrt{\alpha}$. This means $y' \neq y''$, or in symbols,

$$\Pr[y' \neq y''] \geq \Omega(\sqrt{\alpha}) . \quad (\text{C.22})$$

Finally, conditioning on both (C.21) and (C.22) happen, we know that

- either $\text{sign}(f_t(w^{(t)}; x', \rho)) = \text{sign}(f_t(w^{(t)}; x'', \rho))$, in which case $\ell'_t(w^{(t)}; x', y', \rho) + \ell'_t(w^{(t)}; x'', y'', \rho) \geq \frac{1}{2}$,
- or $|f_t(w^{(t)}; x', \rho)| \leq O(L_{\max} \sqrt{\alpha} \log d)$ and $|f_t(w^{(t)}; x'', \rho)| \leq O(L_{\max} \sqrt{\alpha} \log d)$, in which case if we choose $\alpha = \min\{\frac{1}{2}, \frac{1}{L_{\max}^2 \log^2 d}\}$, then we have $|f_t(w^{(t)}; x', \rho)|, |f_t(w^{(t)}; x'', \rho)| \leq O(1)$ and therefore $\ell'_t(w^{(t)}; x', y', \rho) + \ell'_t(w^{(t)}; x'', y'', \rho) \geq \Omega(1)$.

To sum up, we have

$$\begin{aligned} \mathbb{E}_{x, y=y(x), \rho} [\ell'_t(w^{(t)}; x, y, \rho)] &= \frac{1}{2} \mathbb{E}_{z, z', z'', \xi, \rho} [\ell'_t(w^{(t)}; x', y', \rho) + \ell'_t(w^{(t)}; x'', y'', \rho)] \\ &\geq \Omega(\sqrt{\alpha}) = \Omega\left(\min\left\{1, \frac{1}{L_{\max}^2 \log^2 d}\right\}\right) . \end{aligned} \quad \square$$

¹⁷To be precise, we can do so since we still have at least $(1 - \alpha)d \geq \frac{d}{2}$ coordinates.

C.4.6 Proof of Theorem C.2

Proof of Theorem C.2. We first prove that for every $t \geq T_b$,

$$\mathcal{S}_{j,pot}^{(t)} \subseteq \mathcal{S}_{j,pot+}^{(t)} \subseteq \mathcal{S}_{j,pot}^{(0)} \quad (\text{C.23})$$

Note from the definitions the relationship $\mathcal{S}_{j,pot}^{(t)} \subseteq \mathcal{S}_{j,pot+}^{(t)}$ always holds, so we only need to prove the second inclusion.

Suppose (C.23) holds until iteration t . Then, for every $i \notin \mathcal{S}_{j,pot}^{(0)}$, let us apply Lemma C.13, Lemma C.14a together with (C.20) and $L_{t,j} \leq O(\Xi_2^2)$ (using Lemma C.18) to (C.19). We get

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - \eta\lambda) + O\left(\frac{\eta k \Xi_2^2}{d^2}\right)$$

Therefore, for those t that are sufficiently large so that $b^{(t+1)} = \beta \Xi_2^2$, we have (using $\lambda \geq \frac{1}{d}$)

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq O\left(\frac{\eta k \Xi_2^2}{d^2}\right) \cdot \frac{1}{\eta\lambda} = O\left(\frac{k \Xi_2^2}{d \cdot d\lambda}\right) \leq \frac{k}{d\beta} b^{(t+1)}$$

and for those t that are still small so that $b^{(t+1)} = \Theta(\frac{\eta(t+1)}{d})$, we have

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq O\left(\frac{\eta k \Xi_2^2}{d^2} \cdot (t+1)\right) \ll \frac{k}{d\beta} b^{(t+1)}$$

Together, this means $i \notin \mathcal{S}_{j,pot+}^{(t+1)}$ so (C.23) holds for all $t \geq T_b$ and $T \leq d^{O(\log d)}/\eta$.

Phase II.1. We will construct a threshold T_e and prove inductively for all $t \in [T_b, T_e]$. Initially at $t = T_b$, by Lemma C.17 we have $L_{t,j} = o(1)$. As long as $L_{t,j} = o(1)$ holds for all $j \in [d]$, we have

- for every $i \in [m]$, substituting Lemma C.12, Lemma C.14a and (C.20) into (C.19),

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| + O\left(\frac{\eta}{d}\right) \leq \dots \leq O\left(\frac{\eta}{d} \cdot t\right)$$

- for every $i \notin \mathcal{S}_{j,pot}^{(t)}$, substituting Lemma C.13, Lemma C.14a and (C.20) into (C.19),

$$|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \leq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| + O\left(\frac{\eta k \log d}{d^2}\right) \leq \dots \leq O\left(\frac{\eta k \log d}{d^2} \cdot t\right)$$

Since for each i , the number of j satisfying $i \in \mathcal{S}_{j,pot}^{(t)}$ is at most $O(1)$ (using $\mathcal{S}_{j,pot}^{(t)} \subseteq \mathcal{S}_{j,pot}^{(0)}$ and $\mathcal{S}_{ept}^{(0)} = [m]$), we have

$$\|w_i^{(t+1)}\| \leq O\left(\frac{\eta}{d} \cdot t\right) \quad (\text{C.24})$$

These bounds together mean several things:

- $L_{t,j} = o(1)$ for all $j \in [d]$ and $t \in [T_b, T_e]$ with $T_e = \Theta\left(\frac{d}{\eta \Xi_2 \log d}\right)$.

Indeed, (C.24) gives $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq O\left(\frac{1}{\Xi_2 \log d}\right)$, but the number of j satisfying $i \in \mathcal{S}_{j,pot}^{(t)}$ is at most $O(1)$. So we can apply Lemma C.17 to get $L_{t,j} = o(1)$.

- $\mathcal{S}_{ept++}^{(t)} = [m]$ for all $t \in [T_b, T_e]$.

Indeed,

- for those t that are small so that $\sigma_w^{(t)} = \Theta\left(\frac{\eta}{d\sqrt{\log d}}t\right)$, we have (C.24) implies $\|w_i^{(t)}\| \leq O(\sqrt{\log d} \cdot \sigma_w^{(t)}) \ll \frac{\sigma_w^{(t)}}{\beta}$; and

– for those t that are large so that $\sigma_w^{(t)} = \Theta\left(\frac{\beta\Xi_2^2}{\sqrt{\log d}}\right)$, we have (C.24) implies $\|w_i^{(t)}\| \leq O\left(\frac{1}{\Xi_2 \log d}\right) \ll \frac{\sigma_w^{(t)}}{\beta}$.

Together we have $i \in \mathcal{S}_{ept++}^{(t)}$.

- $\mathcal{S}_{ept+}^{(t)} = [m]$ for all $t \in [T_b, T_e]$.

This is a direct corollary of $\mathcal{S}_{ept++}^{(t)} = [m]$ together with the property that the number of j satisfying $i \in \mathcal{S}_{j,pot+}^{(t)}$ is at most $O(1)$.

Next, let us consider any $j \in [d]$ with $i \in \mathcal{S}_{j,sure}^{(0)}$. At any iteration $t \in [T_b, T_e]$, substituting Lemma C.11, Lemma C.14a, (C.24), and (C.20) into (C.19),

$$\begin{aligned} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| &\geq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) + \Omega\left(\frac{\eta}{d}\right) \\ &\geq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - 2\eta\lambda) + \Omega\left(\frac{\eta}{d}\right) \end{aligned}$$

This means two things:

- The value $|\langle w_i^{(t)}, \mathbf{M}_j \rangle|$ keeps increasing as t increases, until it reaches $\Theta\left(\frac{\eta}{d} \cdot \frac{1}{\eta\lambda}\right) = \Theta\left(\frac{1}{d\lambda}\right)$ and at that point it may decrease but will not fall below $\Theta\left(\frac{1}{d\lambda}\right)$. This ensures $i \in \mathcal{S}_{j,sure}^{(t)}$.
- At $t = T_e$, we must have $i \in \mathcal{S}_{j,sure+}^{(t)}$ because

$$\begin{aligned} |\langle w_i^{(t)}, \mathbf{M}_j \rangle| &\geq \Omega\left(\frac{\eta}{d} T_e\right) \geq \Omega\left(\frac{1}{\Xi_2 \log d}\right) \geq \Omega\left(\frac{1}{\Xi_2 \log d}\right) \cdot \frac{(b^{(t)})^2}{\beta^2 \Xi_2^4} \\ &\geq \Omega\left(\frac{1}{k\beta^2 \Xi_2^5 \log d}\right) \cdot 4k(b^{(t)})^2 \geq 4k(b^{(t)})^2 \end{aligned}$$

To sum up, at iteration $t = T_e$, we have

- for $i \in \mathcal{S}_{j,sure}^{(0)}$, $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq \Omega\left(\frac{1}{\Xi_2 \log d}\right)$;
- for $i \in \mathcal{S}_{j,pot}^{(0)}$, $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq O\left(\frac{1}{\Xi_2 \log d}\right)$
- for $i \notin \mathcal{S}_{j,pot}^{(0)}$, $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq O\left(\frac{k}{d\Xi_2}\right)$

Phase II.2. We first make a quick observation that

- $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$ for all $t \geq T_e$.

Indeed, from iteration $t = T_e$ on, we have $b^{(t)} = \beta\Xi_2^2$. Using Lemma C.18 we have for every $i \in [m]$, $\|w_i^{(t)}\| \leq O(\Xi_2^2) \leq \frac{\sigma_w^{(t)}}{\beta}$. Thus, $\mathcal{S}_{ept++}^{(t)} = [m]$ holds for all $t \geq T_e$. As for $\mathcal{S}_{ept+}^{(t)} = [m]$, it is a simple corollary of $\mathcal{S}_{ept++}^{(t)} = [m]$ together with the property that the number of j satisfying $i \in \mathcal{S}_{j,pot+}^{(t)}$ is at most $O(1)$.

Next, we claim for every $i \in \mathcal{S}_{j,sure+}^{(T_e)}$ and every $t \geq T_e$, it must hold that

$$|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq \frac{1}{C'} \left(\max_{i' \in [m]} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| \right) \quad \text{and} \quad i \in \mathcal{S}_{j,sure+}^{(t)} \quad (\text{C.25})$$

for some sufficiently large constant $C' > 1$. We prove by induction. Suppose (C.25) holds for t and we consider $t + 1$. By the definition of $i \in \mathcal{S}_{j,sure+}^{(t)}$, we know $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 2\sqrt{k}b^{(t)}$. Now, consider every other $i' \in [m] \setminus \{i\}$

- if $|\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| < 2C'|\langle w_i^{(t)}, \mathbf{M}_j \rangle|$, then after one iteration we still have $|\langle w_{i'}^{(t+1)}, \mathbf{M}_j \rangle| < C'|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle|$.
- if $|\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| > 2C'|\langle w_i^{(t)}, \mathbf{M}_j \rangle|$, then we have

$$\begin{aligned} \|w_i^{(t)}\|^2 &= |\langle w_i^{(t)}, \mathbf{M}_j \rangle|^2 + \sum_{j' \neq j} |\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle|^2 \leq |\langle w_i^{(t)}, \mathbf{M}_j \rangle|^2 + (d-1) \cdot \frac{k^2}{d^2 \beta^2} (b^{(t)})^2 \\ &\leq 10|\langle w_i^{(t)}, \mathbf{M}_j \rangle|^2 \leq \frac{10}{2C'} |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle|^2 \leq \|w_{i'}^{(t)}\|^2 \end{aligned} \quad (\text{C.26})$$

Therefore, applying Lemma C.15 and Lemma C.14a (for i and i'), and using $\beta \leq \frac{1}{\sqrt{k}}$, we have

$$\begin{aligned} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| &= |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) + \eta \mathbb{E}_{x,y,\rho} [y \ell'_t(w^{(t)}; x, y, \rho) z_j] \pm O\left(\frac{\eta k^{1.5}}{d^2}\right) \\ |\langle w_{i'}^{(t+1)}, \mathbf{M}_j \rangle| &= |\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| (1 - \eta\lambda - \eta\lambda \|w_{i'}^{(t)}\|_2) + \eta \mathbb{E}_{x,y,\rho} [y \ell'_t(w^{(t)}; x, y, \rho) z_j] \pm O\left(\frac{\eta k^{1.5}}{d^2}\right) \end{aligned}$$

Taking the difference and using (C.26), we have

$$\begin{aligned} |\langle w_{i'}^{(t+1)}, \mathbf{M}_j \rangle| - |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| &\leq \left(|\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| - |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \right) (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) + O\left(\frac{\eta k^{1.5}}{d^2}\right) \\ &\leq \left(|\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| - |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \right) - \Omega(\eta\lambda(\sqrt{kb}^{(t)})^3) + O\left(\frac{\eta k^{1.5}}{d^2}\right) \\ &\leq \left(|\langle w_{i'}^{(t)}, \mathbf{M}_j \rangle| - |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \right) \end{aligned}$$

thus we continue to have $|\langle w_{i'}^{(t+1)}, \mathbf{M}_j \rangle| \leq C'|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle|$.

Putting these together we show that the first half of (C.25) holds at $t+1$.

As for why $i \in \mathcal{S}_{j, \text{sure}+}^{(t+1)}$, we consider two cases.

- If $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 4\sqrt{kb}^{(t)}$, then in one iteration we should still have $|\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| \geq 2\sqrt{kb}^{(t)} = 2\sqrt{kb}^{(t+1)}$.
- If $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq 4\sqrt{kb}^{(t)}$, then by the first half of (C.25) together with Lemma C.17, we know the Lipschitzness $L_{t,j} \leq O(\sqrt{kb}^{(t)} \cdot \Xi_2) + O\left(\frac{1}{\Xi_2^2}\right) \leq o(1)$. In this case, we also have (see (C.26)) $\|w_i^{(t)}\|^2 \leq O(k(b^{(t)})^2) = o(1)$. Applying Lemma C.11 and Lemma C.14a again we have

$$\begin{aligned} |\langle w_i^{(t+1)}, \mathbf{M}_j \rangle| &\geq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|_2) + \Omega\left(\frac{\eta}{d}\right) \\ &\geq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| (1 - 2\eta\lambda) + \Omega\left(\frac{\eta}{d}\right) \geq |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \end{aligned}$$

Putting both cases together we have $i \in \mathcal{S}_{j, \text{sure}+}^{(t+1)}$ so the second half of (C.25) holds at $t+1$. \square

D Clean Accuracy Convergence Analysis

In this section we show the upper bound on how the clean training of a two-layer neural network can learn the labeling function from N training samples $\{x_i, y_i\}_{i=1}^N$ up to small generalization error.

Theorem D.1. *Suppose the high-probability initialization event in Lemma B.2 holds, and suppose $\eta, \sigma_0 \in (0, \frac{1}{\text{poly}(d)})$ and $N \geq \text{poly}(d)$. With probability at least $1 - e^{-\Omega(\log^2 d)}$, for any $T \geq \Omega(\frac{d\Xi_2^6}{\eta})$ and $T \leq d^{O(\log d)}/\eta$, if we run the algorithm for $T_{cc} = T_e + T$ iterations, we have*

$$\frac{1}{T} \sum_{t=T_e}^{T_e+T-1} \mathbb{E}_{x,y,\rho} \text{Obj}_t(w^{(t)}; x, y, \rho) \leq o(1)$$

In other words, at least 99% of the iterations $t = T_e, T_e + 1, \dots, T_e + T - 1$ will have population risk $o(1)$ and clean population accuracy $\geq 1 - o(1)$.

Remark D.2. With additional efforts, one can also prove that Theorem D.1 holds with high probability $1 - e^{-\Omega(\log^2 d)}$ for all T in the prescribed range. We do not prove it here since it is not beyond the scope of this paper.

D.1 Proof of Theorem D.1: Convergence Theorem

Our convergence analysis will rely on the following (what we call) *coupling* function which is the first-order approximation of the neural network.

Definition D.3 (coupling). *At every iteration t , we define a linear function in μ*

$$g_t(\mu; x, \rho) \stackrel{\text{def}}{=} \sum_{i=1}^m \left(\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \cdot (\langle \mu_i, x \rangle + \rho_i - b^{(t)}) - \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \cdot (-\langle \mu_i, x \rangle + \rho_i - b^{(t)}) \right)$$

and it equals the output of the real network at point $\mu = w^{(t)}$ both on zero and first order:

$$g_t(w^{(t)}; x, \rho) = f_t(w^{(t)}; x, \rho) \quad \text{and} \quad \nabla_{\mu} g_t(\mu; x, \rho) \Big|_{\mu=w^{(t)}} = \nabla_w f_t(w; x, \rho) \Big|_{w=w^{(t)}}$$

In the analysis, we shall also identify a special choice μ^* defined as follows.

Definition D.4. *Recall $\mathcal{S}_{1,\text{sure}}^{(0)}, \dots, \mathcal{S}_{d,\text{sure}}^{(0)} \subseteq [m]$ are disjoint, so we construct μ_1^*, \dots, μ_m^* by*

$$\mu_i^* \stackrel{\text{def}}{=} \begin{cases} \alpha \left(\frac{w_j^*}{|\mathcal{S}_{j,\text{sure}}^{(0)}|} \right) \mathbf{M}_j, & i \in \mathcal{S}_{j,\text{sure}}^{(0)} \text{ for some } j \in [d]; \\ \vec{0}, & \text{otherwise.} \end{cases}$$

Above, $\alpha = o(1)$ is a parameter to be chosen later. One can easily check (using Lemma B.2) that

Claim D.5. $\sum_{i \in [m]} \|\mu_i^*\|^2 \leq O(\frac{\alpha^2}{\Xi_1} d)$ and $\sum_{i \in [m]} \|\mu_i^*\|^3 \leq O(\frac{\alpha^3}{\Xi_1^2} d)$

More interestingly, our so-constructed μ^* satisfies (to be proved in Section D.2)

Lemma D.6. *Suppose $\mathcal{S}_{ept+}^{(t)} = \mathcal{S}_{ept++}^{(t)} = [m]$, $\mathcal{S}_{j,\text{pot}}^{(0)} \supseteq \mathcal{S}_{j,\text{pot}+}^{(t)}$ and $\mathcal{S}_{j,\text{sure}}^{(0)} \subseteq \mathcal{S}_{j,\text{sure}+}^{(t)}$ for every $j \in [d]$. Then,*

(a) *with probability at least $1 - e^{-\Omega(\log^2 d)}$ over x, ρ , $g_t(\mu^*; x, \rho) = \alpha \langle w^*, z \rangle \pm O(\frac{1}{\Xi_2^2})$*

(b) $\mathbb{E}_{x,y=y(x),\rho} [\log(1 + e^{-y \cdot g_t(\mu^*; x, \rho)})] \leq O\left(\frac{1}{\alpha^2} + \frac{1}{\Xi_2^2}\right)$

We are now ready to prove Theorem D.1. Since $w_i^{(t+1)} = w_i^{(t)} - \eta \nabla_{w_i} \widetilde{\text{Obj}}_t(w^{(t)})$, we have the identity

$$\eta \langle \nabla \widetilde{\text{Obj}}_t(w^{(t)}), w^{(t)} - \mu^* \rangle = \frac{\eta^2}{2} \|\nabla \widetilde{\text{Obj}}_t(w^{(t)})\|_F^2 + \frac{1}{2} \|w^{(t)} - \mu^*\|_F^2 - \frac{1}{2} \|w^{(t+1)} - \mu^*\|_F^2$$

Applying Lemma A.2, we know that by letting $\mathbf{Obj}_t(w^{(t)}) = \mathbb{E}_{x,y,\rho} \mathbf{Obj}_t(w^{(t)}; x, y, \rho)$, it satisfies

$$\eta \langle \nabla \mathbf{Obj}_t(w^{(t)}), w^{(t)} - \mu^* \rangle \leq \eta^2 \cdot \text{poly}(d) + \frac{1}{2} \|w^{(t)} - \mu^*\|_F^2 - \frac{1}{2} \|w^{(t+1)} - \mu^*\|_F^2 + \frac{\eta}{\text{poly}(d)}$$

Let us define a pseudo objective

$$\mathbf{Obj}'_t(\mu) \stackrel{\text{def}}{=} \mathbb{E}_{x,y=y(x),\rho} [\log(1 + e^{-y \cdot g_t(\mu; x, \rho)})] + \lambda \sum_{i \in [m]} \mathbf{Reg}(\mu_i),$$

which is a convex function in μ because $g_t(\mu; x, \rho)$ is linear in μ . We have, for every $t \geq T_e$,

$$\begin{aligned} \langle \nabla \mathbf{Obj}_t(w^{(t)}), w^{(t)} - \mu^* \rangle &\stackrel{\textcircled{1}}{=} \langle \nabla \mathbf{Obj}'_t(w^{(t)}), w^{(t)} - \mu^* \rangle \\ &\geq \mathbf{Obj}'_t(w^{(t)}) - \mathbf{Obj}'_t(\mu^*) = \mathbf{Obj}_t(w^{(t)}) - \mathbf{Obj}'_t(\mu^*) \\ &\stackrel{\textcircled{2}}{\geq} \mathbf{Obj}_t(w^{(t)}) - \lambda \sum_{i \in [m]} \left(\frac{\|\mu_i^*\|^3}{3} + \frac{\|\mu_i^*\|^2}{2} \right) - O\left(\frac{1}{\alpha^2} + \frac{1}{\Xi_2^2}\right) \\ &\stackrel{\textcircled{3}}{\geq} \mathbf{Obj}_t(w^{(t)}) - O\left(\frac{\alpha^3 \log d}{\Xi_1^2} + \frac{\alpha^2 \log d}{\Xi_1} + \frac{1}{\alpha^2} + \frac{1}{\Xi_2^2}\right) \\ &\geq \mathbf{Obj}_t(w^{(t)}) - O\left(\frac{\sqrt{\log d}}{\sqrt{\Xi_1}}\right) \end{aligned}$$

Above, $\textcircled{1}$ uses the definition of g_t , $\textcircled{2}$ uses Lemma D.6b (and Theorem C.2 for the prerequisite for Lemma D.6b), and $\textcircled{3}$ uses Claim D.5 for the bound on $\|\mu_i^*\|^2$ and $\|\mu_i^*\|^3$.

Putting these together, we have

$$\eta \left(\mathbf{Obj}_t(w^{(t)}) - O\left(\frac{\sqrt{\log d}}{\sqrt{\Xi_1}}\right) \right) \leq \eta^2 \cdot \text{poly}(d) + \frac{1}{2} \|w^{(t)} - \mu^*\|_F^2 - \frac{1}{2} \|w^{(t+1)} - \mu^*\|_F^2 + \frac{\eta}{\text{poly}(d)}$$

Therefore, after telescoping for $t = T_e, T_e + 1, \dots, T_e + T - 1$, and using $\eta \leq \frac{1}{\text{poly}(d)}$, we have

$$\frac{1}{T} \sum_{t=T_e}^{T_e+T-1} \left(\mathbf{Obj}_t(w^{(t)}) - O\left(\frac{\sqrt{\log d}}{\sqrt{\Xi_1}}\right) \right) \leq \frac{O(\|w^{(T_e)} - \mu^*\|_F^2)}{\eta T} \leq \frac{O(\Xi_2^4 m)}{\eta T}$$

Finally, we calculate

$$\begin{aligned} \|w^{(T_e)}\|_F^2 &\leq \sum_{i \in \bigcup_j \mathcal{S}_{j,\text{pot}}^{(0)}} \|w_i^{(T_e)}\|_2^2 + \sum_{i \notin \bigcup_j \mathcal{S}_{j,\text{pot}}^{(0)}} \|w_i^{(T_e)}\|_2^2 \\ &\leq d \Xi_2 \cdot O(\Xi_2^4) + m \cdot O\left(\frac{k^2}{d^2} \Xi_2^4\right) \leq O(d \Xi_2^5) \end{aligned}$$

and this finishes the proof. ■

D.2 Proof of Claim D.6: Main Coupling

The proof of Lemma D.6a comes from Claim D.7 and Claim D.8 below. In the two claims, we split $g_t(\mu^*; x) = g_{t,1} + g_{t,4}$ into two terms, and bound them separately. Define

$$\begin{aligned} g_{t,1}(\mu^*; x, \rho) &= \sum_{j \in [d]} \frac{\alpha \cdot w_j^*}{|\mathcal{S}_{j,\text{sure}}^{(0)}|} \sum_{i \in \mathcal{S}_{j,\text{sure}}^{(0)}} \left(\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \cdot z_j \\ g_{t,4}(x, \rho) &= \sum_{i \in [m]} \left((\rho_i - b^{(t)}) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + (b^{(t)} - \rho_i) \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right) \end{aligned}$$

Claim D.7. $\Pr_{x,\rho}[g_{t,1}(\mu^*; x, \rho) = \alpha \langle w^*, z \rangle] \geq 1 - e^{-\Omega(\log^2 d)}$

Proof of Claim D.7. Recall for each $i \in \mathcal{S}_{j, \text{sure}}^{(0)}$,

- it satisfies $i \in \mathcal{S}_{j, \text{sure}+}^{(t)}$ so $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \geq 2\sqrt{k}b^{(t)}$;
- it also implies $i \notin \mathcal{S}_{j', \text{pot}+}^{(t)}$ for any $j' \neq j$, so $|\langle w_i^{(t)}, \mathbf{M}_{j'} \rangle| \leq \frac{k}{d\beta}b^{(t)}$;
- recall $\rho_i \sim \mathcal{N}(0, (\sigma_\rho^{(t)})^2)$ for $\sigma_\rho^{(t)} = \Theta(b^{(t)} \cdot \frac{(\log \log \log d)^3}{\log d})$.
- recall $\langle w_i^{(t)}, \xi \rangle$ is a variable with variance at most $O(\frac{\|w_i^{(t)}\|^2 \sigma_x^2}{d})$ for $\sigma_x = O(1)$.

Applying Lemma C.16, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$ it satisfies

$$\left| \langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \rangle \right| + |\rho_i| \leq \frac{b^{(t)}}{2} = \frac{\beta \Xi_2^2}{2} \quad (\text{D.1})$$

and when this happens it satisfies, whenever $z_j \neq 0$,

$$\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} = 1$$

Summing up over all $i \in \mathcal{S}_{j, \text{sure}}^{(0)}$ and $j \in [d]$, we have with probability at least $1 - e^{-\Omega(\log^2 d)}$ over x, ρ : $g_{t,1}(\mu^*; x) = \alpha \langle w^*, z \rangle$. \square

Claim D.8. $\Pr_{x,\rho}[|g_{t,4}(x, \rho)| \leq O(\frac{1}{\Xi_2^2})] \geq 1 - e^{-\Omega(\log^2 d)}$

Proof of Claim D.8. Let us write $\xi = \sum_{j \in [d]} \mathbf{M}_j \xi_j$ where each ξ_j is i.i.d. Let us write

$$g_{t,4}(x, \rho) = \sum_{i \in [m]} g_{t,4,i}(x, \rho_i)$$

$$\text{for } g_{t,4,i}(x, \rho_i) \stackrel{\text{def}}{=} \left((\rho_i - b^{(t)}) \mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + (b^{(t)} - \rho_i) \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right)$$

We note that $g_{t,4}(x, \rho)$ is a random variable that depends on independent variables

$$\xi_1, \dots, \xi_d, z_1, \dots, z_d, \rho_1, \dots, \rho_m,$$

so we also want to write it as $g_{t,4}(z, \xi, \rho)$ and $g_{t,4,i}(z, \xi, \rho_i)$.

We can without loss of generality assume as if $|\rho_i| \leq \frac{b^{(t)}}{10}$ and $|\xi_j| \leq \frac{b^{(t)}}{\Xi_2^2} := B$ always hold, both of which happen with probability at least $1 - e^{-\Omega(\log^2 d)}$. In the rest of the proof we condition on this happens. By symmetry we have

$$\forall \rho: \mathbb{E}_{\xi, z} [g_{t,4}(z, \xi, \rho)] = 0.$$

We wish to apply a high-probability version of the McDiarmid's inequality (see Lemma H.3) to bound $g_{t,4}$. In order to do so, we need to check the sensitivity of $g_{t,4}(x, \rho)$ regarding every random variable.

- For every z_j , suppose we perturb it to an arbitrary $z'_j \in [-1, 1]$. We also write $z' = (z_{-j}, z'_j)$ and $x' = \mathbf{M}z' + \xi$.

– Now, for every $i \in \mathcal{S}_{j, \text{pot}+}^{(t)}$, we have the naive bound

$$|g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z', \xi, \rho_i)| \leq 2b^{(t)} \cdot \mathbb{1}_{z_j \neq z'_j}$$

and there are at most $|\mathcal{S}_{j, \text{pot}+}^{(t)}| \leq \Xi_2$ such neurons i .

– For every $i \notin \mathcal{S}_{j,pot+}^{(t)}$, we have $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq \frac{k}{d\beta} b^{(t)}$. Define event

$$\mathcal{E}_i = \left\{ \left| \langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} z_{j'} + \xi \rangle \right| \geq \frac{b^{(t)}}{2} \right\}$$

* When event \mathcal{E}_i does not happen, we have $\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} = \mathbf{1}_{\langle w_i^{(t)}, x' \rangle + \rho_i \geq b^{(t)}}$, and thus

$$g_{t,4,i}(z, \xi, \rho_i) = g_{t,4,i}(z', \xi, \rho_i) .$$

* When \mathcal{E}_i happens, using the randomness of ρ_i , we have

$$\begin{aligned} \Pr_{\rho_i} \left[\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \neq \mathbf{1}_{\langle w_i^{(t)}, x' \rangle + \rho_i \geq b^{(t)}} \right] &\leq O \left(\frac{|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \cdot |z_j - z'_j|}{\sigma_{\rho}^{(t)}} \right) \\ &\leq O \left(\frac{k \log d}{d\beta} \right) \cdot |z_j - z'_j| \end{aligned}$$

and thus

$$|g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z', \xi, \rho_i)| = \begin{cases} 0, & \text{w.p. } \geq 1 - O \left(\frac{k \log d}{d\beta} |z_j - z'_j| \right) \text{ over } \rho_i; \\ O(b^{(t)}), & \text{otherwise.} \end{cases}$$

Note with probability at least $1 - e^{-\Omega(\log^2 d)}$, the number of $i \in [m]$ with \mathcal{E}_i holds is at most $O(k\Xi_2)$ (using Lemma C.16). Therefore, by applying Chernoff bound, we know

$$|g_{t,4}(z, \xi, \rho) - g_{t,4}(z', \xi, \rho)| \leq O(b^{(t)}) \cdot \left(\frac{k \log d}{d\beta} |z_j - z'_j| \cdot k\Xi_2 + \Xi_2 \right)$$

This means two things that both hold with probability at least $1 - e^{-\Omega(\log^2 d)}$ over z_{-j}, ξ, ρ :

- For all z_j, z'_j , $|g_{t,4}(x, \rho) - g_{t,4}(x', \rho)| \leq O(b^{(t)}) \cdot \left(\frac{k \log d}{d\beta} \cdot k\Xi_2 + \Xi_2 \right) \leq O(\sqrt{k}b^{(t)}) < o(\frac{1}{\Xi_2^2})$
- $\mathbb{E}_{z_j, z'_j} |g_{t,4}(x, \rho) - g_{t,4}(x', \rho)|^2 \leq O((b^{(t)})^2) \cdot \mathbb{E}_{z_j, z'_j} \left(\left(\frac{k \log d}{d\beta} \cdot k\Xi_2 \right)^2 |z_j - z'_j|^2 + \Xi_2^2 \mathbf{1}_{z_j \neq z'_j} \right) \leq O \left(\left(\frac{k^4 \Xi_2^2 \log^2 d}{d^2 \beta^2} \frac{1}{d} + \Xi_2^2 \frac{k}{d} \right) (b^{(t)})^2 \right) < o(\frac{1}{d\Xi_2^4})$

- For every ξ_j , suppose we perturb it to $\xi'_j \in [-B, B]$. We write $\xi' = \xi + \mathbf{M}_j(\xi'_j - \xi_j)$ and $x' = \mathbf{M}z + \xi'$.

– Now, for every $i \in \mathcal{S}_{j,pot+}^{(t)}$, with probability at least $1 - e^{-\Omega(\log^2 d)}$ we have $|\langle w_i^{(t)}, \sum_{j' \neq j} \mathbf{M}_{j'} \xi_{j'} \rangle| \leq \frac{b^{(t)}}{10}$. Therefore, if it also happens that $|\langle w_i^{(t)}, \mathbf{M}z \rangle| \leq \frac{b^{(t)}}{10}$, then $g_{t,4,i}(z, \xi, \rho_i) = g_{t,4,i}(z, \xi', \rho_i)$. In other words, we have

$$|g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z', \xi, \rho_i)| \leq 2b^{(t)} \cdot \mathbf{1}_{|\langle w_i^{(t)}, \mathbf{M}z \rangle| \geq \frac{b^{(t)}}{10}} .$$

Summing up over $i \in \mathcal{S}_{j,pot+}^{(t)}$, and taking expectation in z , we have

$$\left| \mathbb{E}_z \sum_{i \in \mathcal{S}_{j,pot+}^{(t)}} g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z', \xi, \rho_i) \right| \leq 2b^{(t)} \cdot \mathbb{E}_z \left[\sum_{i \in \mathcal{S}_{j,pot+}^{(t)}} \mathbf{1}_{|\langle w_i^{(t)}, \mathbf{M}z \rangle| \geq \frac{b^{(t)}}{10}} \right] \leq O \left(b^{(t)} \frac{k\Xi_2}{d} \right)$$

where the last inequality uses a variant of Lemma C.5 and $|\mathcal{S}_{j,pot+}^{(t)}| \leq \Xi_2$.

– For every $i \notin \mathcal{S}_{j,pot+}^{(t)}$, we have $|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq \frac{k}{d\beta} b^{(t)}$. Define event

$$\mathcal{E}_i = \left\{ |\langle w_i^{(t)}, \mathbf{M}_z + \sum_{j' \neq j} \mathbf{M}_{j'} \xi_{j'} \rangle| \geq \frac{b^{(t)}}{2} \right\}$$

* When event \mathcal{E}_i does not happen, we have $\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} = \mathbf{1}_{\langle w_i^{(t)}, x' \rangle + \rho_i \geq b^{(t)}}$, and thus

$$g_{t,4,i}(z, \xi, \rho_i) = g_{t,4,i}(z', \xi, \rho_i) .$$

* When \mathcal{E}_i happens, using the randomness of ρ_i , we have

$$\begin{aligned} \Pr_{\rho_i} \left[\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \neq \mathbf{1}_{\langle w_i^{(t)}, x' \rangle + \rho_i \geq b^{(t)}} \right] &\leq O \left(\frac{|\langle w_i^{(t)}, \mathbf{M}_j \rangle| \cdot |\xi_j - \xi'_j|}{\sigma_\rho^{(t)}} \right) \\ &\leq O \left(\frac{k \log d}{d\beta} \right) \cdot |\xi_j - \xi'_j| \end{aligned}$$

and thus

$$|g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z, \xi', \rho_i)| = \begin{cases} 0, & \text{w.p. } \geq 1 - O \left(\frac{k \log d}{d\beta} |\xi_j - \xi'_j| \right) \text{ over } \rho_i; \\ O(b^{(t)}), & \text{otherwise.} \end{cases}$$

Note with probability at least $1 - e^{-\Omega(\log^2 d)}$, the number of $i \in [m]$ with \mathcal{E}_i holds is at most $O(k\Xi_2)$ (using a minor variant of Lemma C.16). Therefore, by applying Chernoff bound, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$ over z, ξ_{-j}, ρ

$$\left| \sum_{i \notin \mathcal{S}_{j,pot+}^{(t)}} g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z, \xi', \rho_i) \right| \leq O(b^{(t)}) \cdot \left(\frac{k \log d}{d\beta} |\xi_j - \xi'_j| \cdot k\Xi_2 \right)$$

Taking expectation over z , we have with probability at least $1 - e^{-\Omega(\log^2 d)}$ over ξ_{-j}, ρ :

$$\left| \mathbb{E}_z \sum_{i \notin \mathcal{S}_{j,pot+}^{(t)}} g_{t,4,i}(z, \xi, \rho_i) - g_{t,4,i}(z, \xi', \rho_i) \right| \leq O(b^{(t)}) \cdot \left(\frac{\sqrt{k} \log d}{\sqrt{d}} |\xi_j - \xi'_j| \cdot k\Xi_2 \right)$$

Putting the two cases together, we have with probability at least $1 - e^{-\Omega(\log^2 d)}$ over ξ_{-j}, ρ :

$$\left| \mathbb{E}_z g_{t,4}(z, \xi, \rho) - \mathbb{E}_z g_{t,4}(z, \xi', \rho) \right| \leq O(b^{(t)}) \cdot O \left(\frac{k \log d}{d\beta} |\xi_j - \xi'_j| \cdot k\Xi_2 + \frac{k\Xi_2}{d} \right)$$

This means two things that both hold with probability at least $1 - e^{-\Omega(\log^2 d)}$ over ξ_{-j}, ρ :

- For all ξ_j, ξ'_j , $|\mathbb{E}_z g_{t,4}(z, \xi, \rho) - \mathbb{E}_z g_{t,4}(z, \xi', \rho)| \leq O(b^{(t)}) \cdot \left(\frac{k \log d}{d\beta} B \cdot k\Xi_2 + \frac{k\Xi_2}{d} \right) \ll o\left(\frac{1}{\Xi_2^2}\right)$
- $\mathbb{E}_{\xi_j, \xi'_j} |\mathbb{E}_z g_{t,4}(z, \xi, \rho) - \mathbb{E}_z g_{t,4}(z, \xi', \rho)|^2 \leq O((b^{(t)})^2) \cdot \mathbb{E}_{z, z'_j} \left(\left(\frac{k \log d}{d\beta} \cdot k\Xi_2 \right)^2 |\xi_j - \xi'_j|^2 + \frac{k^2 \Xi_2^2}{d^2} \right) \leq O \left(\left(\frac{k^4 \Xi_2^2 \log^2 d}{d^2 \beta^2} \frac{1}{d} + \frac{k^2 \Xi_2^2}{d^2} \right) (b^{(t)})^2 \right) \ll o\left(\frac{1}{d\Xi_2^4}\right)$

We are now ready to apply the high-probability version of the McDiarmid's inequality (see Lemma H.3). We apply it twice. In the first time, we use the perturbation on z to derive that, with probability at least $1 - e^{-\Omega(\log^2 d)}$ over z, ξ, ρ :

$$|g_{t,4}(z, \xi, \rho) - \mathbb{E}_z g_{t,4}(z, \xi, \rho)| \leq O\left(\frac{1}{\Xi_2^2}\right)$$

In the second time, we use the perturbation on ξ to derive that, with probability at least $1 - e^{-\Omega(\log^2 d)}$ over ξ, ρ ,

$$|\mathbb{E}_z g_{t,4}(z, \xi, \rho) - \mathbb{E}_{z, \xi} g_{t,4}(z, \xi, \rho)| \leq O\left(\frac{1}{\Xi_2^2}\right)$$

Finally, noticing that $\mathbb{E}_{z, \xi} g_{t,4}(z, \xi, \rho) = 0$ for every ρ , we finish the proof. \square

This finishes the proof of Lemma D.6a. We are only left to prove Lemma D.6b.

By Lipschitz continuity of the $\log(1 + e^{-x})$ function, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$\log(1 + e^{-y(x) \cdot g_t(\mu^*; x)}) = \log(1 + e^{-y(x) \cdot \alpha \langle w^*, z \rangle}) \pm O\left(\frac{1}{\Xi_2^2}\right) = \log(1 + e^{-\alpha |\langle w^*, z \rangle|}) \pm O\left(\frac{1}{\Xi_2^2}\right)$$

Taking expectation (and using the exponential tail) we have

$$\mathbb{E} \left[\log(1 + e^{-y(x) \cdot g_t(\mu^*; x)}) \right] = \mathbb{E} \left[\log(1 + e^{-\alpha |\langle w^*, z \rangle|}) \right] \pm O\left(\frac{1}{\Xi_2^2}\right)$$

Note if we take expectation over z , we have

$$\begin{aligned} \mathbb{E}_z [\log(1 + e^{-\alpha |\langle w^*, z \rangle|})] &\leq \int_{t \geq 0} \log(1 + e^{-\alpha t}) \cdot \Pr[|\langle w^*, z \rangle| \leq t] dt \\ &\stackrel{\textcircled{1}}{\leq} O(1) \cdot \int_{t \geq 0} e^{-\alpha t} \cdot \left(t + \frac{1}{\sqrt{k}}\right) \leq O\left(\frac{1}{\alpha^2} + \frac{1}{\sqrt{k}}\right) \end{aligned}$$

where $\textcircled{1}$ uses Lemma H.1a. This finishes the proof of Lemma D.6b. \blacksquare

E Why Clean Training is Non-Robust

In this section we shall show that clean training will not achieve robustness against ℓ_2 perturbation of size $\tau = \Omega\left(\frac{d^{0.4999}}{k^2}\right)$ as long as $k = \tilde{\Omega}(d^{0.3334})$. Recall $\|\mathbf{M}\|_1 = \sum_{j \in [d]} \|\mathbf{M}_j\|_\infty$.

Theorem E.1 (clean training is non-robust). *Suppose the high-probability initialization event in Lemma B.2 holds. Suppose $k > d^{(1-c_0)/3}$ and consider any iteration $t \geq \Omega\left(\frac{1}{\eta \lambda \Xi_2^2}\right)$ and $t \leq d^{O(\log d)}/\eta$. With probability at least $1 - e^{-\Omega(\log^2 d)}$ the following holds. If we perturb every input x by $\delta = -y \Xi_2^{10}(\mathbf{M}w^*)/k^2$, then the accuracy drops below $e^{-\Omega(\log^2 d)}$:*

$$\begin{aligned} \Pr_{x, y=y(x), \rho} \left[\text{sign}(f_t(x - \delta)) = y \right] &\leq e^{-\Omega(\log^2 d)}, \\ \Pr_{x, y=y(x), \rho} \left[\text{sign}\left(\mathbb{E}_\rho[f_t(x - \delta)]\right) = y \right] &\leq e^{-\Omega(\log^2 d)}. \end{aligned}$$

Note that

$$\|\delta\|_2 \leq \frac{\Xi_2^{10} \sqrt{d}}{k^2} \quad \text{and} \quad \|\delta\|_\infty \leq \frac{\Xi_2^{10} \|\mathbf{M}\|_1}{k^2}.$$

The proof of Theorem E.1 relies on the following main lemma (to be proved in Section E.1). It says that towards the end of clean training, neurons $w_i^{(t)}$ have a (small) common direction in $\mathbf{M}w^*$.

Lemma E.2 (non-robust). *For any iteration $t \geq \Omega\left(\frac{1}{\eta \lambda \Xi_2^2}\right)$, let subset $\mathcal{S} = \cup_{j \in [d]} \mathcal{S}_{j, \text{sure}}^{(0)}$, then*

$$\sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle = \Omega\left(\frac{kd}{\Xi_2^7}\right) \quad \text{and} \quad \forall i \in [m]: \langle w_i^{(t)}, \mathbf{M}w^* \rangle \geq -O\left(\frac{1}{\lambda} \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right)$$

With the help of Lemma E.2, one can calculate that by perturbing input in this direction $-y \cdot \mathbf{M}w^*$, the output label of the network can change dramatically. This is the proof of Theorem E.1 and details can be found in Section E.2.

E.1 Proof of Lemma E.2: Common Direction Among Neurons

Before proving Lemma E.2, let us first present Claim E.3.

Claim E.3. *We have*

$$\begin{aligned} \langle w_i^{(t+1)}, \mathbf{M}w^* \rangle &\geq \langle w_i^{(t)}, \mathbf{M}w^* \rangle \cdot (1 - \eta\lambda - \eta\lambda\|w_i^{(t)}\|) - O\left(\eta \frac{k^2}{d^{1.5}} \sigma_x^2 + \frac{\eta}{\text{poly}(d)}\right) \\ &\quad + \eta \mathbb{E}_{x,\rho} \left[\ell'_t(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} |\langle w^*, z \rangle| \right] \end{aligned}$$

Proof of Claim E.3. Let us recall from (C.19) that

$$\begin{aligned} \langle w_i^{(t+1)}, \mathbf{M}_j \rangle &= \langle w_i^{(t)}, \mathbf{M}_j \rangle \cdot (1 - \eta\lambda - \eta\lambda\|w_i^{(t)}\|) \pm \frac{\eta}{\text{poly}(d)} \\ &\quad + \eta \mathbb{E}_{x,y=y(x),\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) (\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}) (z_j + \langle \xi, \mathbf{M}_j \rangle) \right] \end{aligned}$$

and therefore

$$\begin{aligned} \langle w_i^{(t+1)}, \sum_{j \in [d]} w_j^* \mathbf{M}_j \rangle &\geq \langle w_i^{(t)}, \sum_{j \in [d]} w_j^* \mathbf{M}_j \rangle \cdot (1 - \eta\lambda - \eta\lambda\|w_i^{(t)}\|) - \frac{\eta}{\text{poly}(d)} \\ &\quad + \eta \mathbb{E}_{x,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) (\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}) \langle w^*, z \rangle \right] \\ &\quad - O(\eta) \cdot \sum_{j \in [d]} \left| \mathbb{E}_{x,\rho} \left[y \ell'_t(w^{(t)}; x, y, \rho) (\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}) \langle \xi, \mathbf{M}_j \rangle \right] \right| \end{aligned}$$

Applying Lemma C.14b and using $y \langle w^*, z \rangle = |\langle w^*, z \rangle|$ and $\|w_i^{(t)}\| \leq O(\Xi_2^2)$ (see Lemma C.18), we have

$$\begin{aligned} \langle w_i^{(t+1)}, \sum_{j \in [d]} w_j^* \mathbf{M}_j \rangle &\geq \langle w_i^{(t)}, \sum_{j \in [d]} w_j^* \mathbf{M}_j \rangle \cdot (1 - \eta\lambda - \eta\lambda\|w_i^{(t)}\|) - O\left(\eta \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2 + \frac{\eta}{\text{poly}(d)}\right) \\ &\quad + \eta \mathbb{E}_{x,\rho} \left[\ell'_t(w^{(t)}; x, y, \rho) (\mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} + \mathbf{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}}) |\langle w^*, z \rangle| \right] \\ &\geq \langle w_i^{(t)}, \sum_{j \in [d]} w_j^* \mathbf{M}_j \rangle \cdot (1 - \eta\lambda - \eta\lambda\|w_i^{(t)}\|) - O\left(\eta \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2 + \frac{\eta}{\text{poly}(d)}\right) \\ &\quad + \eta \mathbb{E}_{x,\rho} \left[\ell'_t(w^{(t)}; x, y, \rho) \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} |\langle w^*, z \rangle| \right]. \end{aligned}$$

□

Proof of Lemma E.2. Recall Claim E.3 says that

$$\begin{aligned} \sum_{i \in \mathcal{S}} \langle w_i^{(t+1)}, \mathbf{M}w^* \rangle &\geq \sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle \cdot (1 - \eta\lambda - \eta\lambda\|w_i^{(t)}\|) - O\left(\eta |\mathcal{S}| \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right) \\ &\quad + \eta \mathbb{E}_{x,\rho} \left[\ell'_t(w^{(t)}; x, y, \rho) |\langle w^*, z \rangle| \sum_{i \in \mathcal{S}} \mathbf{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq b^{(t)}} \right] \end{aligned}$$

Using $\mathcal{S}_{j,sure}^{(0)} \subseteq \mathcal{S}_{j,sure+}^{(t)}$, and a similar analysis to Lemma C.16, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$ it satisfies $\sum_{i \in \mathcal{S}} \mathbb{1}_{\langle w_i^{(s)}, x \rangle + \rho_i \geq b^{(s)}} \geq \Omega(k)$. Therefore, the above inequality gives

$$\begin{aligned} \sum_{i \in \mathcal{S}} \langle w_i^{(t+1)}, \mathbf{M}w^* \rangle &\geq \sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle \cdot (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|) - O\left(\eta|\mathcal{S}| \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right) \\ &\quad + \Omega(\eta k) \cdot \mathbb{E}_{x, \rho} \left[\ell'_i(w^{(t)}; x, y, \rho) |\langle w^*, z \rangle| \right] \end{aligned}$$

Now, using small ball probability Lemma H.1a we have

$$\Pr \left[|\langle w^*, z \rangle| \leq 0.01 \mathbb{E}[\ell'_s(w^{(t)}; x, y, \rho)] \right] \leq \frac{1}{2} \mathbb{E}[\ell'_s(w^{(t)}; x, y, \rho)] + O\left(\frac{1}{\sqrt{k}}\right).$$

Therefore, let us abbreviate by writing $\ell'_s = \ell'_s(w^{(t)}; x, y, \rho)$, then

$$\begin{aligned} &\mathbb{E} \left[\ell'_s(w^{(t)}; x, y, \rho) \cdot |\langle w^*, z \rangle| \right] \\ &\geq \mathbb{E} \left[\ell'_s \cdot |\langle w^*, z \rangle| \mid |\langle w^*, z \rangle| \geq 0.01 \mathbb{E}[\ell'_s] \right] \cdot \Pr \left[|\langle w^*, z \rangle| \geq 0.01 \mathbb{E}[\ell'_s] \right] \\ &\geq 0.01 \mathbb{E}[\ell'_s] \cdot \mathbb{E} \left[\ell'_s \mid |\langle w^*, z \rangle| \geq 0.01 \mathbb{E}[\ell'_s] \right] \cdot \Pr \left[|\langle w^*, z \rangle| \geq 0.01 \mathbb{E}[\ell'_s] \right] \\ &= 0.01 \mathbb{E}[\ell'_s] \cdot \left(\mathbb{E}[\ell'_s] - \mathbb{E} \left[\ell'_s \mid |\langle w^*, z \rangle| < 0.01 \mathbb{E}[\ell'_s] \right] \right) \cdot \Pr \left[|\langle w^*, z \rangle| < 0.01 \mathbb{E}[\ell'_s] \right] \\ &\geq 0.01 \mathbb{E}[\ell'_s] \cdot \left(\mathbb{E}[\ell'_s] - \Pr \left[|\langle w^*, z \rangle| < 0.01 \mathbb{E}[\ell'_s] \right] \right) \\ &\geq 0.01 \mathbb{E}[\ell'_s] \cdot \left(\frac{1}{2} \mathbb{E}[\ell'_s] - O\left(\frac{1}{\sqrt{k}}\right) \right) \stackrel{\textcircled{1}}{\geq} \frac{1}{\Xi_2^5} \end{aligned}$$

where the last inequality $\textcircled{1}$ uses Lemma C.18 and Lemma C.19.

Therefore, using $|\mathcal{S}| \leq d\Xi_2$, we have

$$\begin{aligned} \sum_{i \in \mathcal{S}} \langle w_i^{(t+1)}, \mathbf{M}w^* \rangle &\geq \sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle \cdot (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|) - O\left(\eta|\mathcal{S}| \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right) + \Omega\left(\frac{\eta k}{\Xi_2^5}\right) \\ &\geq \sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle \cdot (1 - O(\eta\lambda \Xi_2^2)) + \Omega\left(\frac{\eta k}{\Xi_2^5}\right) \end{aligned}$$

so we conclude for every $t \geq \Omega\left(\frac{1}{\eta\lambda \Xi_2^2}\right)$ it satisfies

$$\sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle \geq \Omega\left(\frac{kd}{\Xi_2^7}\right).$$

As for any arbitrary $i \in [m]$, we have

$$\begin{aligned} \langle w_i^{(t+1)}, \mathbf{M}w^* \rangle &\geq \langle w_i^{(t)}, \mathbf{M}w^* \rangle \cdot (1 - \eta\lambda - \eta\lambda \|w_i^{(t)}\|) - O\left(\eta \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right) \\ &\geq \dots \geq -O\left(\frac{1}{\lambda} \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right). \quad \square \end{aligned}$$

E.2 Proof of Theorem E.1

Proof of Theorem E.1. For every $i \in \mathcal{S}_{j,sure+}^{(t)}$, we know with probability at least $1 - e^{-\Omega(\log^2 d)}$, it satisfies that

$$\mathbb{1}_{\langle w_i^{(t)}, x \rangle + \rho_i \geq 10b^{(t)}} = \mathbb{1}_{w_j^* z_j > 0} \quad \text{and} \quad \mathbb{1}_{-\langle w_i^{(t)}, x \rangle + \rho_i \geq 10b^{(t)}} = \mathbb{1}_{w_j^* z_j < 0}$$

Therefore, setting $\delta = \delta_0 \mathbf{M}w^*$ for some $\delta_0 \in (0, \frac{\beta}{\sqrt{d}})$, we have $|\langle w_i^{(t)}, \delta \rangle| \leq \delta_0 \Xi_2^2 \sqrt{d} \leq b^{(t)}$

$$\begin{aligned} & \sum_{i \in \mathcal{S}} \text{ReLU}(\langle w_i^{(t)}, x - \delta \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x - \delta \rangle + \rho_i - b^{(t)}) \\ &= \sum_{i \in \mathcal{S}} \text{ReLU}(\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \underbrace{\sum_{i \in \mathcal{S}} (\mathbb{1}_{w_{j_i}^* z_{j_i} > 0} + \mathbb{1}_{w_{j_i}^* z_{j_i} < 0}) \langle w_i^{(t)}, \delta \rangle}_{\clubsuit} \end{aligned}$$

where $j_i \in [d]$ is the unique index such that $i \in \mathcal{S}_{j_i, \text{sure}+}^{(t)}$. We can rewrite the decrement

$$\clubsuit = \delta_0 \sum_{j \in [d]} (\mathbb{1}_{w_j^* z_j > 0} + \mathbb{1}_{w_j^* z_j < 0}) \sum_{i \in \mathcal{S}_{j, \text{sure}+}^{(t)}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle$$

Using $|\sum_{i \in \mathcal{S}_{j, \text{sure}+}^{(t)}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle| \leq \Xi_2^3 \sqrt{d}$ and $(\mathbb{1}_{w_j^* z_j > 0} + \mathbb{1}_{w_j^* z_j < 0}) = 1$ with probability $\Theta(\frac{k}{d})$, we can apply Bernstein's inequality and derive

$$\Pr \left[|\clubsuit - \mathbb{E}_z[\clubsuit]| > \delta_0 \cdot \Xi_2^3 \sqrt{kd} \log d \right] \leq e^{-\Omega(\log^2 d)}$$

Also using $(\mathbb{1}_{w_j^* z_j > 0} + \mathbb{1}_{w_j^* z_j < 0}) = 1$ with probability $\Theta(\frac{k}{d})$, we can derive using Lemma E.2 that

$$\begin{aligned} \mathbb{E}_z[\clubsuit] &\geq \delta_0 \cdot \left(\Omega\left(\frac{k}{d}\right) \sum_{i \in \mathcal{S}} \langle w_i^{(t)}, \mathbf{M}w^* \rangle - O(k\Xi_2) \cdot \frac{k^2}{\lambda d^{1.5}} \sigma_x^2 \right) \\ &\geq \delta_0 \cdot \left(\Omega\left(\frac{k^2}{\Xi_2^7}\right) - O(k\Xi_2) \cdot \frac{1}{\lambda} \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2 \right) \geq \delta_0 \cdot \Omega\left(\frac{k^2}{\Xi_2^7}\right) \end{aligned}$$

Combining the above equations and using $k > d^{(1-c_0)/3}$, we have with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$\clubsuit \geq \delta_0 \cdot \Omega\left(\frac{k^2}{\Xi_2^7}\right)$$

For the remainder terms, we using $|\langle w_i^{(t)}, \delta \rangle| \leq \delta_0 \Xi_2^2 \sqrt{d} \leq b^{(t)}/2$, we have

$$\begin{aligned} & \sum_{i \in [m] \setminus \mathcal{S}} \text{ReLU}(\langle w_i^{(t)}, x - \delta \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x - \delta \rangle + \rho_i - b^{(t)}) \\ &\leq \sum_{i \in [m] \setminus \mathcal{S}} \text{ReLU}(\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \underbrace{\sum_{i \in [m] \setminus \mathcal{S}} \mathbb{1}_{|\langle w_i^{(t)}, x \rangle + \rho_i| > \frac{b^{(t)}}{2}} \min\left\{0, \langle w_i^{(t)}, \delta \rangle\right\}}_{\spadesuit} \end{aligned}$$

Using Lemma E.2 and Lemma C.16 we have with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$\spadesuit \geq -\delta_0 \cdot O\left(\frac{1}{\lambda} \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right) \cdot \sum_{i \in [m] \setminus \mathcal{S}} \mathbb{1}_{|\langle w_i^{(t)}, x \rangle + \rho_i| > \frac{b^{(t)}}{2}} \geq -\delta_0 \cdot O\left(\frac{1}{\lambda} \frac{k^3 \Xi_2^4}{d^2} \sigma_x^2\right) \cdot O(k\Xi_2) \geq -\frac{\clubsuit}{2}.$$

Putting together the bounds for \clubsuit and \spadesuit we have

$$\begin{aligned} f_t(x - \delta) &= \sum_{i \in [m]} \text{ReLU}(\langle w_i^{(t)}, x - \delta \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x - \delta \rangle + \rho_i - b^{(t)}) \\ &\leq \sum_{i \in [m]} \text{ReLU}(\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \text{ReLU}(-\langle w_i^{(t)}, x \rangle + \rho_i - b^{(t)}) - \frac{\clubsuit}{2} \leq f_t(x) - \delta_0 \cdot \Omega\left(\frac{k^2}{\Xi_2^7}\right) \end{aligned}$$

In other words, choosing $\delta_0 = \frac{\Xi_2^{10}}{k^2}$, then combining with $|f_t(x)| \leq O(\Xi_2^2 \log d)$ from Lemma C.18,

we immediately have $f_t(x - \delta) < 0$.

Using an analogous proof, one can also show that $f_t(x + \delta) > 0$. Therefore, if we choose a perturb direction $-\delta_0 y \mathbf{M} w^* = -y \delta$, we have

$$\Pr_{x, y=y(x), \rho} \left[\text{sign}(f_t(x - \delta_0 y \mathbf{M} w^*)) = y \right] \leq e^{-\Omega(\log^2 d)} .$$

This means the robust accuracy is below $e^{-\Omega(\log^2 d)}$. Finally, using $\|\mathbf{M} w^*\|_2 \leq O(\sqrt{d})$ and $\|\mathbf{M} w^*\|_\infty \leq O(\sum_{j \in [d]} \|\mathbf{M}_j\|_\infty) = O(\|\mathbf{M}\|_1)$ finishes the proof.

Note that a similar proof as above also shows

$$\Pr_{x, y=y(x)} \left[\text{sign}\left(\mathbb{E}_\rho[f_t(x - \delta_0 y \mathbf{M} w^*)]\right) = y \right] \leq e^{-\Omega(\log^2 d)} . \quad \square$$

F Robust Training Through Local Feature Purification

Suppose we run clean training for $T_f \geq \Omega(\frac{d^{\Xi_2^6}}{\eta})$ iterations following Theorem D.1. From this iteration on, let us perform T more steps of robust training.

During the robust training phase, let us consider an arbitrary (norm-bounded) adversarial perturbation algorithm A . Recall from Definition 4.1 that, given the current network f (which includes hidden weights $\{w_i\}$, output weights $\{a_i\}$, bias $\{b_i\}$ and smoothing parameter σ_ρ), an input x , a label y , and some internal random string r , the perturbation algorithm A outputs a vector satisfying

$$\|A(f, x, y, r)\|_p \leq \tau .$$

for some ℓ_p norm. Our two main theorems below apply to all such perturbation algorithms A (including the Fast Gradient Method, FGM).

Theorem F.1 (ℓ_2 -adversarial training). *In the same setting as Theorem D.1, suppose we first run T_f iterations of clean training with $\Omega(\frac{d^{\Xi_2^6}}{\eta}) \leq T_f \leq d^{O(\log d)}/\eta$ and obtain*

$$\mathbf{Obj}_{clean} = \mathbb{E}_{x, y=y(x), \rho} [\mathbf{Obj}_{T_f}(w^{(T_f)}; x, y, \rho)] \leq o(1) .$$

Next, suppose $\sigma_x \leq \min\{O(1), \frac{d^{2(1-2c_0)}}{k^{5.5}}\}$ and $k^{2.5} < d^{1-2c_0}/\log d$. Starting from iteration T_f , suppose we perform robust training for additional $T = T_g = \Theta(\frac{k^2 \Xi_2^4 m \log d}{\eta d}) \leq O(\frac{k^2}{d^{1-2c_0}})$ iterations, against some ℓ_2 perturbation algorithm A with radius $\tau \stackrel{\text{def}}{=} \frac{1}{\sqrt{k \cdot d^{c_0}}}$. With probability $\geq 1 - e^{-\Omega(\log^2 d)}$,

$$\frac{1}{T} \sum_{t=T_f}^{T_f+T-1} \mathbb{E}_{x, y=y(x), \delta=A(f_t, x, y, \rho), \rho} [\mathbf{Obj}_t(w^{(t)}; x + \delta, y, \rho)] \leq \mathbf{Obj}_{clean} + o(1)$$

Corollary F.2. *In Theorem F.1, if A is Fast Gradient Method (FGM) with ℓ_2 radius τ , and*

$$\mathbb{E}_{x, y=y(x), \delta=A(f_t, x, y), \rho} [\mathbf{Obj}_t(w^{(t)}; x + \delta, y, \rho)] \leq o(1)$$

for some $t \in [T_f, T_f + T_g]$. Then,

$$\Pr_{x, y=y(x)} \left[\exists \delta \in \mathbb{R}^d, \|\delta\|_2 \leq \tau : \text{sign}\left(\mathbb{E}_\rho f_t(w^{(t)}; x + \delta, \rho)\right) \neq y \right] \leq o(1) .$$

Corollary F.3. *Consider for instance $\sigma_x = 0$, $c_0 = 0.00001$, and sufficiently large $d > 1$.*

- *For $k \in [d^{0.0001}, d^{0.3999}]$, robust training gives 99.9% accuracy against ℓ_2 perturbation $\geq \frac{1}{k^{0.5} \cdot d^{0.0001}}$.*

- For $k \geq d^{0.3334}$, clean training gives 0.01% accuracy against ℓ_2 perturbation radius $\leq \frac{d^{0.5001}}{k^2}$.
- For $k \in [d^{0.3334}, d^{0.3999}]$, robust training provably beats clean training in ℓ_2 robust accuracy.

Theorem F.4 (ℓ_∞ -adversarial training). *In the same setting as Theorem D.1, suppose we first run T_f iterations of clean training with $\Omega(\frac{d\Xi_2^6}{\eta}) \leq T_f \leq d^{O(\log d)}/\eta$ and obtain*

$$\mathbf{Obj}_{\text{clean}} = \mathbb{E}_{x,y=y(x),\rho} [\mathbf{Obj}_{T_f}(w^{(T_f)}; x, y, \rho)] \leq o(1) .$$

Next, suppose $\sigma_x \leq O(1)$ and $k^{2.5} < d^{1-2c_0}/\log d$. Starting from iteration T_f , suppose we perform robust training for additional $T = T_g = \Theta(\frac{k^2\Xi_2^4 m \log d}{\eta d}) \leq O(\frac{k^2}{d^{1-2c_0}})$ iterations, against some ℓ_∞ perturbation algorithm A of radius $\tau \stackrel{\text{def}}{=} \frac{1}{k^{1.75} \cdot \|\mathbf{M}\|_\infty \cdot d^{c_0}}$. Then, with probability $\geq 1 - e^{-\Omega(\log^2 d)}$,

$$\frac{1}{T} \sum_{t=T_f}^{T_f+T-1} \mathbb{E}_{x,y=y(x),\delta=A(f_t,x,y,r),\rho} [\mathbf{Obj}_t(w^{(t)}; x + \delta, y, \rho)] \leq \mathbf{Obj}_{\text{clean}} + o(1)$$

Corollary F.5. *In Theorem F.4, if A is Fast Gradient Method (FGM) with ℓ_∞ radius τ , and*

$$\mathbb{E}_{x,y=y(x),\delta=A(f_t,x,y),\rho} [\mathbf{Obj}_t(w^{(t)}; x + \delta, y, \rho)] \leq o(1)$$

for some $t \in [T_f, T_f + T_g]$. Then,

$$\Pr_{x,y=y(x)} \left[\exists \delta \in \mathbb{R}^d, \|\delta\|_\infty \leq \tau : \text{sign}(\mathbb{E}_\rho f_t(w^{(t)}; x + \delta, \rho)) \neq y \right] \leq o(1) .$$

Corollary F.6.

- For $k \in [d^{0.0001}, d^{0.3999}]$, robust training gives 99.9% accuracy against ℓ_∞ perturbation $\geq \frac{1}{k^{1.75} \cdot d^{0.0001} \cdot \|\mathbf{M}\|_\infty}$.
- For $k \geq d^{0.3334}$, clean training gives 0.01% accuracy against ℓ_∞ perturbation $\leq \frac{d^{0.0001} \|\mathbf{M}\|_1}{k^2}$.
- For $k \in [d^{0.3334}, d^{0.3999}]$ and when $\|\mathbf{M}\|_\infty, \|\mathbf{M}\|_1 \leq d^{0.1248}$, robust training provably beats clean training in ℓ_∞ robust accuracy.

Remark F.7. With additional efforts, one can also prove that Theorem F.1 and Theorem F.4 holds with high probability for all T in the range $T = \Theta(T_g)$. We do not prove it here since it is not beyond the scope of this paper.

F.1 Some Notations

We first note some simple structural properties that are corollaries of Theorem C.2.

Proposition F.8. *At iteration $t = T_f$, for every neuron $i \in [m]$, we can write*

$$w_i^{(t)} \stackrel{\text{def}}{=} g_i + u_i \stackrel{\text{def}}{=} \sum_{j \in \mathcal{S}_i} \alpha_{i,j} \mathbf{M}_j + u_i$$

where $\mathcal{S}_i \subseteq \{j \in [d] \mid i \in \mathcal{S}_{j,\text{pot}}^{(0)}\}$ with $|\mathcal{S}_i| = O(1)$, $|\alpha_{i,j}| \leq O(\Xi_2^2)$ and $\max_{j \in [d]} \{|\langle u_i, \mathbf{M}_j \rangle|\} = \frac{k\Xi_2^2}{d}$.

Proof. We can let $\alpha_{i,j} = \langle w_i^{(t)}, \mathbf{M}_j \rangle$ and let u_i be the remaining part. We have $|\mathcal{S}_i| \leq O(1)$ because $\mathcal{S}_{\text{ept}}^{(0)} = [m]$. We have $|\alpha_{i,j}| = |\langle w_i^{(t)}, \mathbf{M}_j \rangle| \leq \|w_i^{(t)}\| \leq O(\Xi_2^2)$. We also have

$$\max_{j \in [d]} \{|\langle u_i, \mathbf{M}_j \rangle|\} = \max_{j \in [d]: i \notin \mathcal{S}_{j,\text{pot}}^{(0)}} \{|\langle w_i^{(t)}, \mathbf{M}_j \rangle|\} \leq \frac{k}{d\beta} b^{(t)} \leq \frac{k\Xi_2^2}{d} . \quad \square$$

We next introduce an important notation that shall be used throughout the proofs of this section.

Definition F.9. For every $t \geq T_{\dagger}$, we write $w_i^{(t)} = g_i + v_i^{(t)}$ by defining $v_i^{(t)} \stackrel{\text{def}}{=} w_i^{(t)} - g_i$.

F.2 Robust Coupling

Definition F.10 (robust coupling). At every iteration t , recalling $w_i^{(t)} = g_i + v_i^{(t)}$, we define a linear function in μ

$$g_t(\mu; x, x_0, \rho) = \sum_{i=1}^m \left(\mathbb{1}_{\langle g_i + v_i^{(t)}, x_0 \rangle + \rho_i \geq b^{(t)}} \cdot (\langle g_i + \mu_i, x \rangle + \rho_i - b^{(t)}) \right. \\ \left. - \mathbb{1}_{-\langle g_i + v_i^{(t)}, x_0 \rangle + \rho_i \geq b^{(t)}} \cdot (-\langle g_i + \mu_i, x \rangle + \rho_i - b^{(t)}) \right)$$

and it equals the output of the real network at point $\mu = v^{(t)}$ both on its zero and first order:

$$g_t(\mu; x + \delta, x + \delta, \rho) \Big|_{\mu=v^{(t)}} = f_t(w; x + \delta, \rho) \Big|_{w=w^{(t)}} \\ \nabla_{\mu} g_t(\mu; x + \delta, x + \delta, \rho) \Big|_{\mu=v^{(t)}} = \nabla_w f_t(w; x + \delta, \rho) \Big|_{w=w^{(t)}}$$

We shall show in this section that, recalling $w^{(t)} = g + v^{(t)}$, then

$$g_t(v^{(t)}; x + \delta, x, \rho) \approx f_t(w^{(t)}; x + \delta, \rho) \\ g_t(0; x + \delta, x, \rho) \approx f_t(w^{(T_{\dagger})}, x, \rho)$$

However, as regarding how close they are, it depends on whether we have an ℓ_2 bound or ℓ_{∞} bound on δ , so we shall prove the two cases separately in Section F.2.1 and F.2.2.

It is perhaps worth nothing that the ‘‘closeness’’ of the above terms depend on two things,

- One is regarding how small $\sum_{i \in [m]} \|v_i^{(t)}\|_2^2$ is, and this shall later be *automatically* guaranteed via implicit regularization of first-order methods.
- The other is regarding how small $\|v_i^{(t)}\|_2$ or $\|v_i^{(t)}\|_1$ is for *every* individual neuron $i \in [m]$. This is a bit non-trivial to prove, and we shall spend the entire Section F.3 to deal with this.

F.2.1 Robust Coupling for ℓ_2 Perturbation

Lemma F.11. Suppose at iteration t , $\sum_{i \in [m]} \|v_i^{(t)}\|_2^2 \leq r^2 m$ for some $r \leq 1$, and suppose $\max_{i \in [m]} \|v_i^{(t)}\|_2 \leq r'$. Then for any vector $\delta \in \mathbb{R}^d$ that can depend on x (but not on ρ) with $\|\delta\|_2 \leq \tau$ for some $\tau \leq o(\frac{b}{\Xi_2^2 + r'})$, we have

$$\mathbb{E}_{x, \rho} \left[\left| g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}; x + \delta, \rho) \right| \right] \leq O(\tau^2) \cdot \left(\frac{\Xi_2^5}{\sigma_{\rho}} + \frac{(\Xi_2^2 + r')^2 r^2 m}{db^2 \sigma_{\rho}} \right)$$

As a corollary, in the event of $r \leq O\left(\frac{k\Xi_2^2}{\sqrt{d}}\right)$ and $r' \leq 1$ and using $m = d^{1+c_0}$, we have

$$\mathbb{E}_{x, \rho} \left[\left| g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}; x + \delta, \rho) \right| \right] \leq O(\tau^2) \cdot \left(\frac{\Xi_2^5}{\sigma_{\rho}} + \frac{k^{3.5}}{d^{1-2c_0}} \right)$$

Proof of Lemma F.11. Let us abbreviate the notations by setting $v_i = v_i^{(t)}$ and $b = b^{(t)}$.

To upper bound $|g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}; x + \delta, \rho)|$ it suffices to upper bound $|V_1 - V_2|$ for

$$\begin{aligned} V_1 &:= \sum_{i \in [m]} (\langle g_i + v_i, x + \delta \rangle + \rho_i - b) \mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} \\ V_2 &:= \sum_{i \in [m]} (\langle g_i + v_i, x + \delta \rangle + \rho_i - b) \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \end{aligned}$$

(and one also needs to take into account the reverse part, whose proof is analogous).

We first make some calculations. Using the definition of g_i , we have $\Pr_x[\langle g_i, x \rangle \geq |b|/10] \leq O(\frac{k}{d})$ for every $i \in [m]$. Thus, we can easily calculate that¹⁸

$$\mathbb{E}_x \left[\sum_{i \in [m]} \langle v_i, \delta \rangle^2 \mathbb{1}_{\langle g_i, x \rangle \geq |b|/10} \right] \leq \tau^2 \sum_{i \in [m]} \|v_i\|^2 \mathbb{E}_x [\mathbb{1}_{\langle g_i, x \rangle \geq |b|/10}] = O\left(\tau^2 \cdot r^2 m \cdot \frac{k}{d}\right) \quad (\text{F.1})$$

$$\begin{aligned} \mathbb{E}_x \left[\sum_{i \in [m]} (\langle v_i, \delta \rangle^2 + \langle g_i, \delta \rangle^2) \mathbb{1}_{\langle v_i, x \rangle \geq |b|/10} \right] &\leq \tau^2 \cdot O(\Xi_2^4 + (r')^2) \sum_{i \in [m]} \mathbb{E}_x [\mathbb{1}_{\langle v_i, x \rangle \geq |b|/10}] \\ &\leq \tau^2 \cdot O((\Xi_2^2 + r')^2) \cdot \sum_{i \in [m]} O\left(\mathbb{E}_x \frac{\langle v_i, x \rangle^2}{b^2}\right) \\ &= O\left(\tau^2 (\Xi_2^2 + r')^2 \cdot \frac{r^2 m}{db^2}\right) \end{aligned} \quad (\text{F.2})$$

$$\sum_{i \in [m]} \langle g_i, \delta \rangle^2 \mathbb{1}_{\langle g_i, x \rangle \geq |b|/10} \leq \sum_{i \in [m]} \langle g_i, \delta \rangle^2 \leq \tau^2 \left\| \sum_{i \in [m]} g_i g_i^\top \right\|_{\text{spectral-norm}} \leq O(\tau^2 \Xi_2^5) \quad (\text{F.3})$$

Now, for every $i \in [m]$,

- Case 1, $|\langle v_i, x \rangle| \leq \frac{b}{10}$ and $|\langle g_i, x \rangle| \leq \frac{b}{10}$ both happen. In this case, it must satisfy $|\langle g_i + v_i, \delta \rangle| \leq (\|g_i\| + \|v_i\|) \cdot \tau \leq O(\Xi_2^2 + r') \cdot \tau \leq \frac{b}{10}$. Also, with probability at least $1 - e^{-\Omega(\log^2 d)}$, it satisfies $|\rho_i| \leq \frac{b}{10}$. To sum up, with high probability we have

$$\mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} = \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} = 0$$

- Case 2, either $|\langle v_i, x \rangle| > \frac{b}{10}$ or $|\langle g_i, x \rangle| > \frac{b}{10}$. In this case, to satisfy $\mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} \neq \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}$, one must have $|\langle g_i + v_i, x + \delta \rangle - b + \rho_i| \leq |\langle v_i, \delta \rangle| + |\langle g_i, \delta \rangle|$. Also, using the randomness of ρ_i , we have

$$\Pr_{\rho_i} [\mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} \neq \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}] \leq O\left(\frac{|\langle v_i, \delta \rangle| + |\langle g_i, \delta \rangle|}{\sigma_\rho}\right)$$

Together, we have

$$\mathbb{E}_{x, \rho, \delta} [|V_1 - V_2|] \leq \mathbb{E}_{x, \delta, \rho} \left[\sum_{i \in [m]} (|\langle v_i, \delta \rangle| + |\langle g_i, \delta \rangle|) |\mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} - \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}| \right]$$

¹⁸Here, the spectral norm bound of $\sum_{i \in [m]} g_i g_i^\top$ holds for the following reason. Each g_i is a sparse vector supported only on $|\mathcal{S}_i| = O(1)$ coordinates, and thus $g_i g_i^\top \preceq \mathbf{D}_i$ holds for a diagonal matrix \mathbf{D}_i that where $[\mathbf{D}_i]_{j,j} = \|g_i\|^2 \leq O(\Xi_2^4)$ for $j \in \mathcal{S}_i$ and $[\mathbf{D}_i]_{j,j} = 0$ otherwise. Now, using the fact that $|\mathcal{S}_{j, \text{pot}}^{(0)}| \leq \Xi_2$, we immediately have that $\mathbf{D}_1 + \dots + \mathbf{D}_m \preceq O(\Xi_2^5) \cdot \mathbf{I}_{d \times d}$.

$$\begin{aligned}
&\leq O(1) \cdot \mathbb{E}_{x,\delta,\rho} \left[\sum_{i \in [m]} \frac{\langle v_i, \delta \rangle^2 + \langle g_i, \delta \rangle^2}{\sigma_\rho} (\mathbb{1}_{\langle v_i, x \rangle \geq |b|/10} + \mathbb{1}_{\langle g_i, x \rangle \geq |b|/10}) \right] + \frac{1}{\text{poly}(d)} \quad (\text{F.4}) \\
&\leq O(\tau^2) \cdot \left(\frac{\Xi_2^5}{\sigma_\rho} + \frac{kr^2m}{d\sigma_\rho} + \frac{(\Xi_2^2 + r')^2 r^2 m}{db^2 \sigma_\rho} \right) \\
&\leq O(\tau^2) \cdot \left(\frac{\Xi_2^5}{\sigma_\rho} + \frac{(\Xi_2^2 + r')^2 r^2 m}{db^2 \sigma_\rho} \right). \quad \square
\end{aligned}$$

Lemma F.12. Suppose at iteration t , $\max_{i \in [m], j \in [d]} \{|\langle u_i, \mathbf{M}_j \rangle|\} \leq \frac{r}{\sqrt{d}}$ and $\sum_{i \in [m]} \|v_i^{(t)}\|_2^2 \leq r^2 m$ with $r \leq 1$. Then for any vector $\delta \in \mathbb{R}^d$ that can depend on x (but not on ρ) with $\|\delta\|_2 \leq \tau$, we have

$$\mathbb{E}_{x,\rho} [|g_t(0; x + \delta, x, \rho) - f_t(w^{(T_t)}, x, \rho)|] \leq O \left(\frac{mr^2}{d\sigma_\rho} + k\Xi_2 \frac{r \log d}{\sqrt{d}} + \tau \Xi_2^3 \sqrt{k\Xi_2 + \frac{r^2 m}{db^2}} \right)$$

As a corollary, in the event of $r \leq O\left(\frac{k\Xi_2^2}{\sqrt{d}}\right)$ and using $m = d^{1+c_0}$, we have

$$\mathbb{E}_{x,\rho} [|g_t(0; x + \delta, x, \rho) - f_t(w^{(T_t)}, x, \rho)|] \leq O \left(\frac{k^{2.5}}{d^{1-2c_0}} + \tau \cdot \sqrt{k\Xi_2^7} \right)$$

Proof of Lemma F.12. To upper bound $|g_t(0; x + \delta, x, \rho) - f_t(v^{(T_t)}, x)|$ it suffices to upper bound $|V_3 - V_4|$ for

$$\begin{aligned}
V_3 &:= \sum_{i \in [m]} (\langle g_i, x + \delta \rangle - b + \rho_i) \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \\
V_4 &:= \sum_{i \in [m]} (\langle g_i + u_i, x \rangle - b + \rho_i) \mathbb{1}_{\langle g_i + u_i, x \rangle + \rho_i \geq b}
\end{aligned}$$

(and one also needs to take into account the reverse part, whose proof is analogous).

Let us first define

$$V_5 := \sum_{i \in [m]} (\langle g_i, x \rangle - b + \rho_i) \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}$$

Let us define $s = \sum_{i \in [m]} \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}$. By the properties that (1) g_i is only supported on \mathcal{S}_i with $|\mathcal{S}_i| \leq O(1)$, (2) for each $j \in [d]$ at most Ξ_2 of the g_i are supported on i , and (3) $\|g_i\|_2 \leq O(\Xi_2^2)$, we can obtain

$$\mathbb{E}_{x,\rho} \left\| \sum_{i \in [m]} g_i \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \right\|_2 \leq O(\Xi_2^3) \mathbb{E}_{x,\rho} [\sqrt{s}] \leq O(\Xi_2^3) \sqrt{\mathbb{E}_{x,\rho} [s]}$$

At the same time, we know

$$\begin{aligned}
\mathbb{E}_{x,\rho} [s] &\leq \mathbb{E}_{x,\rho} \left[\sum_{i \in [m]} \mathbb{1}_{\langle g_i, x \rangle \geq \frac{b}{4}} + \mathbb{1}_{\langle v_i, x \rangle \geq \frac{b}{4}} \right] + \frac{1}{\text{poly}(d)} \leq O(k\Xi_2) + O \left(\sum_{i \in [m]} \frac{\mathbb{E}[\langle v_i, x \rangle^2]}{b^2} \right) \\
&\leq O \left(k\Xi_2 + r^2 m \cdot \frac{1}{db^2} \right)
\end{aligned}$$

Putting them together, we have

$$\mathbb{E}_{x,\rho} |V_3 - V_5| \leq \tau \cdot \mathbb{E}_{x,\rho} \left\| \sum_{i \in [m]} g_i \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \right\|_2 \leq O \left(\tau \Xi_2^3 \sqrt{k \Xi_2 + \frac{r^2 m}{db^2}} \right) \quad (\text{F.5})$$

Next, let us define

$$V_6 := \sum_{i \in [m]} (\langle g_i, x \rangle - b + \rho_i) \mathbb{1}_{\langle g_i, x \rangle + \rho_i \geq b}$$

Using a similar analysis to (F.4), we have

$$\begin{aligned} \mathbb{E}_{x,\rho} |V_5 - V_6| &\leq \mathbb{E}_{x,\rho} \sum_{i \in [m]} |\langle g_i, x \rangle - b + \rho_i| \cdot |\mathbb{1}_{\langle g_i, x \rangle + \rho_i \geq b} - \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}| \\ &\leq \mathbb{E}_{x,\rho} \sum_{i \in [m]} |\langle v_i, x \rangle| \mathbb{E}[|\mathbb{1}_{\langle g_i, x \rangle + \rho_i \geq b} - \mathbb{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}|] \\ &\leq O \left(\mathbb{E}_{x,\rho} \frac{\langle v_i, x \rangle^2}{\sigma_\rho} \right) \leq O \left(\frac{r^2 m}{d \sigma_\rho} \right) \end{aligned} \quad (\text{F.6})$$

Finally, we also have

$$\begin{aligned} \mathbb{E}_{x,\rho} |V_6 - V_4| &= \mathbb{E}_{x,\rho} \left| \sum_{i \in [m]} (\langle g_i + u_i, x \rangle - b + \rho_i) \mathbb{1}_{\langle g_i + u_i, x \rangle + \rho_i \geq b} - (\langle g_i, x \rangle - b + \rho_i) \mathbb{1}_{\langle g_i, x \rangle + \rho_i \geq b} \right| \\ &\leq \mathbb{E}_{x,\rho} \left| \sum_{i \in [m]} \langle u_i, x \rangle \mathbb{1}_{\langle g_i + u_i, x \rangle + \rho_i \geq b} \right| + \mathbb{E}_{x,\rho} \left| \sum_{i \in [m]} (\langle g_i, x \rangle - b + \rho_i) (\mathbb{1}_{\langle g_i + u_i, x \rangle + \rho_i \geq b} - \mathbb{1}_{\langle g_i, x \rangle + \rho_i \geq b}) \right| \\ &\stackrel{\textcircled{1}}{\leq} \mathbb{E}_{x,\rho} \sum_{i \in [m]} |\langle u_i, x \rangle| \mathbb{1}_{\langle g_i + u_i, x \rangle + \rho_i \geq b} + O \left(\frac{mr^2}{d \sigma_\rho} \right) \\ &\stackrel{\textcircled{2}}{\leq} \mathbb{E}_{x,\rho} \sum_{i \in [m]} |\langle u_i, x \rangle| (\mathbb{1}_{\langle g_i, x \rangle \geq b/4} + \mathbb{1}_{\langle u_i, x \rangle \geq b/4}) + O \left(\frac{mr^2}{d \sigma_\rho} \right) + \frac{1}{\text{poly}(d)} \end{aligned}$$

Above, inequality $\textcircled{1}$ is due to a similar analysis as (F.6), and inequality $\textcircled{2}$ is because $|\rho_i| \leq b/4$ with probability at least $1 - e^{-\Omega(\log^2 d)}$. Next, let us recall $\langle u_i, \mathbf{M}_j \rangle \leq \frac{r}{\sqrt{d}}$ and thus, by Bernstein's inequality, with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$|\langle u_i, x \rangle| \leq O \left(\frac{r \log^2 d}{\sqrt{d}} \right) \ll \frac{b}{4}.$$

Putting this back we have

$$\mathbb{E}_{x,\rho} |V_6 - V_4| \leq O \left(\frac{mr^2}{d \sigma_\rho} + k \Xi_2 \frac{r \log d}{\sqrt{d}} \right)$$

Combining the bounds on $|V_6 - V_4|$, $|V_3 - V_5|$, and $|V_5 - V_6|$ finishes the proof. \square

F.2.2 Robust Coupling for ℓ_∞ Perturbation

Lemma F.13. *Suppose at iteration t , $\sum_{i \in [m]} \|v_i^{(t)}\|_2^2 \leq r^2 m$ for some $r \leq 1$, and suppose $\max_{i \in [m]} \|v_i^{(t)}\|_1 \leq r'$. Then for any vector $\delta \in \mathbb{R}^d$ that can depend on x (but not on ρ) with $\|\delta\|_\infty \leq \tau$ for some*

$\tau \leq o\left(\frac{b}{\Xi_2^2 + r'}\right)$, we have

$$\mathbb{E}_{x,\rho} \left[\left| g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}; x + \delta, \rho) \right| \right] \leq O(\tau^2) \cdot \left(\frac{k\Xi_2^5}{\sigma_\rho} + \frac{(\Xi_2^2 + r')^2 r^2 m}{db^2 \sigma_\rho} + \frac{(r')^2 k\Xi_2}{\sigma_\rho} \right)$$

As a corollary, in the event of $r \leq O\left(\frac{k\Xi_2^2}{\sqrt{d}}\right)$ and $r' \leq O(k\Xi_2^2 \cdot \|\mathbf{M}\|_\infty)$ and using $m = d^{1+c_0}$, we have

$$\mathbb{E}_{x,\rho} \left[\left| g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}; x + \delta, \rho) \right| \right] \leq O(\tau^2) \cdot k^{3.5} d^{c_0} \cdot \|\mathbf{M}\|_\infty^2$$

Proof of Lemma F.13. The proof is analogous to Lemma F.11 so we only highly the differences. In fact, we only need to change (F.1), (F.2) and (F.3) with the following calculations.

Using the definition of g_i , we have $\Pr_x[\langle g_i, x \rangle \geq |b|/10] \leq O\left(\frac{k}{d}\right)$ for every $i \in [m]$ as well as $\sum_{i \in [m]} \mathbb{E}_x[\mathbb{1}_{\langle g_i, x \rangle \geq |b|/10}] \leq O(k\Xi_2)$. Thus, we can easily calculate that¹⁹

$$\begin{aligned} \mathbb{E}_x \left[\sum_{i \in [m]} \langle v_i, \delta \rangle^2 \mathbb{1}_{\langle g_i, x \rangle \geq |b|/10} \right] &\leq \tau^2 \sum_{i \in [m]} (r')^2 \mathbb{E}_x[\mathbb{1}_{\langle g_i, x \rangle \geq |b|/10}] = O(\tau^2 \cdot (r')^2 \cdot k\Xi_2) \\ \mathbb{E}_x \left[\sum_{i \in [m]} (\langle v_i, \delta \rangle^2 + \langle g_i, \delta \rangle^2) \mathbb{1}_{\langle v_i, x \rangle \geq |b|/10} \right] &\leq \tau^2 \cdot O(\Xi_2^4 + (r')^2) \sum_{i \in [m]} \mathbb{E}_x[\mathbb{1}_{\langle v_i, x \rangle \geq |b|/10}] \\ &\leq \tau^2 \cdot O((\Xi_2^2 + r')^2) \cdot \sum_{i \in [m]} O\left(\mathbb{E}_x \frac{\langle v_i, x \rangle^2}{b^2}\right) \\ &= O\left(\tau^2 (\Xi_2^2 + r')^2 \cdot \frac{r^2 m}{db^2}\right) \\ \mathbb{E}_x \left[\sum_{i \in [m]} \langle g_i, \delta \rangle^2 \mathbb{1}_{\langle g_i, x \rangle \geq |b|/10} \right] &\leq O(\tau^2 \Xi_2^4) \sum_{i \in [m]} \mathbb{E}_x[\mathbb{1}_{\langle g_i, x \rangle \geq |b|/10}] \leq O(\tau^2 k\Xi_2^5) \end{aligned}$$

Putting those into the rest of the proof (to replace (F.1), (F.2) and (F.3)) finishes the proof. \square

Lemma F.14. Suppose at iteration t , $\max_{i \in [m], j \in [d]} \{|\langle u_i, \mathbf{M}_j \rangle|\} \leq \frac{r}{\sqrt{d}}$ and $\sum_{i \in [m]} \|v_i^{(t)}\|_2^2 \leq r^2 m$ with $r \leq 1$. Then for any vector $\delta \in \mathbb{R}^d$ that can depend on x (but not on ρ) with $\|\delta\|_\infty \leq \tau$, we have

$$\mathbb{E}_{x,\rho} \left[\left| g_t(0; x + \delta, x, \rho) - f_t(w^{(T_t)}; x, \rho) \right| \right] \leq O\left(\frac{mr^2}{d\sigma_\rho} + k\Xi_2 \frac{r \log d}{\sqrt{d}} + \tau \Xi_2^3 \left(k\Xi_2 + \frac{r^2 m}{db^2}\right)\right)$$

As a corollary, in the event of $r \leq O\left(\frac{k\Xi_2^2}{\sqrt{d}}\right)$ and using $m = d^{1+c_0}$, we have

$$\mathbb{E}_{x,\rho} \left[\left| g_t(0; x + \delta, x, \rho) - f_t(w^{(T_t)}; x, \rho) \right| \right] \leq O\left(\frac{k^{2.5}}{d^{1-2c_0}} + \tau \cdot k\Xi_2^4\right)$$

Proof of Lemma F.14. The proof is analogous to Lemma F.12 so we only highly the differences.

¹⁹Here, the spectral norm bound of $\sum_{i \in [m]} g_i g_i^\top$ holds for the following reason. Each g_i is a sparse vector supported only on $|\mathcal{S}_i| = O(1)$ coordinates, and thus $g_i g_i^\top \preceq \mathbf{D}_i$ holds for a diagonal matrix \mathbf{D}_i that where $[\mathbf{D}_i]_{j,j} = \|g_i\|^2 \leq O(\Xi_2^4)$ for $j \in \mathcal{S}_i$ and $[\mathbf{D}_i]_{j,j} = 0$ otherwise. Now, using the fact that $|\mathcal{S}_{j,pot}^{(0)}| \leq \Xi_2$, we immediately have that $\mathbf{D}_1 + \dots + \mathbf{D}_m \preceq O(\Xi_2^5) \cdot \mathbf{I}_{d \times d}$.

Recall we have defined

$$\begin{aligned}
V_3 &:= \sum_{i \in [m]} (\langle g_i, x + \delta \rangle - b + \rho_i) \mathbf{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \\
V_4 &:= \sum_{i \in [m]} (\langle g_i + u_i, x \rangle - b + \rho_i) \mathbf{1}_{\langle g_i + u_i, x \rangle + \rho_i \geq b} \\
V_5 &:= \sum_{i \in [m]} (\langle g_i, x \rangle - b + \rho_i) \mathbf{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \\
V_6 &:= \sum_{i \in [m]} (\langle g_i, x \rangle - b + \rho_i) \mathbf{1}_{\langle g_i, x \rangle + \rho_i \geq b}
\end{aligned}$$

The bounds on $\mathbb{E} |V_5 - V_6|$ and $\mathbb{E} |V_6 - V_4|$ state exactly the same comparing to Lemma F.12 (because they do not have δ involved). Let us now recalculate the difference $|V_3 - V_5|$.

Let us define $s = \sum_{i \in [m]} \mathbf{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b}$. By the properties that (1) g_i is only supported on \mathcal{S}_i with $|\mathcal{S}_i| \leq O(1)$, (2) for each $j \in [d]$ at most Ξ_2 of the g_i are supported on i , and (3) $\|g_i\|_2 \leq O(\Xi_2^2)$, we can obtain

$$\mathbb{E}_{x, \rho} \left\| \sum_{i \in [m]} g_i \mathbf{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \right\|_1 \leq O(\Xi_2^3) \mathbb{E}_{x, \rho} [s]$$

At the same time, we know

$$\begin{aligned}
\mathbb{E}_{x, \rho} [s] &\leq \mathbb{E}_{x, \rho} \left[\sum_{i \in [m]} \mathbf{1}_{\langle g_i, x \rangle \geq \frac{b}{4}} + \mathbf{1}_{\langle v_i, x \rangle \geq \frac{b}{4}} \right] + \frac{1}{\text{poly}(d)} \leq O(k\Xi_2) + O\left(\sum_{i \in [m]} \frac{\mathbb{E}[\langle v_i, x \rangle^2]}{b^2} \right) \\
&\leq O\left(k\Xi_2 + r^2 m \cdot \frac{1}{db^2} \right)
\end{aligned}$$

Putting them together, we have

$$\mathbb{E}_{x, \rho, \delta} |V_3 - V_5| \leq \tau \cdot \mathbb{E}_{x, \rho} \left\| \sum_{i \in [m]} g_i \mathbf{1}_{\langle g_i + v_i, x \rangle + \rho_i \geq b} \right\|_1 \leq O\left(\tau \Xi_2^3 \left(k\Xi_2 + \frac{r^2 m}{db^2} \right) \right)$$

Using this new bound on $\mathbb{E}[V_3 - V_5]$ to replace the old one (F.5), the rest of the proof follows. \square

F.3 Individual Neuron Growth Lemma

As mentioned earlier, the purpose of this section is to upper bound $\max_{i \in [m]} \|v_i^{(T_i+T)}\|_2$ (if it is ℓ_2 perturbation) or $\max_{i \in [m]} \|v_i^{(T_i+T)}\|_1$ (if it is ℓ_∞ perturbation) during the course of robust training. We have two subsections to deal with the two cases.

F.3.1 Growth Lemma for ℓ_2 Perturbation

We first bound $\|v_i^{(t)}\|_2$ during ℓ_2 robust training.

Lemma F.15 (movement bound). *Suppose at iteration t , $\max_{i \in [m]} \|v_i\|_2 \leq r'$. Let $\ell \in [-1, 1]$ be any random variable that can depend on x, ρ , and $\delta \in \mathbb{R}^d$ be any random vector that can depend on x with $\|\delta\|_2 \leq \tau$. Then, for every $i \in [m]$,*

$$\left\| \mathbb{E}_{x, y=y(x), \rho} [\ell \mathbf{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b(x + \delta)}] \right\|_2 \leq O\left(\left(\frac{k}{d} + \frac{(r')^2 \log d}{db^2} \right) \tau + \frac{\sqrt{k}}{d} + \frac{(r')^2}{db^2} \left(\frac{\sqrt{k}}{\sqrt{d}} + \sigma_x \log d \right) + \frac{r'}{db} \right)$$

As a corollary, suppose we run robust training from iteration T_f to $T_f + T$ with $T\eta \leq o(db)$, $\tau \leq \frac{1}{\sqrt{k} \log d}$ and $\sigma_x \leq o\left(\frac{d^2 b^2}{(T\eta)^2 \sqrt{k} \log d}\right)$, then

$$\max_{i \in [m]} \|v_i^{(T_f+T)}\|_2 \leq O\left(\frac{k\Xi_2^2}{\sqrt{d}} + T\eta \cdot \frac{\sqrt{k}}{d}\right) \leq o(1)$$

Proof of Lemma F.15. First of all we can reuse the analysis of (F.4) and derive that

$$\begin{aligned} \Pr[\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b] &\leq \frac{1}{\text{poly}(d)} + \Pr[\langle g_i, x \rangle \geq |b|/10] + \Pr[\langle v_i, x \rangle \geq |b|/10] \\ &\leq O\left(\frac{k}{d} + \frac{(r')^2}{db^2}\right) =: \kappa \end{aligned}$$

This immediately gives

$$\|\mathbb{E}[\ell \mathbf{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b\delta}]\|_2 \leq \tau \cdot \mathbb{E}[\mathbf{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b}] \leq \kappa\tau.$$

Next, in order to bound the norm of $\phi \stackrel{\text{def}}{=} \mathbb{E}[\ell \mathbf{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b}x]$, we first inner product it with \mathbf{M}_j for each $j \in [d]$. This gives

$$\begin{aligned} |\langle \phi, \mathbf{M}_j \rangle| &= |\mathbb{E}[\ell \mathbf{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} \langle x, \mathbf{M}_j \rangle]| \\ &\leq \mathbb{E}[(\mathbf{1}_{\langle g_i, x \rangle \geq b/10} + \mathbf{1}_{\langle v_i, x \rangle \geq b/10}) \cdot |\langle x, \mathbf{M}_j \rangle|] + \frac{1}{\text{poly}(d)} \\ &\leq \mathbb{E}[(\mathbf{1}_{\langle g_i, x \rangle \geq b/10} + \mathbf{1}_{\langle v_i, x - \mathbf{M}_j z_j \rangle \geq b/20} + \mathbf{1}_{\langle v_i, \mathbf{M}_j z_j \rangle \geq b/20}) \cdot |\langle x, \mathbf{M}_j \rangle|] + \frac{1}{\text{poly}(d)} \end{aligned} \quad (\text{F.7})$$

We bound the three terms separately.

- For the first term,

$$\mathbb{E}[\mathbf{1}_{\langle g_i, x \rangle \geq b/10} \cdot |\langle x, \mathbf{M}_j \rangle|] \leq \mathbb{E}[\mathbf{1}_{\langle g_i, x \rangle \geq b/10} \cdot (|z_j| + O(\frac{\log d}{\sqrt{d}}))] \leq \mathbb{E}[\mathbf{1}_{\langle g_i, x \rangle \geq b/10} \cdot |z_j|] + O(\frac{k \log d}{d^{1.5}})$$

Using the property of g_i we have $\mathbf{1}_{\langle g_i, x \rangle \geq b/10} \leq \sum_{j' \in \mathcal{S}_i} \mathbf{1}_{z_{j'} \neq 0}$ for $|\mathcal{S}_i| \leq O(1)$ and therefore

$$\mathbb{E}[\mathbf{1}_{\langle g_i, x \rangle \geq b/10} \cdot |z_j|] \leq \mathbb{E}\left[\sum_{j' \in \mathcal{S}_i} \mathbf{1}_{z_{j'} \neq 0} \cdot |z_j|\right] = \begin{cases} \sqrt{k}/d, & \text{if } j \in \mathcal{S}_i; \\ k^{1.5}/d^2, & \text{if } j \notin \mathcal{S}_i. \end{cases}$$

Therefore, we have

$$\sum_{j \in [d]} (\mathbb{E}[\mathbf{1}_{\langle g_i, x \rangle \geq b/10} \cdot |\langle x, \mathbf{M}_j \rangle|])^2 \leq O\left(\frac{k}{d^2}\right) \quad (\text{F.8})$$

- For the second term,

$$\begin{aligned} \mathbb{E}\left[\mathbf{1}_{\langle v_i, x - \mathbf{M}_j z_j \rangle \geq b/20} \cdot |\langle x, \mathbf{M}_j \rangle|\right] &= \mathbb{E}\left[\mathbf{1}_{\langle v_i, x - \mathbf{M}_j z_j \rangle \geq b/20} \cdot |z_j + \langle \mathbf{M}_j, \xi \rangle|\right] \\ &\leq \mathbb{E}\left[\mathbf{1}_{\langle v_i, x - \mathbf{M}_j z_j \rangle \geq b/20}\right] \cdot O\left(\mathbb{E}[|z_j|] + \frac{\log d}{\sqrt{d}} \sigma_x\right) \\ &\leq O\left(\frac{\mathbb{E}[\langle v_i, x - \mathbf{M}_j z_j \rangle^2]}{b^2}\right) \cdot O\left(\frac{\sqrt{k}}{d} + \frac{\log d}{\sqrt{d}} \sigma_x\right) \\ &\leq O\left(\frac{(r')^2}{db^2}\right) \cdot O\left(\frac{\sqrt{k}}{d} + \frac{\log d}{\sqrt{d}} \sigma_x\right) \end{aligned}$$

and therefore

$$\sum_{j \in [d]} \left(\mathbb{E} \left[\mathbf{1}_{\langle v_i, x - \mathbf{M}_j z_j \rangle \geq b/20} \cdot |\langle x, \mathbf{M}_j \rangle| \right] \right)^2 \leq O \left(\frac{(r')^4}{d^2 b^4} \right) \cdot \left(\frac{k}{d} + \sigma_x^2 \log^2 d \right) \quad (\text{F.9})$$

• For the third term,

$$\begin{aligned} \mathbb{E}[\mathbf{1}_{\langle v_i, \mathbf{M}_j \rangle z_j \geq b/20} \cdot |\langle x, \mathbf{M}_j \rangle|] &\leq \mathbb{E} \left[\mathbf{1}_{\langle v_i, \mathbf{M}_j \rangle z_j \geq b/20} \cdot \left(|z_i| + O\left(\frac{\log d}{\sqrt{d}}\right) \right) \right] \\ &\leq \mathbb{E} \left[\left(\frac{|\langle v_i, \mathbf{M}_j \rangle z_j|}{b} \cdot |z_i| + \frac{|\langle v_i, \mathbf{M}_j \rangle z_j|}{b} \cdot O\left(\frac{\log d}{\sqrt{d}}\right) \right) \right] \\ &\leq |\langle v_i, \mathbf{M}_j \rangle| \cdot O \left(\frac{1}{db} + \frac{\sqrt{k} \log d}{bd^{1.5}} \right) \leq |\langle v_i, \mathbf{M}_j \rangle| \cdot O \left(\frac{1}{db} \right) \end{aligned}$$

and therefore

$$\sum_{j \in [d]} \left(\mathbb{E}[\mathbf{1}_{\langle v_i, \mathbf{M}_j \rangle z_j \geq b/20} \cdot |\langle x, \mathbf{M}_j \rangle|] \right)^2 \leq O \left(\frac{(r')^2}{d^2 b^2} \right) \quad (\text{F.10})$$

Putting (F.7), (F.8), (F.9), (F.10) these together, we have

$$\|\phi\|^2 \leq \sum_{j \in [d]} |\langle \phi, \mathbf{M}_j \rangle|^2 \leq O \left(\frac{k}{d^2} + \frac{(r')^4}{d^2 b^4} \left(\frac{k}{d} + \sigma_x^2 \log^2 d \right) + \frac{(r')^2}{d^2 b^2} \right)$$

Summing everything up, we have

$$\left\| \mathbb{E}_{x, y=y(x), \rho} [\ell \mathbf{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} (x + \delta)] \right\|_2 \leq O \left(\left(\frac{k}{d} + \frac{(r')^2}{db^2} \right) \tau + \frac{\sqrt{k}}{d} + \frac{(r')^2}{db^2} \left(\frac{\sqrt{k}}{\sqrt{d}} + \sigma_x \log d \right) + \frac{r'}{db} \right)$$

Now, suppose we run robust training for $t = T_f, T_f + 1, \dots, T_f + T - 1$ and suppose for all of them we have $\|v_i^{(T)}\|_2 \leq r'$ satisfied. Then, using the gradient update formula (see e.g. (C.19))

$$\|v_i^{(T_f+T)}\|_2 \leq \|v_i^{(T_f)}\|_2 + T\eta \cdot O \left(\left(\frac{k}{d} + \frac{(r')^2}{db^2} \right) \tau + \frac{\sqrt{k}}{d} + \frac{(r')^2}{db^2} \left(\frac{\sqrt{k}}{\sqrt{d}} + \sigma_x \log d \right) + \frac{r'}{db} \right)$$

This means, in order to show $\|v_i^{(T_f+T)}\|_2 \leq r'$ we can choose any $r' > 0$ satisfying

$$O \left(\frac{k\Xi_2^2}{\sqrt{d}} \right) + T\eta \cdot O \left(\left(\frac{k}{d} + \frac{(r')^2}{db^2} \right) \tau + \frac{\sqrt{k}}{d} + \frac{(r')^2}{db^2} \left(\frac{\sqrt{k}}{\sqrt{d}} + \sigma_x \log d \right) + \frac{r'}{db} \right) \leq r' .$$

Using the assumption of $T\eta \leq o(db)$ (which also implies $(T\eta)^2 \leq o(\frac{d^{2.5}b^2}{k})$), $\tau \leq \frac{1}{\sqrt{k} \log d}$ (which also implies $\tau \leq o(\frac{d^2 b^2}{(T\eta)^2 \sqrt{k} \log d})$), and $\sigma_x \leq o(\frac{d^2 b^2}{(T\eta)^2 \sqrt{k} \log d})$, we can choose

$$r' \leq O \left(\frac{k\Xi_2^2}{\sqrt{d}} \right) + T\eta \cdot O \left(\frac{\sqrt{k}}{d} \right) .$$

□

F.3.2 Growth Lemma for ℓ_∞ Perturbation

We now bound $\|v_i^{(t)}\|_1$ during ℓ_∞ robust training. Recall $\|\mathbf{M}\|_\infty \stackrel{\text{def}}{=} \max_{j \in [d]} \|\mathbf{M}_j\|_1$.

Lemma F.16 (movement bound). *Suppose at iteration t , $\max_{i \in [m]} \|v_i\|_1 \leq r'$. Let $\ell \in [-1, 1]$ be any random variable that can depend on x, ρ , and $\delta \in \mathbb{R}^d$ be any random vector that can depend on x with $\|\delta\|_\infty \leq \tau$. Then, for every $i \in [m]$,*

$$\|\mathbb{E} [\ell \mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} (x + \delta)]\|_1 \leq O\left(\frac{k}{d} + \frac{(r')^2}{db^2}\right) \cdot (\tau d + \|\mathbf{M}\|_\infty \log d)$$

As a corollary, suppose we run robust training from iteration T_{\dagger} to $T_{\dagger} + T$ with $T\eta \leq \frac{db^2}{\|\mathbf{M}\|_\infty^2 k \Xi_2^3}$ and $\tau \leq o\left(\frac{b^2}{T\eta \cdot k \Xi_2^2 \|\mathbf{M}\|_\infty}\right)$, then

$$\max_{i \in [m]} \|v_i^{(T_{\dagger} + T)}\|_1 \leq O(k \Xi_2^2 \cdot \|\mathbf{M}\|_\infty)$$

Proof of Lemma F.16. Similar to the proof of Lemma F.15, and using $\|v_i\|_2 \leq \|v_i\|_1 \leq r'$, we have

$$\begin{aligned} \Pr[\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b] &\leq \frac{1}{\text{poly}(d)} + \Pr[\langle g_i, x \rangle \geq |b|/10] + \Pr[\langle v_i, x \rangle \geq |b|/10] \\ &\leq O\left(\frac{k}{d} + \frac{(r')^2}{db^2}\right) =: \kappa \end{aligned}$$

This implies

$$\|\mathbb{E} [\ell \mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} \delta]\|_1 \leq \kappa \cdot \tau d$$

On the other hand, let us look at $h := \mathbb{E} [\ell \mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} x]$ and set $u = \text{sign}(h) \in \{-1, 1\}^d$. We have

$$\|h\|_1 = \mathbb{E} [\ell \mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} \langle x, u \rangle]$$

Since with probability at least $1 - e^{-\Omega(\log d)}$ it satisfies $|\langle x, u \rangle| = O(\max_{j \in [d]} \|\mathbf{M}_j\|_1 \log d)$, we can conclude that $\|h\|_1 = O(\kappa \|\mathbf{M}\|_\infty \log d)$. Together we have

$$\|\mathbb{E} [\ell \mathbb{1}_{\langle g_i + v_i, x + \delta \rangle + \rho_i \geq b} (x + \delta)]\|_1 \leq O\left(\frac{k}{d} + \frac{(r')^2}{db^2}\right) \cdot (\tau d + \|\mathbf{M}\|_\infty \log d)$$

Now, suppose we run robust training for $t = T_{\dagger}, T_{\dagger} + 1, \dots, T_{\dagger} + T - 1$ and suppose for all of them we have $\|v_i^{(T)}\|_1 \leq r'$ satisfied. Then, using the gradient update formula (see e.g. (C.19))

$$\|v_i^{(T_{\dagger} + T)}\|_1 \leq \|v_i^{(T_{\dagger})}\|_1 + T\eta \cdot O\left(\frac{k}{d} + \frac{(r')^2}{db^2}\right) \cdot (\tau d + \|\mathbf{M}\|_\infty \log d)$$

Recalling $|\langle v_i^{(T_{\dagger})}, \mathbf{M}_j \rangle| \leq \frac{k \Xi_2^2}{d}$ from (F.8), we have

$$\|v_i^{(T_{\dagger})}\|_1 = \left\| \sum_{j \in [d]} \langle v_i^{(T_{\dagger})}, \mathbf{M}_j \rangle \cdot \mathbf{M}_j \right\|_1 \leq k \Xi_2^2 \cdot \|\mathbf{M}\|_\infty$$

This means, to prove that $\|v_i^{(T_{\dagger})}\|_1 \leq r'$, we can choose any r' satisfying

$$k \Xi_2^2 \cdot \|\mathbf{M}\|_\infty + T\eta \cdot O\left(\frac{k}{d} + \frac{(r')^2}{db^2}\right) \cdot (\tau d + \|\mathbf{M}\|_\infty \log d) \leq r'$$

and using the assumption of $T\eta \leq \frac{db^2}{\|\mathbf{M}\|_\infty^2 k \Xi_2^3}$ (which implies $T\eta \leq O(d)$), and $\tau \leq o\left(\frac{b^2}{T\eta \cdot k \Xi_2^2 \|\mathbf{M}\|_\infty}\right)$ (which implies $\tau \leq \frac{1}{\eta T}$), we can choose

$$r' \leq 2k \Xi_2^2 \cdot \|\mathbf{M}\|_\infty + T\eta \cdot O(\tau k) \leq O(k \Xi_2^2 \cdot \|\mathbf{M}\|_\infty) \quad \square$$

F.4 Robust Convergence

We are now ready to prove the main convergence theorem (that is, Theorem F.1 and F.4) for robust learning. Let us first calculate a simple bound:

Claim F.17. $\left| \sum_{i \in [m]} \mathbf{Reg}(g_i) - \mathbf{Reg}(w_i^{(T_f)}) \right| \leq O(k\sqrt{d}\Xi_2^4)$

Proof. Recalling $\|g_i\|_2 \leq O(\Xi_2^2)$ and $\|u_i\| \leq O(\frac{k\Xi_2^2}{\sqrt{d}})$ from Proposition F.8, we have

$$\left| \|g_i\|^3 - \|g_i + u_i\|^3 \right| \leq O(\|u_i\| \cdot (\|u_i\|^2 + \|g_i\|^2)) \leq O\left(\frac{k\Xi_2^4}{\sqrt{d}}\right). \quad \square$$

F.4.1 Robust Convergence for ℓ_2 Perturbation

Proof of Theorem F.1. Since $w_i^{(t+1)} = w_i^{(t)} - \eta \nabla_{w_i} \widetilde{\mathbf{RobObj}}_t(w^{(t)})$, we have the identity

$$\eta \langle \nabla \widetilde{\mathbf{RobObj}}_t(w^{(t)}), w^{(t)} - g \rangle = \frac{\eta^2}{2} \|\nabla \widetilde{\mathbf{RobObj}}_t(w^{(t)})\|_F^2 + \frac{1}{2} \|w^{(t)} - g\|_F^2 - \frac{1}{2} \|w^{(t+1)} - g\|_F^2$$

Applying (a variant of) Lemma A.2 (which requires us to use the Lipschitz continuity assumption on A , see Definition 4.1), we know that by letting

$$\mathbf{RobObj}_t(w) = \mathbb{E}_{x, y=y(x), \delta, \rho} [\mathbf{Obj}_t(w; x + \delta, y, \rho)],$$

it satisfies

$$\eta \langle \nabla \mathbf{RobObj}_t(w^{(t)}), w^{(t)} - g \rangle \leq \eta^2 \cdot \text{poly}(d) + \frac{1}{2} \|w^{(t)} - g\|_F^2 - \frac{1}{2} \|w^{(t+1)} - g\|_F^2 + \frac{\eta}{\text{poly}(d)} \quad (\text{F.11})$$

Let us also define the clean objective and the pseudo objective as follows:

$$\begin{aligned} \mathbf{Obj}_t(w) &= \mathbb{E}_{x, y=y(x), \rho} [\mathbf{Obj}_t(w; x, y, \rho)] \\ \mathbf{RobObj}'_t(\mu) &= \mathbb{E}_{x, y=y(x), \delta, \rho} [\log(1 + e^{-y \cdot g_t(\mu; x + \delta, x, \rho)})] + \lambda \sum_{i \in [m]} \mathbf{Reg}(g_i + \mu_i), \end{aligned}$$

which is a convex function in μ because $g_t(\mu; x + \delta, x, \rho)$ is linear in μ .

Now, we inductively prove that at every iteration $t \in [T_f, T_f + T]$, it satisfies

$$\sum_{i \in [m]} \|v_i^{(t)}\|_2^2 \leq r^2 m \quad \text{for } r = \Theta\left(\frac{k\Xi_2^2}{\sqrt{d}}\right) \quad (\text{F.12})$$

$$\max_{i \in [m]} \|v_i^{(t)}\|_2 \leq r' \quad \text{for } r' = 1 \quad (\text{F.13})$$

In the base case $t = T_f$ this is obvious due to Proposition F.8. Next, suppose (F.12) and (F.13) hold at iteration t . Using the notation $w_i^{(t)} = g_i + v^{(t)}$ and the Lipschitz continuity of $\log(1 + e^t)$, we have²⁰

$$\begin{aligned} \mathbb{E}[\|\mathbf{RobObj}'_t(v^{(t)}) - \mathbf{RobObj}_t(w^{(t)})\|] &\leq \mathbb{E} \left[\left| g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}, x + \delta) \right| \right] \\ &\leq O(\tau^2) \cdot \left(\frac{\Xi_2^5}{\sigma_\rho} + \frac{k^{3.5}}{d^{1-2c_0}} \right) \quad (\text{using Lemma F.11}) \end{aligned}$$

²⁰Note to apply Lemma F.11 we also need to check $\tau \leq o(\frac{b}{\Xi_2^{2+r'}})$ but this is automatically satisfied under our parameter choice $\tau \leq \frac{1}{\sqrt{k \cdot d^{c_0}}}$.

$$\begin{aligned}
&\leq O\left(\frac{1}{\log d}\right) && \text{(using } \tau \leq \frac{1}{\sqrt{k \cdot d^{c_0}}}\text{)} \\
\mathbb{E}[\|\mathbf{RobObj}'_t(0) - \mathbf{Obj}_t(w^{(T_f)})\|] &\leq \mathbb{E}[|g_t(0; x + \delta, x) - f_t(w^{(T_f)}, x)|] + \lambda \left| \sum_{i \in [m]} \mathbf{Reg}(w_i^{(T_f)}) - \mathbf{Reg}(g_i) \right| \\
&\leq O\left(\frac{k^{2.5}}{d^{1-2c_0}} + \tau \sqrt{k \Xi_2^7}\right) + O\left(\frac{k \Xi_2^4 \log d}{\sqrt{d}}\right) \\
&\hspace{10em} \text{(using Lemma F.12 and Claim F.17)} \\
&\leq O\left(\frac{1}{\log d} + \tau \sqrt{k \Xi_2^7}\right) && \text{(using } k^{2.5} < d^{1-2c_0} / \log d\text{)} \\
&\leq O\left(\frac{1}{\log d}\right) && \text{(using } \tau \leq \frac{1}{\sqrt{k \cdot d^{c_0}}}\text{)}
\end{aligned}$$

Therefore, we can bound the left hand side of (F.11) as follows:

$$\begin{aligned}
\langle \nabla \mathbf{RobObj}_t(w^{(t)}), w^{(t)} - g \rangle &= \langle \nabla \mathbf{RobObj}'_t(v^{(t)}), v^{(t)} \rangle \\
&\geq \mathbf{RobObj}'_t(v^{(t)}) - \mathbf{RobObj}'_t(0) \geq \mathbf{RobObj}_t(w^{(t)}) - \mathbf{Obj}_t(w^{(T_f)}) - O\left(\frac{1}{\log d}\right).
\end{aligned}$$

Putting this back to (F.11) and telescoping for $t = T_f, T_f + 1, \dots, T_f + T_0 - 1$ for any $T_0 \leq T$, we have

$$\begin{aligned}
&\frac{1}{T_0} \sum_{t=T_f}^{T_f+T_0-1} \left(\mathbf{RobObj}_t(w^{(t)}) - \mathbf{Obj}_t(w^{(T_f)}) - O\left(\frac{1}{\log d}\right) \right) \\
&\leq \frac{1}{2\eta T_0} \|w^{(T_f)} - g\|_F^2 - \frac{1}{2\eta T_0} \|w^{(T_f+T_0)} - g\|_F^2 \leq \frac{1}{\eta T_0} \cdot O\left(\frac{k^2 \Xi_2^4}{d} m\right) - \frac{1}{2\eta T_0} \|w^{(T_f+T_0)} - g\|_F^2
\end{aligned} \tag{F.14}$$

Inequality (F.14) now implies that

$$\sum_{i \in [m]} \|v_i^{(T_f+T_0)}\|^2 = \|w^{(T_f+T_0)} - g\|_F^2 \leq O\left(\frac{k^2 \Xi_2^4}{d} m\right)$$

so (F.12) holds at iteration $t = T_f + T_0$. We can then also apply Lemma F.15 which ensures (F.13) holds at iteration $t = T_f + T_0$.

Finally, let us go back to (F.14) and choose $T_0 = T = \Theta\left(\frac{k^2 \Xi_2^4 m \log d}{\eta d}\right)$. It implies

$$\frac{1}{T} \sum_{t=T_f}^{T_f+T-1} \left(\mathbf{RobObj}_t(w^{(t)}) - \mathbf{Obj}_t(w^{(T_f)}) - O\left(\frac{1}{\log d}\right) \right) \leq O\left(\frac{1}{\log d}\right)$$

Note that our final choice of T also ensures that the pre-requisite $T\eta \leq o(db)$ and $\tau, \sigma_x \leq o\left(\frac{d^2 b^2}{(T\eta)^2 \sqrt{k} \log d}\right)$ of Lemma F.15 hold. \square

F.4.2 Robust Convergence for ℓ_∞ Perturbation

Proof of Theorem F.4. The proof is nearly identical to that of Theorem F.1. In particular, we want to inductively prove that at every iteration $t \in [T_f, T_f + T]$, it satisfies

$$\sum_{i \in [m]} \|v_i^{(t)}\|_2^2 \leq r^2 m \quad \text{for } r = \Theta\left(\frac{k \Xi_2^2}{\sqrt{d}}\right) \tag{F.15}$$

$$\max_{i \in [m]} \|v_i^{(t)}\|_1 \leq r' \quad \text{for } r' = \Theta(k\Xi_2^2 \cdot \|\mathbf{M}\|_\infty) \quad (\text{F.16})$$

We also need to redo the following calculations:²¹

$$\begin{aligned} \mathbb{E}[|\mathbf{RobObj}'_t(v^{(t)}) - \mathbf{RobObj}_t(w^{(t)})|] &\leq \mathbb{E}\left[|g_t(v^{(t)}; x + \delta, x, \rho) - f_t(w^{(t)}, x + \delta)|\right] \\ &\leq O(\tau^2) \cdot k^{3.5} d^{c_0} \cdot \|\mathbf{M}\|_\infty^2 \quad (\text{using Lemma F.13}) \\ &\leq O\left(\frac{1}{\log d}\right) \quad (\text{using } \tau \leq \frac{1}{k^{1.75} \cdot \|\mathbf{M}\|_\infty \cdot d^{c_0}}) \end{aligned}$$

$$\begin{aligned} \mathbb{E}[|\mathbf{RobObj}'_t(0) - \mathbf{Obj}_t(w^{(T_f)})|] &\leq \mathbb{E}[|g_t(0; x + \delta, x) - f_t(w^{(T_f)}, x)|] + \lambda \left| \sum_{i \in [m]} \mathbf{Reg}(w_i^{(T_f)}) - \mathbf{Reg}(g_i) \right| \\ &\leq O\left(\frac{k^{2.5}}{d^{1-2c_0}} + \tau \cdot k\Xi_2^4\right) + O\left(\frac{k\Xi_2^4 \log d}{\sqrt{d}}\right) \\ &\quad (\text{using Lemma F.14 and Claim F.17}) \\ &\leq O\left(\frac{1}{\log d} + \tau \sqrt{k\Xi_2^7}\right) \quad (\text{using } k^{2.5} < d^{1-2c_0} / \log d) \\ &\leq O\left(\frac{1}{\log d}\right) \quad (\text{using } \tau \leq \frac{1}{k^{1.75} \cdot \|\mathbf{M}\|_\infty \cdot d^{c_0}}) \end{aligned}$$

□

F.5 Fast Gradient Method (FGM) Robust Training

Let us prove Corollary F.2 only for the ℓ_2 case, and the other ℓ_∞ case Corollary F.5 is completely analogous.

Proof of Corollary F.2. At any iteration $t \in [T_f, T_f + T_g]$, consider any perturbation vector $\delta \in \mathbb{R}^d$ which may depend on x but not on ρ , with $\|\delta\|_2 \leq \tau$.

Recall from Lemma F.11 that

$$\mathbb{E}_x \left[\left| \mathbb{E}_\rho g_t(v^{(t)}; x + \delta, x, \rho) - \mathbb{E}_\rho f_t(w^{(t)}; x + \delta, \rho) \right| \right] \leq O(\tau^2) \cdot \left(\frac{\Xi_2^5}{\sigma_\rho} + \frac{k^{3.5}}{d^{1-2c_0}} \right) \leq O\left(\frac{1}{\log^2 d}\right)$$

This means for at least $1 - O(\frac{1}{\log d})$ probability mass of inputs x , we have

$$\left| \mathbb{E}_\rho g_t(v^{(t)}; x + \delta, x, \rho) - \mathbb{E}_\rho f_t(w^{(t)}; x + \delta, \rho) \right| \leq O\left(\frac{1}{\log d}\right)$$

For those choices of x , using the fact that g_t is linear in δ , we also have

$$\begin{aligned} &\mathbb{E}_\rho g_t(v^{(t)}; x + \delta, x, \rho) - \mathbb{E}_\rho f_t(w^{(t)}; x, \rho) \\ &= \mathbb{E}_\rho g_t(v^{(t)}; x + \delta, x, \rho) - \mathbb{E}_\rho g_t(v^{(t)}; x, x, \rho) = \langle \nabla_x \mathbb{E}_\rho g_t(v^{(t)}; x, x, \rho), \delta \rangle \\ &= \langle \nabla_x \mathbb{E}_\rho f_t(w^{(t)}; x, \rho), \delta \rangle \end{aligned}$$

²¹Note to apply Lemma F.13 we also need to check $\tau \leq o(\frac{b}{\Xi_2^2 + r'})$ but this is automatically satisfied under our parameter choice for τ .

Putting them together we have

$$\left[-y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x + \delta, \rho) \right] = \left[-y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x, \rho) - \langle y(x) \nabla_x \mathbb{E}_{\rho} f_t(w^{(t)}; x, \rho), \delta \rangle \right] \pm O\left(\frac{1}{\log d}\right) \quad (\text{F.17})$$

$$\leq \left[-y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x, \rho) - \langle y(x) \nabla_x \mathbb{E}_{\rho} f_t(w^{(t)}; x, \rho), \delta^* \rangle \right] + O\left(\frac{1}{\log d}\right) \quad (\text{F.18})$$

where $\delta^* = A(f_t, x, y)$ is the perturbation obtained by the fast gradient method with ℓ_2 radius τ . This means two things.

On the other hand, by applying Markov's inequality and Jensen's inequality to $\mathbb{E}_{x, y=y(x), \rho} [\mathbf{Obj}_t(w^{(t)}; x + \delta^*, y, \rho)] \leq o(1)$, we know for at least $1 - o(1)$ probability mass of the choices of x , it satisfies

$$\begin{aligned} \log(1 + e^{-y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x + \delta^*, \rho)}) &\leq o(1) \\ \implies -y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x + \delta^*, \rho) &\leq -10 \end{aligned}$$

Therefore, for all of those x (with total mass $\geq 1 - o(1)$) satisfying both, we can first apply (F.17) (with $\delta = \delta^*$) to derive

$$-y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x, \rho) - \langle y(x) \nabla_x \mathbb{E}_{\rho} f_t(w^{(t)}; x, \rho), \delta^* \rangle \leq -9$$

Applying (F.18) then we obtain (for any δ)

$$-y(x) \mathbb{E}_{\rho} f_t(w^{(t)}; x + \delta, \rho) \leq -8$$

This means, the output of the network f_t is robust at point x against *any* perturbation δ with radius τ . We finish the proof of Corollary F.2. \square

G NTK Lower Bound For ℓ_{∞} Perturbation

Recall from Definition 5.5 that the feature mapping of the neural tangent kernel for our two-layer network f is

$$\Phi(x) = \left(x \mathbb{E}_{\rho_i} (\mathbf{1}_{\langle w_i, x \rangle + \rho_i \geq b_i} - \mathbf{1}_{-\langle w_i, x \rangle + \rho_i \geq b_i}) \right)_{i=1}^m$$

Therefore, given weights $\{v_i\}_{i \in [m]}$, the NTK function $p(x)$ is given as

$$p(x) = \sum_{i \in [m]} \langle x, v_i \rangle \mathbb{E}_{\rho_i \sim \mathcal{N}(0, \sigma_{\rho_i}^2)} (\mathbf{1}_{\langle w_i, x \rangle + \rho_i \geq b_i} - \mathbf{1}_{-\langle w_i, x \rangle + \rho_i \geq b_i})$$

To make our lower bound stronger, in this section, we consider the simplest input distribution with $\mathbf{M} = \mathbf{I}$ and $\sigma_x = 0$ (so $\xi \equiv 0$). Our main theorem is the following.

Theorem G.1. *Suppose $w_1, \dots, w_m \in \mathbb{R}^d$ are i.i.d. sampled from $\mathcal{N}(0, \mathbf{I})$ with $m \leq d^C$ for some constant $C > 1$; and suppose $\rho_i \sim \mathcal{N}(0, \sigma_{\rho_i}^2)$ with $|\sigma_{\rho_i}| \leq d^{o(1)}$ and $|b_i| \leq d^{o(1)}$. Then, there exists constant $c_6 > 0$ so that, with probability at least $1 - e^{-\Omega(\log^2 d)}$, choosing $\tau = \frac{1}{d^{c_6}}$, then for any $k \in [d^{\frac{c_6}{100}}, d^{0.5 - \frac{c_6}{100}}]$ and sufficiently large d .*

$$\Pr_{x, y=y(x)} \left[\exists \delta \in \mathbb{R}^d, \|\delta\|_{\infty} \leq \tau : \text{sign}(p(x + \delta)) \neq y \right] \geq \frac{1 - o(1)}{2} .$$

G.1 Proof of Theorem G.1

We first note the following:

Claim G.2. *Suppose at point $z \in \mathbb{R}^d$, some function $p(z)$ gives the correct label $y(z) = \text{sign}(\langle w^*, z \rangle)$ against any ℓ_∞ perturbation of radius τ . Then, letting $\zeta \sim \mathcal{N}(0, \frac{\tau^2}{\log^8 d} \mathbf{I}_{d \times d})$ be a random vector, and $\delta \in \mathbb{R}^d$ be any vector with $\|\delta\|_\infty \leq \tau/2$, it satisfies*

$$\mathbb{E}_\zeta [p(z + \delta + \zeta)] \cdot \text{sign}(\langle w^*, z \rangle) \geq -e^{-\Omega(\log^2 d)} \max_{i \in [m]} \{\|v_i\|_2\}$$

Proof of Claim G.2. With probability at least $1 - e^{-\Omega(\log^2 d)}$ it satisfies $\|\zeta + \delta\|_\infty \leq \tau$. When this happens, we must have $p(z + \delta + \zeta) \cdot \text{sign}(\langle w^*, z \rangle) \geq 0$. \square

Therefore, for the analysis purpose (by sacrificing ℓ_∞ norm radius from τ to $\tau/2$), we can imagine as if the input is *randomly perturbed* by ζ . This serves for the purpose of smoothing the NTK function $p(\cdot)$, which originally has indicator functions in it so may be trickier to analyze.

Next, we define $M_W(x) \stackrel{\text{def}}{=} \max_{i \in [m]} |\langle w_i, x \rangle|$. One can carefully apply the Taylor expansion of the smoothed indicator function (using the randomness of ζ), to derive the following claim. (Detailed proof in Section G.4.)

Claim G.3. *Consider any NTK function $p(x)$ with parameters $\|w_i\|_2 \geq \frac{\sqrt{d}}{2}$, $\|w_i\|_\infty \leq \log^2 d$, $\rho_i \sim \mathcal{N}(0, \sigma_{\rho_i}^2)$ with $|\sigma_{\rho_i}| \leq d^{o(1)}$ and $|b_i| \leq d^{o(1)}$. Suppose $\tau \in [\frac{1}{d^{1/5}}, 1]$, then there exists coefficients $\{c_{i,r}, c'_{i,r}, c''_i\}_{i \in [m], r \geq 0}$ with*

- each $|c_{i,r}|, |c'_{i,r}| \leq O(1)$,
- each $|c'_{i,r}| \leq |c_{i,r}| \cdot O(d^{-0.1r})$,
- each $|c_{i,r}| \geq \Omega(\frac{1}{d^2})$ for every odd constant $r \geq 1$
- each $|c''_i| \leq O(d^{-1/4})$.

so that, for every z with $\|z\|_1 \leq d^{1/4}$ and every δ with $\|\delta\|_\infty \leq \tau/2$ and $M_W(\delta) \leq \tau d^{1/4}$, we have:

$$\begin{aligned} & \mathbb{E}_{\zeta \sim \mathcal{N}(0, \frac{\tau^2}{\log^8 d} \mathbf{I}_{d \times d})} [p(z + \delta + \zeta)] \\ &= \sum_{r \geq 0} \|v_i\|_2 \left(c''_i + \sum_{i \in [m]} \left(c_{i,r} \langle \frac{v_i}{\|v_i\|_2}, z + \delta \rangle + c'_{i,r} \langle \frac{w_i}{\|w_i\|_2}, z + \delta \rangle \right) \left(\frac{\langle w_i, z + \delta \rangle}{\tau \|w_i\|_2} \right)^r \right) \end{aligned}$$

Using the above formula, we can write

$$\begin{aligned} \mathbb{E}_\zeta [p(x + \zeta)] &= \text{CONST} + \sum_{r \geq 0} T_{r+1}(x^{\otimes r+1}) \\ &\text{for } T_{r+1}(x^{\otimes r+1}) \stackrel{\text{def}}{=} \sum_{i \in [m]} \|v_i\|_2 \left\langle c_{i,r} \frac{v_i}{\|v_i\|_2} + c'_{i,r} \frac{w_i}{\|w_i\|_2}, x \right\rangle \left(\frac{\langle w_i, x \rangle}{\tau \|w_i\|_2} \right)^r \end{aligned}$$

Using $|c_{i,r}| \geq \Omega(\frac{1}{d^2})$ for odd constant $r \geq 1$, and $|c'_{i,r}| \leq O(d^{-0.1}) \cdot |c_{i,r}|$, by applying Lemma G.4,²² we know that when $r = 3C + 3$ (say wlog. $3C + 3$ is odd),

$$\|T_{3C+4}\|_F = \Omega \left(\frac{1}{d^3} \max_{i \in [m]} \{\|v_i\|_2\} \right) \quad (\text{G.1})$$

²²Specifically, one should substitute $\|v_i\|_2 (c_{i,r} \frac{v_i}{\|v_i\|_2} + c'_{i,r} \frac{w_i}{\|w_i\|_2})$ as the new v_i when applying Lemma G.4.

Also, for a parameter $q = \sqrt{d}$, let us apply Lemma G.5 to derive

$$\lambda_r \stackrel{\text{def}}{=} \max_{\delta \in \mathbb{R}^d: \|\delta\|_\infty \leq \tau, M_W(\delta) \leq \tau\sqrt{q}} |T_r(\delta^{\otimes r})| \geq \Omega\left(\frac{1}{(\tau)^r} \|T_r\|_F\right) \quad (\text{G.2})$$

Let $R \geq 3C + 3$ be a constant to be chosen later, $\lambda_{\max} = \max_{r < R} \{\lambda_r\}$, and let δ_{\max} be the choice of δ which maximizes the value of λ_{\max} .

Consider the high probability event that $M_W(z) = \tilde{O}(1)$, then using $M_W(\delta_{\max}) \leq \tau\sqrt{q}$, we have

$$\begin{aligned} \left| \sum_{r \geq R} T_{r+1}((z + \delta_{\max})^{\otimes r+1}) \right| &= \left| \sum_{r \geq R} \sum_{i \in [m]} c_{i,r} \langle v_i, z + \delta_{\max} \rangle \left(\frac{\langle w_i, z + \delta_{\max} \rangle}{\tau \|w_i\|_2} \right)^r \right| \\ &\leq d^4 m \max_{i \in [m]} \{\|v_i\|_2\}_{i \in [m]} \sum_{r \geq R} \left(\frac{\tilde{O}(1) + \tau\sqrt{q}}{\tau\sqrt{d}} \right)^r \\ &\leq d^5 m \max_{i \in [m]} \{\|v_i\|_2\}_{i \in [m]} \sum_{r \geq R} \left(\frac{O(1)}{d^{1/4}} \right)^r \end{aligned}$$

When $R \geq 10000(C + 1)$, we have

$$\left| \sum_{r \geq R} T_{r+1}((z + \delta_{\max})^{\otimes r+1}) \right| \leq O\left(\frac{\max_{i \in [m]} \{\|v_i\|_2\}_{i \in [m]}}{d^{100C}}\right) \quad (\text{G.3})$$

Next, for every $s \in [1/2, 1]$, let us define

$$q_{<R}(z, s) := \text{CONST} + \sum_{r < R} T_{r+1}((z + s\delta_{\max})^{\otimes r+1})$$

- On one hand, by applying Lemma G.5 twice for each r , we know for every set of vectors z_1, \dots, z_q with $\|z_i\|_\infty \leq 1$, $M_W(z_i) = \tilde{O}(1)$ and $\text{supp}(z_i) \cap \text{supp}(z_j) = \emptyset$ for $i \neq j$, it satisfies

$$\sum_{j \in [q]} (|q_{<R}(z_j, s) - q_{<R}(0, s)| + |q_{<R}(-z_j, s) - q_{<R}(0, s)|) \leq \sum_{r < R} \tilde{O}\left(\frac{\lambda_{\max}}{\tau^r}\right) \leq \tilde{O}\left(\frac{\lambda_{\max}}{\tau^R}\right)$$

This means by Markov's inequality, for at least $(1 - \frac{1}{\log d})$ fraction of the indices $j \in [q]$, denoting them by $\Lambda \subseteq [q]$, it satisfies

$$|q_{<R}(z_j, s) - q_{<R}(0, s)| + |q_{<R}(-z_j, s) - q_{<R}(0, s)| \leq \frac{1}{q} \tilde{O}\left(\frac{\lambda_{\max}}{\tau^R}\right)$$

- On the other hand, by Claim G.7, we know that there is an $s \in [1/2, 1]$ such that

$$|q_{<R}(0, s)| \geq \Omega(\lambda_{\max})$$

Without loss of generality, suppose $q_{<R}(0, s)$ is positive and $q_{<R}(0, s) \geq \Omega(\lambda_{\max})$.

Combining the two, when $\tau^{10000(C+1)} \geq \frac{1}{d}$, we derive that for those $j \in \Lambda$,

$$q_{<R}(z_j, s) \geq \Omega(\lambda_{\max}) \quad \text{and} \quad q_{<R}(-z_j, s) \geq \Omega(\lambda_{\max})$$

Thus, combining with (G.1), (G.2) and (G.3), we have for those $j \in \Lambda$,

$$\begin{aligned} \mathbb{E}_\zeta[p(z_j + s\delta_{\max} + \zeta)] &= \text{CONST} + \sum_{r \geq 0} T_{r+1}((z_j + s\delta_{\max})^{\otimes r+1}) \geq \Omega\left(\frac{1}{d^4} \max_{i \in [m]} \{\|v_i\|_2\}\right) \\ \mathbb{E}_\zeta[p(-z_j + s\delta_{\max} + \zeta)] &= \text{CONST} + \sum_{r \geq 0} T_{r+1}((-z_j + s\delta_{\max})^{\otimes r+1}) \geq \Omega\left(\frac{1}{d^4} \max_{i \in [m]} \{\|v_i\|_2\}\right) \end{aligned}$$

but according to Claim G.2 (see end of this section), this means the NTK function $p(\cdot)$ outputs the wrong label either z_j or for $-z_j$. Therefore, among those $2q$ data points $z_1, \dots, z_q, -z_1, \dots, -z_q$, at least $50\% \cdot (1 - o(1))$ of them must be wrong under ℓ_2 perturbation with radius τ .

Finally, recall when z is generated from the data distribution, with high probability $z \in \mathbb{R}^d$ is $O(k)$ -sparse. Therefore, we can divide (nearly) all possible choices of z into $q = \sqrt{d} \ll O(d/k)$ groups, in a way that when we generate z_1, \dots, z_q from those groups, they have disjoint support and they together match the overall distribution. Using this argument one can prove that, for at least $50\% \cdot (1 - o(1))$ of the probability mass of z from the data distribution, the prediction must be wrong under ℓ_2 perturbation with radius τ .

This finishes the proof of Theorem G.1 ■

G.2 Tensor Lower Bound

Next, for each degree- r homogenous part of the polynomial expansion of Claim G.3, we can write it as a tensor and lower bound its Frobenius norm as follows.

Lemma G.4. *Suppose $w_1, \dots, w_m \in \mathbb{R}^d$ are i.i.d. sampled from $\mathcal{N}(0, \mathbf{I})$ with $m \leq d^C$ for some constant $C > 0$. Let $v_1, \dots, v_m \in \mathbb{R}^d$ be arbitrary vectors that can depend on the randomness of w_1, \dots, w_m . Let us denote by T_{r+1} the symmetric tensor $\mathbb{R}^{d \times (r+1)} \rightarrow \mathbb{R}$ such that*

$$T_{r+1}(x^{\otimes r+1}) = \sum_{i \in [m]} \langle v_i, x \rangle \left(\frac{\langle w_i, x \rangle}{\|w_i\|_2} \right)^r$$

We have as long as $r \geq 3C$, then w.p. $\geq 1 - e^{-\Omega(\log^2 d)}$ over the randomness of $\{w_i\}_{i \in [m]}$, for every $\{v_i\}_{i \in [m]}$ we have

$$\|T_{r+1}\|_F \geq \Omega \left(\frac{1}{\sqrt{d}} \max_{i \in [m]} \{\|v_i\|_2\} \right)$$

Proof of Lemma G.4. Consider any fixed $j \in [m]$, and some $\gamma \in [-1, 1]$ to be chosen later.

Let us define $x = \frac{w_j}{2\|w_j\|_2} + \gamma \frac{v_j}{2\|v_j\|_2}$ which satisfies $\|x\|_2 \leq 1$. We have

$$\begin{aligned} T_{r+1}(x^{\otimes r+1}) &= \sum_{i \in [m]} \langle v_i, x \rangle \left(\frac{\langle w_i, x \rangle}{\|w_i\|_2} \right)^r \\ &= \sum_{i \in [m] \setminus \{j\}} \langle v_i, x \rangle \left(\frac{\langle w_i, x \rangle}{\|w_i\|_2} \right)^r + \left(\frac{\gamma}{2} \|v_j\|_2 + \frac{\langle v_j, w_j \rangle}{2\|w_j\|_2} \right) \left(\frac{1}{2} + \gamma \frac{\langle w_j, v_j \rangle}{2\|v_j\|_2 \|w_j\|_2} \right)^r \end{aligned}$$

Note that for every $j \neq i$, with probability at least $1 - e^{-\Omega(\log^2 d)}$,

$$\left| \frac{\langle w_i, x \rangle}{\|w_i\|_2} \right| = \left| \frac{\langle w_i, w_j \rangle}{2\|w_i\|_2 \|w_j\|_2} + \gamma \frac{\langle w_i, v_j \rangle}{2\|v_j\|_2 \|w_i\|_2} \right| \leq O \left(\frac{\log d}{\sqrt{d}} + \gamma \right).$$

This implies that as long as $|\gamma| \leq \frac{1}{\sqrt{d}}$,

$$|T_{r+1}(x^{\otimes r+1})| \geq \frac{1}{3^r} \left| \frac{\gamma}{2} \|v_j\|_2 + \frac{\langle v_j, w_j \rangle}{2\|w_j\|_2} \right| - \left(\frac{O(\log d)}{\sqrt{d}} \right)^r m \cdot \max_{i \in [m]} \{\|v_i\|_2\}$$

Since the above lower bound holds for every $|\gamma| \leq \frac{1}{\sqrt{d}}$ and every $j \in [d]$, we immediately know

$$\max_{\|x\|_2 \leq 1} \{T_{r+1}(x^{\otimes r+1})\} \geq \Omega \left(\frac{1}{\sqrt{d}} \max_{i \in [m]} \{\|v_i\|_2\} \right)$$

This implies our bound on the Frobenius norm as well. □

G.3 Tensor Perturbation

We present the following critical lemma, which serves as the major step to prove the non-robustness of Neural Tangent Kernel:

Lemma G.5 (Tensor difference). *For every $m = \text{poly}(d)$, every set of vectors $W = \{w_i\}_{i \in [m]}$ with each $\|w_i\|_2 = O(\sqrt{d})$, for every constant $r > 0$, every $q \in [0, d]$, every symmetric tensor T of degree $r: \mathbb{R}^{d \times r} \rightarrow \mathbb{R}$, for every $\tau > 0$,*

1. *The following is true*

$$\lambda := \max_{\delta \in \mathbb{R}^d: \|\delta\|_\infty \leq \tau, M_W(\delta) \leq \tau\sqrt{q}} |T(\delta^{\otimes r})| \geq \Omega\left(\frac{1}{(\tau)^r} \|T\|_F\right)$$

2. *For every vectors $z_1, \dots, z_q \in \mathbb{R}^d$ with $\|z_i\|_\infty \leq 1$, $M_W(z_i) = \tilde{O}(1)$ and $\text{supp}(z_i) \cap \text{supp}(z_j) = \emptyset$ for $i \neq j$, for every y such that $\|y\|_\infty \leq \tau$ and $M_W(y) \leq \tau\sqrt{q}$, the following holds:*

$$\sum_{i \in [q]} |T(y^{\otimes r}) - T((y + z_i)^{\otimes r})| \leq \tilde{O}\left(\frac{\lambda}{\tau^r}\right)$$

Proof of Lemma G.5. For the first item, we can simply let $\delta \sim \mathcal{N}\left(0, \frac{\tau^2}{\log^2 d}\right)$. This choice of δ satisfies $\|\delta\|_\infty \leq \tau$ and $M_W(\delta) \leq \tau\sqrt{q}$ with high probability. Furthermore, by applying anti-concentration of Gaussian polynomials (see for instance [5, Lemma I.1]), we know with at least constant probability $|T(\delta^{\otimes r})| \geq \frac{\Omega(\|T\|_F)}{\tau^r}$. This proves the first item.

To see the second item, we first note by tensor r -linearity and symmetry,

$$\sum_{i \in [q]} |T(y^{\otimes r}) - T((y + z_i)^{\otimes r})| \leq \sum_{r'=1}^r \binom{r}{r'} \sum_{j \in [q]} |T(z_j^{\otimes r'}, y^{\otimes(r-r')})|$$

and therefore we only need to bound the terms on the right hand side for any fixed $r' \in [r]$.

Define random variable $\{\xi_{i,j}\}_{i \in [r'-1], j \in [q]}$ where each $\xi_{i,j}$ is i.i.d. uniformly at random chosen from $\{-\tau, \tau\}$. Consider arbitrary fixed values $\gamma_j \in \{-1, 1\}$ for $j \in [q]$. Let us define random variables $Z_1, Z_2, \dots, Z_{r'} \in \mathbb{R}^d$ as:

$$\forall i \in [r' - 1]: Z_i := \sum_{j \in [q]} \xi_{i,j} z_j, \quad Z_{r'} := \sum_{j \in [q]} \gamma_j \left(\prod_{i \in [r'-1]} \xi_{i,j} \right) z_j$$

From these notions one can directly calculate that

$$\mathbb{E}_\xi [T(Z_1, Z_2, \dots, Z_{r'}, y^{\otimes(r-r')})] = \tau^{r'} \sum_{j \in [q]} \gamma_j T(z_j^{\otimes r'}, y^{\otimes(r-r')})$$

On the other hand, we have $\|Z_i\|_\infty \leq \tau$ and moreover, using the randomness of $\xi_{i,j}$, we know w.h.p. $|M_W(Z_i)| = \tilde{O}(\tau\sqrt{q})$ for every $i \in [q]$. Hence, by Claim G.8, we know that

$$|\mathbb{E}[T(Z_1, Z_2, \dots, Z_{r'}, y^{\otimes(r-r')})]| = \tilde{O}(\lambda)$$

Putting them together, we have $\left| \sum_{i \in [q]} \gamma_i T(z_i^{\otimes r'}, y^{\otimes(r-r')}) \right| = \tilde{O}\left(\frac{\lambda}{\tau^{r'}}\right)$, and since this holds for every $\gamma_i \in \{-1, 1\}$, we conclude that:

$$\sum_{i \in [q]} |T(z_i^{\otimes r'}, y^{\otimes(r-r')})| = \tilde{O}\left(\frac{\lambda}{\tau^{r'}}\right)$$

Putting this back to the binomial expansion finishes the proof. \square

G.4 Smoothed ReLU Taloy Series: Proof of Claim G.3

We first note the following Taylor expansion formula for smoothed ReLU.

Claim G.6 (smoothed ReLU). *Let $a \geq 0$ be any real and $\rho \sim \mathcal{N}(0, \sigma^2)$ for $\sigma \geq a$. Then, for every $x \in [-a, a]$,*

$$\mathbb{E}_{\rho} [\rho \mathbf{1}_{\rho+x \geq 0}] = \sigma \sum_{i=0}^{\infty} c_{2i} \left(\frac{x}{\sigma}\right)^{2i} \quad \text{and} \quad \mathbb{E}_{\rho} [\mathbf{1}_{\rho+x \geq 0}] = \frac{1}{2} + \sum_{i=0}^{\infty} c'_{2i+1} \left(\frac{x}{\sigma}\right)^{2i+1}$$

where $|c_{2i}| = \Theta\left(\frac{1}{i!}\right)$, $|c'_{2i+1}| = \Theta\left(\frac{1}{(i+1)!}\right)$

Proof of Claim G.6. We can directly calculate that

$$\mathbb{E} [\rho \mathbf{1}_{\rho+x \geq 0}] = \frac{1}{\sqrt{2\pi}\sigma} \int_{\rho \geq -x} \rho e^{-\frac{\rho^2}{2\sigma^2}} d\rho = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2\sigma^2}} \sigma$$

so using Taylor expansion of $e^{-\frac{x^2}{2\sigma^2}}$ we prove the first equation. As for the second equation, we have

$$\mathbb{E} [\mathbf{1}_{\rho+x \geq 0}] = \frac{1}{\sqrt{2\pi}\sigma} \int_{\rho \geq -x} e^{-\frac{\rho^2}{2\sigma^2}} d\rho$$

This implies that

$$\frac{d}{dx} \mathbb{E} [\mathbf{1}_{\rho+x \geq 0}] = -\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}$$

Using Taylor expansion and integrating once, we prove the second equation. \square

We are now ready to prove Claim G.3.

Proof of Claim G.3. Specifically, for each $i \in [m]$, denoting by $x = z + \delta$, we wish to apply Claim G.6 to

$$\begin{aligned} & \mathbb{E}_{\rho_i, \zeta} \langle x + \zeta, v_i \rangle (\mathbf{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} - \mathbf{1}_{-\langle w_i, x + \zeta \rangle + \rho_i \geq b_i}) \\ = & \underbrace{\mathbb{E}_{\rho_i, \zeta} \langle x, v_i \rangle (\mathbf{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} - \mathbf{1}_{-\langle w_i, x + \zeta \rangle + \rho_i \geq b_i})}_{\heartsuit} + \underbrace{\mathbb{E}_{\rho_i, \zeta} \langle \zeta, v_i \rangle (\mathbf{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} - \mathbf{1}_{-\langle w_i, x + \zeta \rangle + \rho_i \geq b_i})}_{\diamond} \end{aligned}$$

Note that $g \stackrel{\text{def}}{=} \langle w_i, \zeta \rangle + \rho_i \sim \mathcal{N}(0, \sigma^2)$ for $\sigma^2 = \frac{\tau^2}{\log^{16} d} \|w_i\|_2^2 + \sigma_{\rho_i}^2 \in \left[\frac{\tau^2}{\log^{16} d} \|w_i\|_2^2, \frac{2\tau^2}{\log^{16} d} \|w_i\|_2^2\right]$.

- We first deal with the \heartsuit part. Using Claim G.6, we have

$$\mathbb{E}_{\rho_i, \zeta} \langle x, v_i \rangle \mathbf{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} = \langle x, v_i \rangle \mathbb{E}_g \mathbf{1}_{\langle w_i, x \rangle - b_i + g \geq 0} = \langle x, v_i \rangle \left(\frac{1}{2} + \sum_{r=0}^{\infty} c'_{2r+1} \left(\frac{\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r+1} \right)$$

for $|c'_{2r+1}| = \Theta\left(\frac{1}{(r+1)!}\right)$. Similarly, we also have

$$- \mathbb{E}_{\rho_i, \zeta} \langle x, v_i \rangle \mathbf{1}_{-\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} = \langle x, v_i \rangle \left(-\frac{1}{2} - \sum_{r=0}^{\infty} c'_{2r+1} \left(\frac{-\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r+1} \right)$$

Putting them together, and using the fact that $b_i \ll d^{-0.2} \ll \sigma$, we can write

$$\begin{aligned} \heartsuit &= \mathbb{E}_{\rho_i, \zeta} \langle x, v_i \rangle \left[\mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} - \mathbb{1}_{-\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} \right] \\ &= \langle x, v_i \rangle \left(\sum_{r=0}^{\infty} c'_{2r+1} \left(\frac{\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r+1} - c'_{2r+1} \left(\frac{-\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r+1} \right) \\ &= \langle x, v_i \rangle \sum_{r \geq 0} c''_r \left(\frac{\langle w_i, x \rangle}{\sigma} \right)^r \end{aligned}$$

for $|c''_{2r}| \leq O\left(\frac{1}{(r)!}\right)$ for every $r \geq 0$ and $|c''_{2r+1}| \geq \Omega\left(\frac{1}{(r+1)!}\right)$.

- Let us now focus on the \diamond part. Let v_i^\parallel be the part of v_i that is parallel to w_i . Then obviously we have

$$\begin{aligned} \mathbb{E}_{\rho_i, \zeta} \langle \zeta, v_i \rangle \mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} &= \mathbb{E}_{\zeta, \rho_i} \langle \zeta, v_i^\parallel \rangle \mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} = \frac{\|v_i^\parallel\|_2}{\|w_i\|_2} \mathbb{E}_{\zeta, \rho_i} \langle \zeta, w_i \rangle \mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} \\ &\stackrel{\textcircled{1}}{=} \frac{\|v_i^\parallel\|_2}{\|w_i\|_2} \mathbb{E}_{\zeta, \rho_i} (\langle \zeta, w_i \rangle + \rho_i) \mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} \pm \|v_i^\parallel\|_2 \cdot O(d^{-1/4}) \end{aligned}$$

Above, the last $\textcircled{1}$ is due to $\sigma_{\rho_i} \leq d^{o(1)}$ and $\|w_i\|_2 \geq \Omega(\sqrt{d})$.

Next, we again treat $g \stackrel{\text{def}}{=} \langle \zeta, w_i \rangle + \rho_i \sim \mathcal{N}(0, \sigma^2)$ and apply Claim G.6. We have

$$\mathbb{E}_{\rho_i, \zeta} (\langle \zeta, w_i \rangle + \rho_i) \mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} = \mathbb{E}_g g \mathbb{1}_{\langle w_i, x \rangle - b_i + g \geq 0} = \sigma \sum_{r=0}^{\infty} c_{2r} \left(\frac{\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r}$$

for $|c_{2r}| = \Theta\left(\frac{1}{r!}\right)$. Putting them together, and doing the same thing for the symmetric part, we have

$$\begin{aligned} \diamond &= \mathbb{E}_{\rho_i, \zeta} \langle \zeta, v_i \rangle \left(\mathbb{1}_{\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} - \mathbb{1}_{-\langle w_i, x + \zeta \rangle + \rho_i \geq b_i} \right) \\ &= \frac{\|v_i^\parallel\|_2 \sigma}{\|w_i\|_2} \sum_{r=0}^{\infty} \left(c_{2r} \left(\frac{\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r} - c_{2r} \left(\frac{-\langle w_i, x \rangle - b_i}{\sigma} \right)^{2r} \right) \pm \|v_i^\parallel\|_2 \cdot O(d^{-1/4}) \\ &\stackrel{\textcircled{1}}{=} \frac{\|v_i^\parallel\|_2 \sigma}{\|w_i\|_2} \sum_{r=1}^{\infty} c'''_r \left(\frac{\langle w_i, x \rangle}{\sigma} \right)^r \pm \|v_i^\parallel\|_2 \cdot O(d^{-1/4}) \\ &= \|v_i^\parallel\|_2 \left\langle \frac{w_i}{\|w_i\|_2}, x \right\rangle \sum_{r=0}^{\infty} c'''_{r+1} \left(\frac{\langle w_i, x \rangle}{\sigma} \right)^r \pm \|v_i^\parallel\|_2 \cdot O(d^{-1/4}) \end{aligned}$$

Above, using the property of $b_i \ll d^{-0.2} \ll \sigma$, equation $\textcircled{1}$ holds for some $|c'''_{2r}| \leq O\left(\frac{d^{-0.1}}{r!}\right)$ and $|c'''_{2r+1}| \leq O\left(\frac{d^{-0.1}}{(r+1)!}\right)$.

Finally, putting the bounds for \heartsuit and \diamond together, and using $\frac{\tau \|w_i\|_2}{\log^8 d} \leq \sigma \leq \tau \|w_i\|_2$, we derive that

$$\heartsuit + \diamond = \|v_i\|_2 \cdot \sum_{r \geq 0} \left(c''_{i,r} \left\langle x, \frac{v_i}{\|v_i\|_2} \right\rangle + c'''_{i,r} \left\langle x, \frac{w_i}{\|w_i\|_2} \right\rangle \right) \left(\frac{\langle w_i, x \rangle}{\tau \|w_i\|_2} \right)^r \pm \|v_i\|_2 \cdot O(d^{-1/4})$$

for $|c''_{i,r}| \leq O(1)$ for every $r \geq 0$, $c''_{i,r} \leq O(d^{-0.1r}) \cdot c'''_{i,r}$ for every $r \geq 0$, and $|c'''_{i,r}| \geq \Omega\left(\frac{1}{d^2}\right)$ for every odd constant $r \geq 1$. This finishes the proof of Claim G.3. \square

G.5 Simple Lemmas

We have the following claim relating polynomial value with its coefficients:

Claim G.7 (low degree polynomial). *Let $p : \mathbb{R} \rightarrow \mathbb{R}$ be a constant-degree polynomial $p(x) = \sum_{r=0}^R c_r x^r$, then there exists $x \in [1/2, 1]$ such that*

$$|p(x)| \geq \Omega \left(\max_{r=0,1,2,\dots,R} |c_r| \right) .$$

Proof of Claim G.7. Let us define $q(x) \stackrel{\text{def}}{=} p(x + \frac{1}{2})$ and write accordingly $q(x) = \sum_{r=0}^R c'_r x^r$. Using the identity formula $\sum_{r=0}^R c'_r x^r = \sum_{r=0}^R c_r (x + 0.5)^r$ we can derive (recalling R is constant)

$$\max_{r=0,1,2,\dots,R} |c'_r| \leq O \left(\max_{r=0,1,2,\dots,R} |c_r| \right)$$

Conversely, by writing $\sum_{r=0}^R c'_r (x-0.5)^r = \sum_{r=0}^R c_r x^r$, we also have the other direction and therefore

$$\max_{r=0,1,2,\dots,R} |c'_r| = \Theta \left(\max_{r=0,1,2,\dots,R} |c_r| \right)$$

Now, notice that $|\frac{d^r}{dx^r} q(x)|_{x=0} = \Theta(|c'_r|)$, so we can apply Markov brother's inequality to derive that

$$\max_{x \in [0,1/2]} |q(x)| \geq \Omega \left(\max_{r=0,1,2,\dots,R} |c'_r| \right) .$$

This finishes the proof. □

Using this Claim, we also have the following claim about symmetric tensor:

Claim G.8 (symmetric tensor norms). *For every constant $r > 0$, every fixed $a_1, a_2 > 0$, every symmetric tensor T of degree r of the form $T : \mathbb{R}^{d \times r} \rightarrow \mathbb{R}$, let*

$$\lambda_1 := \max_{x: \|x\|_\infty \leq a_1, M_W(x) \leq a_2} \{|T(x^{\otimes r})|\}, \quad \lambda_2 := \max_{\{x_i\}_{i \in [r]}: \|x_i\|_\infty \leq a_1, M_W(x_i) \leq a_2} \{|T(x_1, x_2, \dots, x_r)|\}$$

then we have:

$$\lambda_1 \leq \lambda_2 \leq O(\lambda_1)$$

Proof of Claim G.8. $\lambda_1 \leq \lambda_2$ is obvious so let us prove the other direction. Define polynomial

$$p(s) = T \left(\left(x_1 + s^{r+1} x_2 + s^{(r+1)^2} x_3 + \dots + s^{(r+1)^{r-1}} x_r \right)^{\otimes r} \right)$$

The coefficient of $p(s)$ at degree $\sum_{r' \in [r]} (r+1)^{r'-1}$ is $\Theta(T(x_1, x_2, \dots, x_r))$. Thus, applying Claim G.7 and appropriately scaling the operator, we complete the proof. □

H Appendix for Probability Theory

H.1 Small ball probability: The basic property

We also have the following property:

Lemma H.1 (small ball probability, 1-d case).

(a) For every subset $\Lambda \subseteq [d]$, every r , and every $t > 0$,

$$\Pr \left[\left| \sum_{j \in \Lambda} w_j^* \cdot z_j - r \right| \leq t \right] \leq O\left(\frac{t}{\sqrt{|\Lambda|/d}} + \frac{1}{\sqrt{|\Lambda|k/d}}\right)$$

(b) For every subset $\Lambda \subseteq [d]$ with $|\Lambda| \geq \Omega(d)$, and every $t > 0$,

$$\Pr \left[\left| \sum_{j \in \Lambda} w_j^* \cdot z_j \right| \leq t \right] \geq \Omega(t) - O\left(\frac{\log k}{\sqrt{k}}\right)$$

Proof of Lemma H.1. Recall we have $\Pr_{z_j}[z_j \neq 0] \geq \Omega(\frac{k}{d})$ for each $j \in \Lambda$. Let $\Lambda' \subseteq \Lambda$ be the subset of such indices j with non-zero z_j , so by our assumption we have $|z_j| \geq \frac{1}{\sqrt{k}}$ for each $j \in \Lambda'$. By Chernoff bound, with probability at least $1 - e^{-\Omega(|\Lambda|k/d)}$, we know $|\Lambda'| \geq \Omega(\frac{k}{d}) \cdot |\Lambda|$.

Conditioning on such Λ' , by the Littlewood-Offord problem (a.k.a. small ball probability theorem, or anti-concentration for sum of Bernoulli variables, see [27]), we know

$$\Pr \left[\left| \sum_{j \in \Lambda} w_j^* \cdot z_j - r \right| \leq t \mid \mathcal{E} \right] \leq O\left(\frac{\sqrt{kt} + 1}{\sqrt{|\Lambda'|}}\right) = O\left(\frac{\sqrt{kt} + 1}{\sqrt{|\Lambda|k/d}}\right)$$

As for the lower bound, let us denote by $\Lambda'' \subseteq \Lambda$ be the subset of such indices j with non-zero z_j and $|z_j| \leq O(\frac{1}{\sqrt{k}})$. We know with high probability $|\Lambda''| \geq \Omega(k)$. Using $\mathbb{E} \left[\left| \sum_{j \in \Lambda \setminus \Lambda''} w_j^* \cdot z_j \right| \right] \leq O(1)$, we can apply Markov's inequality and get

$$\Pr \left[\left| \sum_{j \in \Lambda \setminus \Lambda''} w_j^* \cdot z_j \right| \leq B \right] \geq 0.6 \quad \text{for some constant } B = O(1)$$

Now, for the sum over Λ'' , we can apply a Wasserstein distance version of the central limit theorem (that can be derived from [104], full statement see [6, Appendix A.2]) to derive that, for a Gaussian variable $g \sim (0, V^2)$ where $V = \sum_{j \in \Lambda''} (w_j^*)^2 \mathbb{E}[(z_j)^2] \geq \Omega(1)$, the Wasserstein distance:

$$\mathcal{W}_2 \left(\sum_{j \in \Lambda''} w_j^* \cdot z_j, g \right) \leq O\left(\frac{\log k}{\sqrt{k}}\right)$$

Using the property of Gaussian variables and $B = O(1)$, we have

$$\Pr \left[g \in \left[\sum_{j \in \Lambda \setminus \Lambda''} w_j^* \cdot z_j - \frac{t}{2}, \sum_{j \in \Lambda \setminus \Lambda''} w_j^* \cdot z_j + \frac{t}{2} \right] \right] \geq \Omega(t)$$

and using the above Wasserstein distance bound, we have

$$\Pr \left[\sum_{j \in \Lambda''} w_j^* \cdot z_j \in \left[\sum_{j \in \Lambda \setminus \Lambda''} w_j^* \cdot z_j - t, \sum_{j \in \Lambda \setminus \Lambda''} w_j^* \cdot z_j + t \right] \right] \geq \Omega(t) - O\left(\frac{\log k}{\sqrt{k}}\right)$$

□

H.2 McDiarmid's Inequality and An Extension

We state the standard McDiarmid's inequality,

Lemma H.2 (McDiarmid's inequality). *Consider independent random variables $x_1, \dots, x_n \in \mathcal{X}$ and a mapping $f : \mathcal{X}^n \rightarrow \mathbb{R}$. If for all $i \in [n]$ and for all $y_1, \dots, y_n, y'_i \in \mathcal{X}$, the function f satisfies*

$$|f(y_1, \dots, y_{i-1}, y_i, y_{i+1}, \dots, y_n) - f(y_1, \dots, y_{i-1}, y'_i, y_{i+1}, \dots, y_n)| \leq c_i.$$

Then

$$\begin{aligned}\Pr[f(x_1, \dots, x_n) - \mathbb{E} f \geq t] &\geq \exp\left(\frac{-2t^2}{\sum_{i=1}^n c_i^2}\right), \\ \Pr[f(x_1, \dots, x_n) - \mathbb{E} f \leq -t] &\geq \exp\left(\frac{2t^2}{\sum_{i=1}^n c_i^2}\right).\end{aligned}$$

We prove a more general version of McDiarmid's inequality,

Lemma H.3 (McDiarmid extension). *Let w_1, \dots, w_N be independent random variables and $f: (w_1, \dots, w_N) \mapsto [0, B]$. Suppose it satisfies for every $k \in \{2, 3, \dots, N\}$,*

- with probability at least $1 - p$ over w_1, \dots, w_N , it satisfies

$$\forall w_k'': |f(w_{-k}, w_k) - f(w_{-k}, w_k'')| \leq c$$

- with probability at least $1 - p$ over $w_1, \dots, w_{k-1}, w_{k+1}, \dots, w_N$, it satisfies

$$\mathbb{E}_{w_k', w_k''} [(f(w_{-k}, w_k') - f(w_{-k}, w_k''))^2] \leq V_k^2$$

Then,

$$\begin{aligned}\Pr_{w_1, \dots, w_N} \left[\left| f(w_1, \dots, w_N) - \mathbb{E}_{w_2, \dots, w_N} [f(w_1, \dots, w_N) \mid w_1] \right| \geq t \right] \\ \leq O(N\sqrt{p}) + \exp\left(\frac{-\Omega(t^2)}{t(c + \sqrt{p}B) + \sum_{t=2}^N (V_t^2 + \sqrt{p}B^2)^2}\right).\end{aligned}$$

Proof of Lemma H.3. For each $t = 1, \dots, N - 1$, we have with probability at least $1 - \sqrt{p}$ over w_1, \dots, w_t , it satisfies

$$\Pr_{w_{t+1}, \dots, w_N} [\forall w_{t+1}'': |f(w_{\leq t}, w_{t+1}, w_{>t+1}) - f(w_{\leq t}, w_{t+1}'', w_{>t+1})| \leq c] \geq 1 - \sqrt{p}.$$

We also have with probability at least $1 - \sqrt{p}$ over w_1, \dots, w_t , it satisfies

$$\Pr_{w_{t+2}, \dots, w_N} \left[\mathbb{E}_{w_{t+1}', w_{t+1}''} (f(w_{\leq t}, w_{t+1}', w_{>t+1}) - f(w_{\leq t}, w_{t+1}'', w_{>t+1}))^2 \leq V_{t+1}^2 \right] \geq 1 - \sqrt{p}.$$

We denote by $K_{\leq t}$ the event (over $w_{\leq t} = (w_1, \dots, w_t)$) that the above two statements hold. We know that $\Pr[w_{\leq t} \in K_{\leq t}] \geq 1 - 2\sqrt{p}$. For notational simplicity, we denote by $K_{\leq N}$ the full set over all possible (w_1, \dots, w_N) .

Define random variable X_t (which depends only on w_1, \dots, w_t) as

$$X_t := \mathbb{E}_{w_{>t}} [f(\vec{w}) \mid w_{\leq t}] \mathbf{1}_{(w_{\leq 1}, \dots, w_{\leq t}) \in K_{\leq 1} \times \dots \times K_{\leq t}} \in [0, B]$$

For every t and fixed w_1, \dots, w_{t-1} .

- If $(w_{\leq 1}, \dots, w_{<t}) \notin K_{\leq 1} \times \dots \times K_{<t}$, then $X_t = X_{t-1} = 0$.
- If $(w_{\leq 1}, \dots, w_{<t}) \in K_{\leq 1} \times \dots \times K_{<t}$,
 - If $w_{\leq t} \notin K_{\leq t}$, then $X_t - X_{t-1} = 0 - X_{t-1} \leq 0$.
 - If $w_{\leq t} \in K_{\leq t}$, then

$$X_t - X_{t-1} = \mathbb{E}_{w_{>t}} [f(w_{<t}, w_t, w_{>t}) \mid w_{\leq t}] - \mathbb{E}_{w_{>t}} [f(w_{<t}, w_t, w_{>t}) \mid w_{<t}]$$

Recall the property $w_{<t} \in K_{<t}$, we know with probability at least $1 - \sqrt{p}$ over w_t and $w_{>t}$, it satisfies

$$\forall w_t'': |f(w_{<t}, w_t'', w_{>t}) - f(w_{<t}, w_t, w_{>t})| \leq c$$

Taking expectation over w_t and $w_{>t}$, we have

$$\forall w_t'': \mathbb{E}_{w_{>t}} [f(w_{<t}, w_t'', w_{>t})] - \mathbb{E}_{w_{\geq t}} [f(w_{<t}, w_t, w_{>t})] \leq (c + \sqrt{p}B)$$

This precisely means $X_t - X_{t-1} \leq c + \sqrt{p}B$.

- Using the property $w_{<t} \in K_{<t}$, we know with probability at least $1 - \sqrt{p}$ over $w_{>t}$, it satisfies

$$\mathbb{E}_{w_t, w_t''} (f(w_{<t}, w_t, w_{>t}) - f(w_{<t}, w_t'', w_{>t}))^2 \leq V_t^2$$

Taking expectation also over $w_{>t}$, we have

$$\begin{aligned} & \mathbb{E}_{w_t, w_t'', w_{>t}} (f(w_{<t}, w_t, w_{>t}) - f(w_{<t}, w_t'', w_{>t}))^2 \leq V_t^2 + \sqrt{p}B^2 \\ \implies & \mathbb{E}_{w_t} \left(\mathbb{E}_{w_{>t}} [f(w_{<t}, w_t, w_{>t})] - \mathbb{E}_{w_t'', w_{>t}} [f(w_{<t}, w_t'', w_{>t})] \right)^2 \leq V_t^2 + \sqrt{p}B^2 \end{aligned}$$

Now observe that, since $(w_{\leq 1}, \dots, w_{<t}) \in K_{\leq 1} \times \dots \times K_{<t}$, we have $X_{t-1} = \mathbb{E}_{w_t'', w_{>t}} [f(w_{<t}, w_t'', w_{>t})]$. We also have that as long as $w_{\leq t} \in K_{\leq t}$, then $X_t = \mathbb{E}_{w_{>t}} [f(w_{<t}, w_t, w_{>t})]$. Putting these together, and using the fact $\Pr[w_{\leq t} \in K_{\leq t}] \geq 1 - 2\sqrt{p}$, we have

$$\mathbb{E}_{w_k} [(X_{t+1} - X_t)^2 | w_{<t}] \leq V_t^2 + 3\sqrt{p}B^2$$

In sum, we have just shown that for all choices of w_1, \dots, w_{t-1} ,

$$X_t - X_{t-1} \leq (c + \sqrt{p}B) \quad \text{and} \quad \mathbb{E}_{w_k} [(X_{t+1} - X_t)^2 | w_{<t}] \leq V_t^2 + 3\sqrt{p}B^2$$

always holds. Note in addition we also have $\mathbb{E}_{w_t} [X_t | w_{<t}] \leq X_{t-1}$. Therefore, by applying martingale concentration (with its one-sided and Bernstein form, see Lemma H.4),

$$\Pr[X_N - X_1 > t] \leq \exp \left(\frac{-\Omega(t^2)}{t(c + \sqrt{p}B) + \sum_{t=2}^N (V_t^2 + \sqrt{p}B^2)^2} \right)$$

Recalling

$$X_N := f(\vec{w}) \mathbb{1}_{(w_{\leq 1}, \dots, w_{\leq t}) \in K_{\leq 1} \times \dots \times K_{\leq t}}$$

and we have $X_N = f(w_1, \dots, w_N)$ with probability at least $1 - 2N\sqrt{p}$ (and $X_N = 0$ with the remaining probability). Also recalling

$$X_1 := \mathbb{E}_{w_2, \dots, w_N} [f(\vec{w}) | w_1] \mathbb{1}_{w_{\leq 1}}$$

and we have $X_1 = \mathbb{E}_{w_2, \dots, w_N} [f(\vec{w}) | w_1]$ with probability at least $1 - 2\sqrt{p}$ (and $X_1 = 0$ with the remaining probability).

Together, we have the desired theorem. □

Let us state, for completeness' sake, a simple one-sided Bernstein form of martingale concentration (that we do not know a good reference to it).

Lemma H.4. *Suppose we have a submartingale sequence X_0, X_1, \dots, X_N , satisfying:*

- $X_0 = 0$ and $\mathbb{E}[X_t | X_{t-1}] \leq X_t$,
- $X_t - X_{t-1} \leq c$ always holds, and
- $\mathbb{E}_{X_t} [(X_t - X_{t-1})^2 | X_{t-1}] \leq V_t^2$ always holds.

Then,

$$\Pr[X_N > t] \leq e^{-\Omega(\frac{t^2}{tc + \sum_t V_t^2})}$$

Proof. Define potential function $\Psi_t = e^{\frac{\eta}{2c} X_t}$ for some $\eta \in (0, 1)$ to be chosen later. We have

$$\Psi_t = \Psi_{t-1} \cdot e^{\frac{\eta}{2c}(X_t - X_{t-1})} \leq \Psi_{t-1} \cdot \left(1 + \left(\frac{\eta(X_t - X_{t-1})}{2c}\right) + \left(\frac{\eta(X_t - X_{t-1})}{2c}\right)^2\right)$$

where the inequality is due to $e^y \leq 1 + y + y^2$ which holds for all $-\infty < y \leq 0.5$. Taking conditional expectation, we have

$$\begin{aligned} \mathbb{E}[\Psi_t | X_{t-1}] &\leq \Psi_{t-1} \cdot \left(1 + \eta \mathbb{E}\left[\frac{X_t - X_{t-1}}{2c} \mid X_{t-1}\right] + \eta^2 \mathbb{E}\left[\left(\frac{X_t - X_{t-1}}{2c}\right)^2 \mid X_{t-1}\right]\right) \\ &\leq \Psi_{t-1} \cdot \left(1 + \eta^2 \frac{V_t^2}{4c^2}\right) \leq \Psi_{t-1} \cdot e^{\eta^2 \frac{V_t^2}{4c^2}}. \end{aligned}$$

After telescoping, we have $\mathbb{E}[\Psi_N] \leq e^{\eta^2 \frac{\sum_t V_t^2}{4c^2}}$, and therefore

$$\Pr[X_N > t] \leq \frac{\mathbb{E}[e^{\eta X_N / (2c)}]}{e^{\eta t / (2c)}} \leq e^{\eta^2 \frac{\sum_t V_t^2}{4c^2} - \eta \frac{t}{2c}}$$

Choosing the optimal $\eta \in (0, 1)$ gives us bound

$$\Pr[X_N > t] \leq e^{-\Omega(\frac{t^2}{tc + \sum_t V_t^2})}$$

□

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