





# Improving Customer Satisfaction in Bike Sharing Systems through Dynamic Repositioning

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### **Motivation: Bike Sharing Systems**

### Bike Sharing Systems (BSS)

- 1700 active systems all over the world
- Attractive alternative to private vehicles
- Reduce traffic congestion, green house gas emission and air pollution
- Problem: Starvation or congestion of bikes at stations
  - Increase usage of private vehicle and carbon emission
- Goal: Repositioning of bikes during the day to address availability issues







### Starvation/congestion in Capitalbikeshare

**Supriyo GHOSH** 

### **Background: Repositioning in Bike Sharing**

- Static repositioning (at the end of day)
  - Raviv and Kolka (2013), Raidl et al. (2013)
- Dynamic repositioning (myopic & offline)
  - Schuijbroek et al. (2013), Shu et al. (2013)
- Repositioning using incentives
  - Singla et. al. (2015), Ghosh et al. (2017)
- Robust repositioning under demand uncertainty
  - Ghosh et. al. (2016)
- Our contribution:
  - Using satisficing approach to tackle the demand uncertainty



Uncertainty (higher variance) in demand

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## **Satisficing Approach**

- Tractable satisficing approach [Jaillet et. al. 2016]
  - Constraints are defined over uncertain variables.
  - Maximize the probability of satisficing feasibility constraints.

$$\begin{array}{ll} \max \ \rho(\boldsymbol{\alpha}) & \text{Family of uncertainty set} \\ \text{s.t. } \boldsymbol{A}(\boldsymbol{z})\boldsymbol{x} \geq \boldsymbol{b}(\boldsymbol{z}) \ \forall \boldsymbol{z} \in \mathcal{U}(\boldsymbol{\alpha}) & \text{Uncertain parameter} \\ & \text{Uncertain variable} \end{array}$$

- Taking satisficing approach to bike-sharing system
  - Support set for station s:

 $W_s = \{\zeta_s^1, \dots, \zeta_s^n\} = \{1, 2, 3\}$ 

Realization probability:

 $\lambda_s^2 = P(\bar{z}_s \le 2) = 3/4$ 

• Objective:

$$\max\sum_{s} \log(P(\bar{z}_s \in W_s))$$



## **Optimization Model**



- Outputs: Repositioning & routing strategy
- Decision Variables:

 $\alpha_s^l \in \{0,1\}: 1$  if  $\zeta_s^l$  is selected as demand bound

 $y_s^+, y_s^-: \mathrm{Total}$  number of biles picked up and dropped off from station s

 $z_{s,v}^r \in \{0,1\}$ : Set to 1 if vehicle v is stationed at s at episode r



## **Problem Constraints**

Feasibility constraints

$$\sum_{l} \zeta_{s}^{l} \alpha_{s}^{l} \leq d_{s}^{\#} + y_{s}^{-} - y_{s}^{+} + \rho_{s} \quad \forall s$$
$$\sum_{l} \zeta_{s}^{l} = 1 \quad ; \quad \sum_{s} \rho_{s} \leq \rho$$

- Routing constraints:
  - A vehicle can only be at one station at any episode.



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- Routing constraints:
  - A vehicle can only be at one station at any episode.
  - Time spend in routing & repositioning is bounded by duration of decision period.
- Repositioning constraints
  - Flow preservation of bikes at vehicles.
  - Reposition at a station is possible only if a vehicle is present there.

 $y_{s,v}^{+,r} + y_{s,v}^{-,r} \le C_v^* \cdot z_{s,v}^r$ 



 $\forall s, v, r$ 

# **Experimental Setup**

- Dataset:
  - Hubway (95 stations, 3 carrier vehicles)
  - Trip history data for 3 months
  - Planning period: 6AM-12PM (each decision epoch is 30 minutes)
  - Training data: 20 days of demand scenarios
  - Testing data: 40 days of demand scenarios
- Evaluation Metrics: Average and worst-case lost demand over all testing demand scenarios.
- Approaches:
  - Static (Redeployment at the end of day)
  - Offline approach [Shu et. al., (OR Journal, 2013)]
  - Online approach [Schuijbroek et. al., (EJOR Journal, 2017)]
  - Robust approach [Ghosh et. al., (IJCAI, 2016)]
  - DrROBUST (our approach using satisficing)



# **Experimental Results**

- A vehicle is allowed to visit a maximum of 3 stations (R=3):
  - Our Satisficing approach reduces the average lost demand by at least 15% over all the benchmarks.
  - The worst-case lost demand is reduced by at least 5%.



# **Experimental Results**

- A vehicle is allowed to visit a maximum of 4 stations (R=4):
  - Our Satisficing approach reduces the average lost demand by at least 19% over all the benchmarks.
  - The worst-case lost demand is reduced by at least 9%.



# **Runtime performance**

- DrROBUST is more computationally attractive than Robust approach for 3 episodes per decision epoch.
- For 4 episodes per decision epoch, DrROBUST has highest runtime complexity, but runtime is always bounded by 15 minutes.



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# **Concluding Remarks**

### **Robust repositioning in Bike Sharing Systems**

- A practically important and challenging problem.
- A tractable satisficing approach is adopted to maximize the loglikelihood of meeting uncertain future demand.
- Solutions are validated on a simulator built on a real-world data set.
- Lost demand (average) is reduced by at least 15%.
- Solution is robust to uncertainty in future demand.

### Future Direction:

- How to adapt the solution approach to tackle the problem in the context of dockless bike sharing systems?
- How to consider future demand for multiple time-steps to further reduce the lost demand?

**Supplementary Slides** 

## **Simulation Model**

• Compute flows of customers between stations given the distribution of bikes



Compute distribution of bikes for next decision epoch



# **Routing Distance Comparison**

- Robust approach reduces the average and worst-case lost demand by at least 18% and 17% over all the benchmarks.
- Satisficing approach further reduces the average and worst-case lost demand by 26% and 14% over the Robust approach.

