# Complexity and algorithms for monomial and clausal predicate abstraction

Shuvendu K. Lahiri and Shaz Qadeer

Microsoft Research

Abstract. In this paper, we investigate the asymptotic complexity of various predicate abstraction problems relative to the asymptotic complexity of checking an annotated program in a given assertion logic. Unlike previous approaches, we pose the predicate abstraction problem as a decision problem, instead of the traditional inference problem. For assertion logics closed under weakest (liberal) precondition and Boolean connectives, we show two restrictions of the predicate abstraction problem where the two complexities match. The restrictions correspond to the case of *monomial* and *clausal* abstraction. For these restrictions, we show a symbolic encoding that reduces the predicate abstraction problem to checking the satisfiability of a single formula whose size is polynomial in the size of the program and the set of predicates. We also provide a new iterative algorithm for solving the *clausal* abstraction problem that can be seen as the dual of the Houdini algorithm for solving the *monomial* abstraction problem.

# 1 Introduction

Predicate abstraction [8] is a method for constructing inductive invariants for programs or transition systems over a given set of predicates  $\mathcal{P}$ . It has been an enabling technique for several automated hardware and software verification tools. SLAM [1], BLAST [11] use predicate abstraction to construct invariants for sequential software programs. Predicate abstraction has also been used in tools for verifying hardware descriptions [12] and distributed algorithms [14]. Although predicate abstraction is an instance of the more general theory of abstract interpretation [5], it differs from most other abstract interpretation techniques (e.g. for numeric domains [6], shape analysis [17]) in that it does not require a fixed abstract domain; it is parameterized by decision procedures for the assertion logic in which the predicates are expressed.

Most previous work on predicate abstraction has been concerned with *con*structing an inductive invariant over a set of predicates  $\mathcal{P}$  using abstract interpretation techniques. A (finite) abstract domain over the predicates is defined and the program is executed over the abstract domain until the set of abstract states do not change. At that point, the abstract state can be shown to be an inductive invariant. These techniques are usually *eager* in that the inductive invariant is computed without recourse to the property of interest. The property directedness is somewhat recovered using various forms of refinements (e.g. counterexample-guided [13, 3, 11], or proof-guided [10] refinements) by varying the set of predicates. However, these techniques do not usually address the problem for the case of a fixed set of predicates.

In this paper, we study the problem of predicate abstraction as a decision problem. For a given program Prog(pre, post, body)

where *pre* and *post* are assertions, *body* is loop-free code, and a set of predicates  $\mathcal{P}$ , we are interested in the question:

Does there exist a loop invariant I over  $\mathcal{P}$  such that program *Prog* can be proved correct?

We define this decision problem to be  $InferPA(Prog, \mathcal{P})$ . By posing the problem as a decision problem, we do not have to adhere to any particular way to *construct* the loop invariant I (say using abstract interpretation), and it allows us to study the complexity of the problem. Besides, the problem formulation requires us to search for only those I that can prove the program. This problem formulation has been first proposed in the context of the annotation inference problem in ESC/Java [7] for a restricted case, and more recently by Gulwani et al. [9]. Although the latter has the same motivation as our work, they do not study the complexity of the predicate abstraction problems.

In this paper, we study the asymptotic complexity of the decision problem  $InferPA(Prog, \mathcal{P})$  relative to the decision problem Check(Prog, I) which checks if I is a loop invariant that proves the program correct. Throughout the paper, we assume that the assertion logic of assertions in pre, post and predicates in  $\mathcal{P}$  is closed under weakest (liberal) precondition predicate transformer wp, and also closed under Boolean connectives. The assertion logic determines the logic in which Check(Prog, I) is expressed. We are also most interested in logics for which the decision problem is **Co-NP** complete— this captures a majority of the assertion logic, this includes the useful theories of uninterpreted functions, arithmetic, select-update arrays, inductive datatypes, and more recently logics about linked lists [15] and types in programs [4].

For such assertion logics, we show that if checking Check(Prog, I) is in **PSPACE**, then checking  $InferPA(Prog, \mathcal{P})$  is **PSPACE** complete. We also study the problem of template abstraction [19, 21] where the user provides a formula J with some free Boolean variables  $\mathcal{W}$ , and is interested in finding whether there is a valuation  $\sigma_{\mathcal{W}}$  of  $\mathcal{W}$  such that  $Check(Prog, J[\sigma_{\mathcal{W}}/\mathcal{W}])$  is **true**. We call this decision problem  $InferTempl(Prog, J, \mathcal{W})$ , and show  $InferTempl(Prog, J, \mathcal{W})$  is  $\Sigma_2^{\mathbf{P}}$  complete (**NP**^{NP} complete), when Check(Prog, I) is in **Co-NP**.

Given that the general problem of predicate or template abstraction can be much more complex than checking Check(Prog, I), we focus on two restrictions:

 $\phi, \psi \in Formula ::= e \leq e |\phi \land \phi | \neg \phi | \dots$ 

Fig. 1. A simple programming language SIMPPL and an extensible assertion logic *Formula*.

- InferMonome(Prog,  $\mathcal{P}$ ): Given a set of predicates  $\mathcal{P}$ , does there exist a  $\mathcal{R} \subseteq \mathcal{P}$  such that  $Check(Prog, \bigwedge_{p \in \mathcal{R}} p)$  is true, and
- InferClause(Prog,  $\mathcal{P}$ ): Given a set of predicates  $\mathcal{P}$ , does there exist a  $\mathcal{R} \subseteq \mathcal{P}$  such that  $Check(Prog, \bigvee_{n \in \mathcal{R}} p)$  is true.

These problems can also be seen as restrictions on the template abstraction problem. For example, the problem  $InferMonome(Prog, \mathcal{P})$  can also be interpreted as  $InferTempl(Prog, J, \mathcal{W})$  where J is restricted as  $(\bigwedge_{p \in \mathcal{P}} b_p \implies p)$  and  $\mathcal{W} = \{b_p | p \in \mathcal{P}\}.$ 

We show that for both  $InferMonome(Prog, \mathcal{P})$  and  $InferClause(Prog, \mathcal{P})$ , the complexity of the decision problem matches the complexity of Check(Prog, I). For instance, when the complexity of Check(Prog, I) is **Co-NP** complete, both  $InferMonome(Prog, \mathcal{P})$  and  $InferClause(Prog, \mathcal{P})$  are **Co-NP** complete. We obtain these results by providing a symbolic encoding of both problems into logical formulas, such that the logical formulas are satisfiable if and only if the inference problems return false. The interesting part is that these logical formulas are polynomially bounded in Prog and  $\mathcal{P}$ .

The symbolic encoding of the inference problems also provides algorithms to answer these decision problems, in addition to establishing the complexity results. In the process, we also describe a new iterative algorithm for checking  $InferClause(Prog, \mathcal{P})$  that can be seen as the dual of an existing algorithm Houdini [7] that checks  $InferMonome(Prog, \mathcal{P})$ .

# 2 Background

We describe some background on programs and their correctness, assertion logics, weakest liberal preconditions, and motivate the inference problems.

#### 2.1 A simple programming language for loop-free programs

Figure 1 describes a simple programming language SIMPPL for loop-free programs. The language supports scalar variables *Scalars* and mutable maps or arrays *Maps*. The language supports arithmetic operations on scalar expressions *Expr* and *select-update* reasoning for array expressions *MapExpr*. The symbols **sel** and **upd** are interepreted symbols for selecting from or updating an array. The operation havoc assigns a type-consistent (scalar or map) arbitrary value to its argument. s; t denotes the sequential composition of two statements s and  $t, s \diamond t$  denotes a non-deterministic choice to either execute statements in s or t. This statement along with the **assume** models conditional statements. For example, the statement if (e) {s} is desugared into {assume e; s}  $\diamond$  assume  $\neg e$ .

$wp(skip,\phi) = \phi$	
$wp(assert \ \psi, \phi) = \psi \wedge \phi$	$wp(havoc x, \phi) = \phi[v/x]$
$wp(assume \ \psi, \phi) = \psi \implies \phi$	$wp(havoc\;X,\phi)=\phi[V/X]$
$wp(x := e, \phi) = \phi[e/x]$	$wp(s;t,\phi) = wp(s,wp(t,\phi))$
$wp(X := E, \phi) = \phi[E/X]$	$wp(s \diamond t, \phi) = wp(s, \phi) \land wp(t, \phi)$

Fig. 2. Weakest liberal precondition for the logic without any extensions. Here v and V represent fresh symbols.

The assertion language in *Formula* is extensible and contains the theories for equality, arithmetic, arrays, and is closed under Boolean connectives. Any formula  $\phi \in Formula$  can be interpreted as a set of states of a program that satisfy  $\phi$ . For any  $s \in Stmt$ , and  $\phi \in Formula$ , the weakest liberal precondition  $wp(s, \phi)$  corresponds to a formula such that from any state in  $wp(s, \phi)$ , the statement s does not fail any assertions and any terminating execution ends in a state satisfying  $\phi$ . For our assertion logic (without any extensions), Figure 2 shows the wp for statements in the programming language. For more complex extensions to the assertion logic (e.g. [15]), the rule for  $wp(X := E, \phi)$  is more complex. Although applying wp can result in an exponential blowup in the size of a program, standard methods generate a linear-sized formula that preserves validity by performing static single assignment (SSA) and introducing auxiliary variables [2].

We say that the assertion logic is closed under wp (for SIMPPL) when for any  $\phi \in Formula$  and for any  $s \in Stmt$ ,  $wp(s, \phi) \in Formula$ . In the rest of the paper, we will abstract from the details of the particular assertion logic, with the following restrictions on the assertion logic:

- the assertion logic is closed under Boolean connectives (i.e. subsumes propositional logic).
- the assertion logic is closed under wp.
- wp distributes over  $\land$ , i.e.,  $wp(s, \phi \land \psi) \equiv wp(s, \phi) \land wp(s, \psi)$ .

A model  $\mathcal{M}$  assigns a type-consistent valuation to symbols in a formula. Any model assigns the standard values for interpreted symbols such as =, +, -, sel, upd, and assigns an integer value to symbols in *Scalars* and function values to symbols in *Maps*. For a given model  $\mathcal{M}$ , we say that the model satisfies a formula  $\phi \in Formula$  (written as  $\mathcal{M} \models \phi$ ) if and only if the result of evaluating  $\phi$  in  $\mathcal{M}$  is true; in such a case, we say that  $\phi$  is *satisfiable*. We use  $\models \phi$  to denote that  $\phi$  is *valid* when  $\phi$  is satisfiable for any model.

**Definition 1.** For any  $\phi, \psi \in$  Formula and  $s \in$  Stmt, the Floyd-Hoare triple  $\{\phi\}$  s  $\{\psi\}$  holds if and only if the logical formula  $\phi \implies wp(s, \psi)$  is valid.

Intuitively, the Floyd-Hoare triple  $\{\phi\}$  s  $\{\psi\}$  captures the specification that from a state satisfying  $\phi$ , no execution of s fails any assertions and every terminating execution ends in a state satisfying  $\psi$ . Given our assumptions on the assertion logic *Formula*, checking the correctness of a program in SIMPPL reduces to checking validity in the assertion logic.

## 2.2 Loops and loop invariants

Having defined the semantics of loop-free code blocks, consider the following class of programs Prog(pre, post, body) below (ignore the annotation {inv I} initially) where  $pre, post \in Formula$  and  $body \in Stmt$ :

$${pre}$$
  
while (\*){inv I} do body  
 ${post}$ 

Since this program can have unbounded computations due to the while loop, generating a verification condition requires a loop invariant. This is indicated by inv annotation. The loop invariant I is a formula in *Formula*. The Floyd-Hoare triple for *Prog* holds if and only if there exists a loop invariant I such that the three formula are valid:

$$\begin{array}{l} \models pre \implies I \\ \models I \implies wp(body, I) \\ \models I \implies post \end{array}$$

For any such program Prog(pre, post, body), we define Check(Prog, I) to return true if and only if all the three formulas are valid. Intuitively, Check(Prog, I)*checks* whether the supplied loop invariant I holds on entry to the loop, is preserved by an arbitrary loop iteration and implies the postcondition.

We now define the decision problem that corresponds to *inferring* the loop invariant I for *Prog*. For a given program Prog(pre, post, body), Infer(Prog) returns true if and only if there exists a formula  $I \in Formula$  such that Check(Prog, I) is true.

Although Check(Prog, I) is efficiently decidable for our programming language for a rich class of assertions (including the one shown in Figure 1), checking Infer(Prog) is undecidable even when Prog consists of only scalar integer variables and include arithmetic operations — one can encode the reachability problem for a two counter machine, checking which is undecidable. Therefore, most approaches search for I within some restricted space. Predicate abstraction is one such technique that searches for an I within a finite space.

# 3 Complexity of predicate and template abstraction

In this section, we study the complexity of two inference techniques (relative to the complexity of Check(Prog, I)) that search for loop invariants over a finite space:

- 1. The first technique is based on *predicate abstraction*, where the loop invariant is searched over Boolean combination of an input set of predicates.
- 2. The second technique is based on *templates*, where the loop invariant is searched over the valuations of a set of free Boolean variables in a candidate template assertion.

#### 3.1 Predicate abstraction

Predicate abstraction [8], an instance of the more general theory of abstract interpretation [5], is a mechanism to make the Infer(Prog) problem more tractable by searching for I over restricted formulas. In predicate abstraction, in addition to Prog, we are given a set of predicates  $\mathcal{P} = \{p_1, \ldots, p_n\}$  where  $p_i \in Formula$ . Throughout this paper, we assume that the set  $\mathcal{P}$  is closed under negation, i.e., if  $p \in \mathcal{P}$  then  $\neg p \in \mathcal{P}$ . Instead of looking for a loop invariant I over arbitrary formulas, predicate abstraction restricts the search to those formulas that are a Boolean combination (using  $\lor$  or  $\land$ ) over the predicates in  $\mathcal{P}$ . More formally, for a program Prog(pre, post, body) and a set of predicates  $\mathcal{P}$ ,  $InferPA(Prog, \mathcal{P})$ returns true if and only if there exists a formula  $I \in Formula$  which is a Boolean combination over  $\mathcal{P}$  such that Check(Prog, I) is true.

**Theorem 1.** If checking Check(Prog, I) is in **PSPACE** in the size of Prog and I, then checking InferPA(Prog,  $\mathcal{P}$ ) is **PSPACE** complete in the size of Prog and  $\mathcal{P}$ .

*Proof sketch.* Showing that  $InferPA(Prog, \mathcal{P})$  is **PSPACE** hard is easy. We can encode the reachability problem for a propositional transition system (which is **PSPACE** complete) into  $InferPA(Prog, \mathcal{P})$  by encoding the transition system as Prog, and setting  $\mathcal{P}$  to be the set of state variables in the transition system.

To show that  $InferPA(Prog, \mathcal{P})$  is in **PSPACE**, we will provide a nondeterministic algorithm for checking if  $\neg post$  can be reached by an abstract interpretation of the program  $\{pre\}$  while (\*) do body  $\{post\}$  over the set of predicates in  $\mathcal{P}$ . Moreover, the algorithm will only use polynomial space in Progand  $\mathcal{P}$ .

The abstract state of the program corresponds to an evaluation of the predicates in  $\mathcal{P}$  to {true, false}. The algorithm performs an abstract *run* of size upto  $2^{|\mathcal{P}|}$  to determine if  $\neg post$  can be reachable starting from *pre*. The nondeterministic algorithm returns false if and only if some abstract run ends up in a state satisfying  $\neg post$ .

We need to store two successive states in a run and the length of the run, both of which only require linear space over the inputs. Moreover, to check that an abstract state is a successor of another, one needs to make a query to check that there is some concrete transition in *Prog* between the concretizations of the two abstract states — this can be done in **PSPACE** since the decision problem is in **PSPACE**. 

#### $\mathbf{3.2}$ **Template** abstraction

In template abstraction [18,9,21], the user provides a *template* formula  $J \in$  $Formula^{\mathcal{W}}$  in addition to Prog(pre, post, body), where

- $\mathcal{W} = \{w_1, w_2, \dots, w_m\}$  is a set of Boolean valued symbols, and  $Formula^{\mathcal{W}}$  extends *Formula* to contain formulas whose symbols range over both state variables (*Scalars* and *Maps*) and  $\mathcal{W}$ .

Given J, the goal is to infer a loop invariant I by searching over the different valuations of the symbols in  $\mathcal{W}$ .

For a set of symbols X, let  $\sigma_X$  denote an *assignment* of values of appropriate types to each symbols in X. For any expression e and an assignment  $\sigma_X$ ,  $e[\sigma_X/X]$ replaces a symbol  $x \in X$  in e with  $\sigma_X(x)$ . For a program Prog and a template  $J \in Formula^{\mathcal{W}}$ , InferTempl(Prog, J, W) returns true if and only if there exists an assignment  $\sigma_{\mathcal{W}}$  to the symbols in  $\mathcal{W}$  such that  $Check(Prog, J[\sigma_{\mathcal{W}}/\mathcal{W}])$  is true.

*Example 1.* Consider the simple program  $\{x = 0 \land y = 10\}$  while  $(y \neq 0)$  do x := $x+1; y := y-1; \{x = 10\}$ . In our language, the program would be written as  $\{x = 10\}$ .  $0 \land y = 10$  while (\*) do assume  $y \neq 0$ ; x := x+1; y := y-1;  $\{y = 0 \implies x = 10\}$ . A potential loop invariant that proves the program is x+y=10. A template J for which InferTempl(Prog, J, W) is true is  $(w_1 \implies x + y = 10) \land (w_2 \implies x = y)$ . Clearly, for the assignment  $\sigma_{w_1} = \mathsf{true}$  and  $\sigma_{w_2} = \mathsf{false}$ , the template is a loop invariant.

The complexity class  $\Sigma_2^{\mathbf{P}}$  contains all problems that can be solved in NP using an **NP** oracle.

**Theorem 2.** If checking Check(Prog, I) is in **Co-NP** in the size of Prog and I, then checking InferTempl(Prog, J, W) is  $\Sigma_2^{\mathbf{P}}$  complete in Prog, J, and W.

*Proof.* The problem is in  $\Sigma_2^{\mathbf{P}}$  because we can non-deterministically guess an assignment of  $\mathcal{W}$  and check if the resulting J is an inductive invariant. The **NP** oracle used in this case is a checker for  $\neg Check(Prog, I)$ .

On the other hand, one can formulate InferTempl(Prog, J, W) as the formula  $\exists W. Check(Prog, J).$  Given a quantified Boolean formula (QBF)  $\exists X. \forall Y. \phi(X, Y)$ where  $\phi$  is quantifier-free, for which checking the validity is  $\Sigma_2^{\mathbf{P}}$  complete, we can encode it to InferTempl(Prog, J, W), by constructing pre = post = true,  $body = skip, \mathcal{W} = X \text{ and } J = \phi(X, Y).$  $\square$ 

Having shown that the complexity of both predicate abstraction and template abstraction are considerably harder than checking an annotated program, we will focus on two restricted versions of the abstraction problem for monomials and clauses. As mentioned in the introduction, these problems can be seen as restrictions of either predicate abstraction or template abstraction.

# 4 Monomial abstraction

For any set  $\mathcal{R} \subseteq \mathcal{P}$ , a monome over  $\mathcal{R}$  is the formula  $\bigwedge_{p \in \mathcal{R}} p$ . For a set of predicates  $\mathcal{P}$ , let us define  $InferMonome(Prog, \mathcal{P})$  to return true if and only if there exists  $\mathcal{R} \subseteq \mathcal{P}$  such that  $Check(Prog, \bigwedge_{p \in \mathcal{R}} p)$  is true.

#### 4.1 Houdini algorithm

```
\begin{split} FailsCheck(\mathcal{S},\mathcal{M}) & \stackrel{\triangle}{=} \mathcal{M} \models (\bigwedge_{q \in \mathcal{S}} q) \land \neg post \\ RemovesPredicate(\mathcal{S},\mathcal{M},p) \stackrel{\triangle}{=} \lor \mathcal{M} \models pre \land \neg p \\ \lor \mathcal{M} \models (\bigwedge_{q \in \mathcal{S}} q) \land \neg wp(body,p) \end{split}
\begin{aligned} \mathsf{proc} \ FindInvAux(\mathcal{R}) \\ \mathsf{if} \ (exists a model \ \mathcal{M} \ s.t. \ FailsCheck(\mathcal{R},\mathcal{M})) \\ \mathcal{M}_{guess} \leftarrow \mathcal{M}; \\ \mathsf{return} \ FAIL; \\ \mathsf{if} \ (exists q \in \mathcal{R} \ and \ model \ \mathcal{M} \ s.t. \ RemovesPredicate(\mathcal{R},\mathcal{M},q)) \\ \mathcal{M}_{guess} \leftarrow \mathcal{M}; \\ \mathcal{Q}_{guess+1} \leftarrow \mathcal{Q}_{guess} \cup \{q\}; \\ guess \leftarrow guess+1; \\ \mathsf{return} \ FindInvAux(\mathcal{R} \setminus \{q\}); \\ \mathsf{return} \ SUCCESS(\mathcal{R}); \end{aligned}
\begin{aligned} \mathsf{proc} \ FindInv(\mathcal{P}) \\ guess \leftarrow \{\}; \\ FindInvAux(\mathcal{P}); \end{aligned}
```

Fig. 3. Procedure to construct either a monomial invariant or a witness to show its absence. The *shaded* lines represent extensions for computing the witness.

Figure 3 describes an algorithm *FindInv* for solving the *InferMonome* problem. Initially, ignore the shaded regions of the algorithm. The algorithm iteratively prunes the set of predicates in the invariant starting from  $\mathcal{P}$ , removing a predicate whenever *RemovesPredicate* holds. The algorithm terminates with a *FAIL* when *FailsCheck* holds, denoting that there is no monomial invariant that satisfies the postcondition *post*. On the other hand, the algorithm terminates with  $SUCCESS(\mathcal{R})$  when it finds an invariant. It is easy to see that the procedure *FindInvAux* terminates within a recursion depth of  $|\mathcal{P}|$  since its argument  $\mathcal{R}$  monotonically decreases along any call chain.

**Lemma 1.** The procedure  $FindInv(\mathcal{P})$  satisfies the following:

- 1. FindInv( $\mathcal{P}$ ) returns FAIL if and only if InferMonome(Prog,  $\mathcal{P}$ ) is false.
- 2. If FindInv( $\mathcal{P}$ ) returns SUCCESS( $\mathcal{R}$ ), then for any  $\mathcal{S} \subseteq \mathcal{P}$  such that Check(Prog,  $\bigwedge_{p \in \mathcal{S}} p$ ), we have  $S \subseteq \mathcal{R}$ .

The algorithm is a variant of the Houdini algorithm in ESC/Java [7], where *RemovesPredicate* considers each predicate p in isolation instead of the conjunction ( $\bigwedge_{q \in S} q$ ). The Houdini algorithm solves the *InferMonome*(*Prog*,  $\mathcal{P}$ ) problem with at most  $|\mathcal{P}|$  number of theorem prover calls. However, this only provides an upper bound on the complexity of the problem. For example, making  $|\mathcal{P}|$ number of queries to a **Co-NP** complete oracle (a theorem prover) does not establish that the complexity of the inference problem is **Co-NP** complete; it only establishes that the upper bound of the complexity is **P**<sup>NP</sup>.

In the next subsection, we provide a model-theoretic justification for the correctness of *FindInv*. Our construction will provide insight into the complexity of *InferMonome*(*Prog*,  $\mathcal{P}$ ) relative to the complexity of *Check*(*Prog*, *I*).

#### 4.2 A model-theoretic proof of FindInv

For a guess  $\in \mathbb{N}$ , an indexed set of models  $\{\mathcal{M}_i\}_i$ , an indexed set of sets of predicates  $\{\mathcal{Q}_i\}_i$ , we define a predicate  $NoMonomeInv(\mathcal{P}, guess, \{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i)$ , that is true if and only if:

- 1.  $1 \leq guess \leq |\mathcal{P}| + 1$ , and
- 2.  $Q_1 = \{\}, \text{ and }$
- 3. For  $1 \leq i < guess$ ,  $\mathcal{Q}_{i+1} \setminus \mathcal{Q}_i = \{p_i\}$  for some  $p_i \in \mathcal{P}$ , and
- 4. For each  $1 \leq i < guess$ , and for  $p_i \in \mathcal{Q}_{i+1} \setminus \mathcal{Q}_i$ , either  $\mathcal{M}_i \models pre \land \neg p_i$  or  $\mathcal{M}_i \models (\bigwedge_{p \in \mathcal{P} \setminus \mathcal{Q}_i} p) \land \neg wp(body, p_i)$ , and
- 5.  $\mathcal{M}_{guess} \models (\bigwedge_{p \in \mathcal{P} \setminus \mathcal{Q}_{guess}} p) \land \neg post.$

The following three lemmas, whose proofs are given in the appendix, establish the connection between the *InferMonome* problem, the *NoMonomeInv* predicate, and the *FindInv* algorithm.

**Lemma 2.** If FindInv( $\mathcal{P}$ ) returns FAIL, then NoMonomeInv( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ) holds on the values computed by the procedure.

**Lemma 3.** If NoMonomeInv( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ) holds for some guess  $\in \mathbb{N}$ , a set of models  $\mathcal{M}_1, \ldots, \mathcal{M}_{guess}$ , and sets of predicates  $\mathcal{Q}_1, \ldots, \mathcal{Q}_{guess}$ , then InferMonome(Prog,  $\mathcal{P}$ ) is false.

**Lemma 4.** If  $FindInv(\mathcal{P})$  returns  $SUCCESS(\mathcal{R})$ , then  $Check(Prog, \bigwedge_{p \in \mathcal{R}} p)$  is true, and therefore  $InferMonome(Prog, \mathcal{P})$  is true.

The proofs of these lemmas requires the use of the additional shaded lines in the Figure 3, which compute the witness to show that no monomial invariant suffices to prove the program. Together, these three lemmas allow us to conclude that  $InferMonome(Prog, \mathcal{P})$  is false iff  $NoMonomeInv(\mathcal{P}, guess, {\mathcal{M}_i}_i, {\mathcal{Q}_i}_i)$ holds for some  $guess \in \mathbb{N}$ , a set of models  $\mathcal{M}_1, \ldots, \mathcal{M}_{guess}$ , sets of predicates  $\mathcal{Q}_1, \ldots, \mathcal{Q}_{guess}$ . This fact is used to define the symbolic encoding of the problem  $InferMonome(Prog, \mathcal{P})$  in the next subsection.

#### 4.3 Symbolic encoding and complexity of $InferMonome(Prog, \mathcal{P})$

In this section, we provide a symbolic encoding of  $InferMonome(Prog, \mathcal{P})$ . That is, given a program Prog(pre, post, body) and a set of predicates  $\mathcal{P}$ , we will construct a formula  $SymbInferMonome(Prog, \mathcal{P})$  which is satisfiable if and only if  $InferMonome(Prog, \mathcal{P})$  is false. The formula can be seen as a symbolic encoding of an iterative version of the FindInv algorithm that symbolically captures all executions of the algorithm for any input. Finally, we will use the encoding to relate the complexity of  $InferMonome(Prog, \mathcal{P})$  to the complexity of Check(Prog, I).

The following notations are used:

- The set of predicates is  $\mathcal{P}$ , and  $n = |\mathcal{P}|$
- For any formula  $\phi$ ,  $\phi^i$  represents the formula with any variable x is replaced with a fresh variable  $x^i$ . We will use this for each predicate  $p \in \mathcal{P}$ , pre, post and wp(body, p).
- The symbols  $b_p^j$  for a predicate p denotes that the predicate p was removed from consideration for the invariant in the *j*-th iteration.

For each  $p \in \mathcal{P}$  and  $i \in [1, n+1]$ , we define

$$present_p^i \stackrel{\triangle}{=} \bigwedge_{j \in [0,i)} \neg b_p^j$$

For each  $i \in [1, n]$ , we define

$$iter_i \stackrel{\triangle}{=} \lor pre^i \land \bigwedge_{p \in \mathcal{P}} (b_p^i \implies \neg p^i) \\ \lor \bigwedge_{p \in \mathcal{P}} ((present_p^i \implies p^i) \land (b_p^i \implies \neg wp(body, p)^i))$$

For each  $i \in [1, n+1]$ , we define

$$check_i \stackrel{ riangle}{=} \bigwedge_{p \in \mathcal{P}} (present_p^i \implies p^i) \land \neg post^i$$

Finally, the desired symbolic encoding  $SymbInferMonome(Prog, \mathcal{P})$  is the following formula:

$$\begin{split} &\wedge 1 \leq guess \leq n+1 \\ &\wedge \bigwedge_{p \in \mathcal{P}} \neg b_p^0 \\ &\wedge (\bigwedge_{i \in [1,n]} i < guess \implies \varSigma_{p \in \mathcal{P}} b_p^i = 1) \wedge (\bigwedge_{p \in \mathcal{P}} \varSigma_{i \in [1,n]} (i \leq guess \wedge b_p^i) \leq 1) \\ &\wedge \bigwedge_{i \in [1,n]} i < guess \implies iter_i \\ &\wedge \bigwedge_{i \in [1,n+1]} i = guess \implies check_i \end{split}$$

To get some intuition behind the formula, observe that each of the five conjuncts in this formula resembles closely the five conjuncts in the definition of *NoMonomeInv*( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ). The symbols shared across the different  $i \in [1, n + 1]$  are the  $b_p^i$  symbols and guess. This is similar to the definition of *NoMonomeInv*( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ), where the different models in  $\{\mathcal{M}_i\}_i$ only agree on the evaluation of the sets  $\mathcal{Q}_i$  and guess. The role of the  $b_p^i$  variable is precisely to encode the sets  $\mathcal{Q}_{i+1}$ ;  $b_p^i = \text{true}$  denotes that  $\{p\} = \mathcal{Q}_{i+1} \setminus \mathcal{Q}_i$ . The second conjunct denotes that  $Q_1 = \{\}$  where no predicate has been removed. The third conjunct has two parts. The first part  $i < guess \implies \Sigma_{p \in \mathcal{P}} b_p^i = 1$  denotes that  $Q_{i+1}$  and  $Q_i$  differ by exactly one predicate, for any i < guess. The second part  $\bigwedge_{p \in \mathcal{P}} \Sigma_{i \in [1,n]} (i \leq guess \wedge b_p^i) \leq 1$  denotes that a predicate is removed at most once in any one of the guess iterations. Similarly, the fourth conjunct justifies the removal of the predicate in  $Q_{i+1} \setminus Q_i$ .

**Theorem 3.** The formula SymbInferMonome(Prog,  $\mathcal{P}$ ) is satisfiable if and only if InferMonome(Prog,  $\mathcal{P}$ ) is false.

*Proof sketch.* We provide a proof sketch in this paper.

" $\implies$ ": Let us assume that  $SymbInferMonome(Prog, \mathcal{P})$  is satisfiable. Given a satisfying model  $\mathcal{M}$  to  $SymbInferMonome(Prog, \mathcal{P})$ , one can split  $\mathcal{M}$  into a set of models  $\{\mathcal{M}_i\}_i$  where  $\mathcal{M}_i$  assigns values to the *i*-th copy of the variables in  $\phi^i$ , only agreeing on the values of  $b_p^i$  and guess. Also, the valuation of the  $b_p^i$ can be used to construct the sets  $\mathcal{Q}_i$ ;  $\mathcal{Q}_{i+1} \leftarrow \mathcal{Q}_i \cup \{p\}$  when  $b_p^i$  is true in  $\mathcal{M}$ .

" $\Leftarrow$ ": Let us assume that  $InferMonome(Prog, \mathcal{P})$  returns false. Then by Lemma 2, we can construct a model  $\mathcal{M}$  by the union of the models  $\{\mathcal{M}_i\}_i$ , and construct an evaluation for  $b_p^i$  as follows: If  $\mathcal{Q}_{i+1} \setminus \mathcal{Q}_i = \{p\}$ , then assign  $b_p^i$  to true. In all other cases, assign  $b_p^i$  to be false. The model  $\mathcal{M}$  satisfies  $SymbInferMonome(Prog, \mathcal{P})$ .

**Theorem 4.** For an assertion logic closed under wp and Boolean connectives, the complexity of InferMonome(Prog,  $\mathcal{P}$ ) matches the complexity of Check(Prog, I).

Proof sketch. Since  $SymbInferMonome(Prog, \mathcal{P})$  results in a formula which is polynomial in  $\mathcal{P}$  and the size of wp(body, p) for any predicate  $p \in \mathcal{P}$ , the complexity of checking the satisfiability of  $SymbInferMonome(Prog, \mathcal{P})$  is simply the complexity of checking assertions in the assertion logic in which Check(Prog, I) is expressed.

**Corollary 1.** If the decision problem for Check(Prog, I) is **Co-NP** complete, then the decision problem for  $InferMonome(Prog, \mathcal{P})$  is **Co-NP** complete.

The encoding  $SymbInferMonome(Prog, \mathcal{P})$  can also be seen as an alternative algorithm for the  $InferMonome(Prog, \mathcal{P})$  problem. However, when the formula  $SymbInferMonome(Prog, \mathcal{P})$  is unsatisfiable, it does not readily provide us with the invariant I. We believe this can be extracted from the unsatisfiable core, and we are currently working on it.

# 5 Clausal abstraction

For any set  $\mathcal{R} \subseteq \mathcal{P}$ , a *clause* over  $\mathcal{R}$  is the formula  $\bigvee_{p \in \mathcal{R}} p$ . For a program Prog(pre, post, body) and a set of predicates  $\mathcal{P}$ , let us define  $InferClause(Prog, \mathcal{P})$  to return true if and only if there exists a  $\mathcal{R} \subseteq \mathcal{P}$  such that  $Check(Prog, \bigvee_{p \in \mathcal{R}} p)$  is true.

#### 5.1 Dual Houdini algorithm

First, let us describe an algorithm for solving the  $InferClause(Prog, \mathcal{P})$  problem. Recall that the Houdini algorithm for solving the  $InferMonome(Prog, \mathcal{P})$  problem starts with the conjunction of all predicates in  $\mathcal{P}$  and iteratively removes predicates until a fixpoint is reached. Conversely, the dual Houdini algorithm starts with the disjunction of all predicates in  $\mathcal{P}$  and removes predicates until a fixpoint is reached. The algorithm invokes  $FindInv(\mathcal{P})$  (in Figure 3), only this time using the following definitions of FailsCheck and RemovesPredicate macros:

$$\begin{array}{l} FailsCheck(\mathcal{S},\mathcal{M}) & \stackrel{\triangle}{=} \mathcal{M} \models (\bigwedge_{q \in \mathcal{S}} \neg q) \land pre \\ RemovesPredicate(\mathcal{S},\mathcal{M},p) & \stackrel{\triangle}{=} \lor \mathcal{M} \models \neg post \land p \\ \lor \mathcal{M} \models \neg wp(body,\bigvee_{q \in \mathcal{S}} q) \land p \end{array}$$

In the remainder of this section, we let  $FindInv(\mathcal{P})$  denote the algorithm with the above definitions of  $FailsCheck(\mathcal{S}, \mathcal{M})$  and  $RemovesPredicate(\mathcal{S}, \mathcal{M}, p)$ , rather than those given in Figure 3.

**Theorem 5.** The procedure  $FindInv(\mathcal{P})$  enjoys the following properties:

- 1. FindInv( $\mathcal{P}$ ) returns FAIL if and only if InferClause(Prog,  $\mathcal{P}$ ) is false.
- 2. If FindInv( $\mathcal{P}$ ) returns SUCCESS( $\mathcal{R}$ ), then for any  $\mathcal{S} \subseteq \mathcal{P}$  such that Check(Prog,  $\bigvee_{p \in \mathcal{S}} p$ ), we have  $S \subseteq \mathcal{R}$ .

The theorem signifies that the dual Houdini constructs the weakest clause I that satisfies Check(Prog, I), as opposed to Houdini, which computes the strongest monome I that satisfies Check(Prog, I). This is not surprising because Houdini solves the problem in the forward direction starting from pre, whereas the dual algorithm solves the problem backwards staring from post.

The structure of the rest of the section is similar to Section 4. For brevity, we mostly state the analogues of lemmas, theorems and symbolic encoding in the next two subsections, without details of the proofs.

#### 5.2 Model-theoretic proof

For a guess  $\in \mathbb{N}$ , an indexed set of models  $\{\mathcal{M}_i\}_i$ , an indexed set of sets of predicates  $\{\mathcal{Q}_i\}_i$ , we define a predicate *NoClauseInv*( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ), that is true if and only if the following conditions hold:

- 1.  $1 \leq guess \leq |\mathcal{P}| + 1$ ,
- 2.  $Q_1 = \{\},\$
- 3. For  $1 \leq i < guess$ ,  $\mathcal{Q}_{i+1} \setminus \mathcal{Q}_i = \{p_i\}$  for some  $p_i \in \mathcal{P}$ ,
- 4. For each  $1 \leq i < guess$ , and for  $p_i \in \mathcal{Q}_{i+1} \setminus \mathcal{Q}_i$ , either  $\mathcal{M}_i \models \neg post \land p_i$  or  $\mathcal{M}_i \models \neg wp(body, \bigvee_{p \in \mathcal{P} \setminus \mathcal{Q}_i} p) \land p_i$ , and
- 5.  $\mathcal{M}_{guess} \models (\bigwedge_{p \in \mathcal{P} \setminus \mathcal{Q}_{guess}} \neg p) \land pre.$

The following three lemmas establish the connection between the *InferClause* problem, the *NoClauseInv* predicate, and the *FindInv* algorithm.

**Lemma 5.** If FindInv( $\mathcal{P}$ ) returns FAIL, then NoClauseInv( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ) holds on the values computed by the procedure.

**Lemma 6.** If NoClauseInv( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ) holds for some guess  $\in \mathbb{N}$ , a set of models  $\mathcal{M}_1, \ldots, \mathcal{M}_{guess}$ , and sets of predicates  $\mathcal{Q}_1, \ldots, \mathcal{Q}_{guess}$ , then InferClause(Prog,  $\mathcal{P}$ ) is false.

**Lemma 7.** If  $FindInv(\mathcal{P})$  returns  $SUCCESS(\mathcal{R})$ , then  $Check(Prog, \bigvee_{p \in \mathcal{R}} p)$  is true, and therefore  $InferClause(Prog, \mathcal{P})$  is true.

#### 5.3 Symbolic encoding

Similar to the monomial abstraction, we define the  $SymbInferClause(Prog, \mathcal{P})$  which is satisfiable if and only if  $InferClause(Prog, \mathcal{P})$  returns false. The symbolic encoding for clausal abstraction retains the structure of the symbolic encoding for monomial abstraction. The only difference is that the definitions of the predicates  $iter_i$  and  $check_i$  change as follows:

For each  $i \in [1, n]$ , we define

$$iter_i \stackrel{\triangle}{=} \lor \neg post^i \land \bigwedge_{p \in \mathcal{P}} (b_p^i \implies p^i) \\ \lor \neg wp(s, \bigvee_{p \in \mathcal{P}} present_p^i \land p)^i \land \bigwedge_{p \in \mathcal{P}} (b_p^i \implies p^i)$$

For each  $i \in [1, n+1]$ , we define

$$check_i \stackrel{\triangle}{=} \bigwedge_{n \in \mathcal{P}} (present_p^i) \implies \neg p^i) \land pre^i$$

Finally, the analogues of Theorem 3, Theorem 4, and Corollary 1 can be shown for the clausal abstraction as well.

**Theorem 6.** The formula SymbInferClause( $Prog, \mathcal{P}$ ) is satisfiable if and only if  $InferClause(Prog, \mathcal{P})$  is false.

**Theorem 7.** For an assertion logic closed under wp and Boolean connectives, the complexity of  $InferClause(Prog, \mathcal{P})$  matches the complexity of Check(Prog, I).

**Corollary 2.** If the decision problem for Check(Prog, I) is **Co-NP** complete, then the decision problem for  $InferClause(Prog, \mathcal{P})$  is **Co-NP** complete.

#### 6 Conclusions

Formulation of predicate abstraction as a decision problem allows us to infer annotations for programs in a property guided manner, by leveraging off-the-shelf and efficient verification condition generators. In this work, we have studied the complexity of the decision problem of predicate abstraction relative to the complexity of checking an annotated program. The monomial and clausal restrictions considered in this paper are motivated by practical applications, where most invariants are monomes and a handful of clauses [16]. We have also provided a new algorithm for solving the InferClause(Prog, I) problem.

There are several questions that are still unanswered. We would like to construct an invariant from the unsatisfiable core, when the symbolic encoding of the  $InferMonome(Prog, \mathcal{P})$  or  $InferClause(Prog, \mathcal{P})$  returns unsatisfiable. It is also not clear what the complexity is for inferring invariants that are either a disjunction of up to c monomes, or a conjunction of up to c clauses, for a fixed constant c.

# References

- T. Ball, R. Majumdar, T. Millstein, and S. K. Rajamani. Automatic predicate abstraction of C programs. In *Programming Language Design and Implementation* (*PLDI '01*), pages 203–213, 2001.
- M. Barnett and K. R. M. Leino. Weakest-precondition of unstructured programs. In Program Analysis For Software Tools and Engineering (PASTE '05), pages 82– 87, 2005.
- E. M. Clarke, O. Grumberg, S. Jha, Y. Lu, and H. Veith. Counterexample-guided abstraction refinement. In *Computer Aided Verification (CAV '00)*, LNCS 1855, pages 154–169, 2000.
- J. Condit, B. Hackett, S. K. Lahiri, and S. Qadeer. Unifying type checking and property checking for low-level code. In *Principles of Programming Languages* (POPL '09), pages 302–314, 2009.
- P. Cousot and R. Cousot. Abstract interpretation: A unified lattice model for the static analysis of programs by construction or approximation of fixpoints. In *Principles of Programming Languages (POPL '77)*, pages 238–252, 1977.
- P. Cousot and N. Halbwachs. Automatic discovery of linear restraints among variables of a program. In *Principles of Programming Languages (POPL '78)*, pages 84–96, 1978.
- C. Flanagan and K. R. M. Leino. Houdini, an annotation assistant for ESC/Java. In International Symposium of Formal Methods Europe (FME '01), pages 500–517, 2001.
- S. Graf and H. Saïdi. Construction of abstract state graphs with PVS. In Computer-Aided Verification (CAV '97), LNCS 1254, pages 72–83, June 1997.
- S. Gulwani, S. Srivastava, and R. Venkatesan. Constraint-based invariant inference over predicate abstraction. In Verification, Model Checking, and Abstract Interpretation (VMCAI '09), LNCS 5403, pages 120–135, 2009.
- T. A. Henzinger, R. Jhala, R. Majumdar, and K. L. McMillan. Abstractions from proofs. In *Principles of Programming Languages (POPL)*, pages 232–244, 2004.
- T. A. Henzinger, R. Jhala, R. Majumdar, and G. Sutre. Lazy abstraction. In Principles of Programming Languages (POPL '02), pages 58–70, 2002.
- H. Jain, D. Kroening, N. Sharygina, and E. M. Clarke. Word level predicate abstraction and refinement for verifying rtl verilog. In *Design Automation Conference* (*DAC '05*), pages 445–450. ACM, 2005.
- R. P. Kurshan. Computer-Aided Verification of Coordinating Processes: The Automata-Theoretic Approach. Princeton University Press, 1995.

- S. K. Lahiri and R. E. Bryant. Constructing quantified invariants via predicate abstraction. In Verification, Model Checking and Abstract Interpretation (VMCAI '04), LNCS 2937, pages 267–281, 2004.
- S. K. Lahiri and S. Qadeer. Back to the future: Revisiting precise program verification using SMT solvers. In *Principles of Programming Languages (POPL '08)*, pages 171–182, 2008.
- S. K. Lahiri, S. Qadeer, J. P. Galeotti, J. W. Voung, and T. Wies. Intra-module inference. In *Computer-Aided Verification (CAV '09)*, LNCS (to appear), July 2009.
- S. Sagiv, T. W. Reps, and R. Wilhelm. Solving shape-analysis problems in languages with destructive updating. ACM Transactions on Programming Languages and Systems (TOPLAS), 20(1):1–50, 1998.
- S. Sankaranarayanan, H. B. Sipma, and Z. Manna. Constraint-based linearrelations analysis. In *Static Analysis Symposium (SAS '04)*, LNCS 3148, pages 53–68, 2004.
- S. Sankaranarayanan, H. B. Sipma, and Z. Manna. Scalable analysis of linear systems using mathematical programming. In *Verification, Model Checking, and Abstract Interpretation (VMCAI '05)*, LNCS 3385, pages 25–41, 2005.
- 20. Satisfiability Modulo Theories Library (SMT-LIB). Available at http://goedel.cs.uiowa.edu/smtlib/.
- A. Solar-Lezama, R. M. Rabbah, R. Bodík, and K. Ebcioglu. Programming by sketching for bit-streaming programs. In *Programming Language Design and Implementation (PLDI '05)*, pages 281–294. ACM, 2005.

# Appendix

#### Proof of Lemma 2

*Proof.* The first four conditions of *NoMonomeInv*( $\mathcal{P}$ , guess,  $\{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ) are easily satisfied by construction. The fifth condition can be shown by observing that  $\mathcal{Q}_{guess} \cup \mathcal{R} = \mathcal{P}$  is a precondition to *FindInvAux*.

# Proof of Lemma 3

*Proof.* Let us assume that there exists guess,  $\{\mathcal{M}_i\}_{i \in [1, guess]}, \{\mathcal{Q}_i\}_{i \in [1, guess]}$  satisfying *NoMonomeInv*( $\mathcal{P}, guess, \{\mathcal{M}_i\}_i, \{\mathcal{Q}_i\}_i$ ). We will show that in such a case, *InferMonome*(*Prog*,  $\mathcal{P}$ ) returns false.

We will prove this by contradiction. Let us assume that there is a  $\mathcal{R} \subseteq \mathcal{P}$  such that  $Check(Prog, \bigwedge_{p \in \mathcal{R}} p)$  holds. Let  $I = \bigwedge_{p \in \mathcal{R}} p$ . We claim that  $\mathcal{R} \cap \mathcal{Q}_{guess} = \{\}$ . We will prove this by induction on i for  $1 \leq i \leq guess$ , showing  $\mathcal{R} \cap \mathcal{Q}_i = \{\}$ . The base case for i = 1 holds vacuously since  $\mathcal{Q}_1 = \{\}$ . Let us assume that the induction hypothesis holds for all  $j \leq i$ . Consider the set  $\{p_i\} = \mathcal{Q}_{i+1} \setminus \mathcal{Q}_i$ . We show that  $p_i$  cannot be in  $\mathcal{R}$ . Consider the two cases how  $p_i$  gets removed.

- If  $\mathcal{M}_i \models pre \land \neg p_i$ , then we know that  $\not\models pre \implies p_i$ . If  $p_i \in \mathcal{R}$ , then  $\models pre \implies p_i$ , which is a contradiction.

- On the other hand, suppose  $\mathcal{M}_i \models (\bigwedge_{p \in \mathcal{P} \setminus \mathcal{Q}_i} p) \land \neg wp(body, p_i)$ . By induction hypothesis, we know that  $\mathcal{R} \cap \mathcal{Q}_i = \{\}$ , therefore  $\mathcal{R} \subseteq \mathcal{P} \setminus \mathcal{Q}_i$ . This implies  $\mathcal{M}_i \models (\bigwedge_{p \in \mathcal{R}} p) \land \neg wp(body, p_i)$ . If  $p_i \in \mathcal{R}$ , then we can conclude that  $\mathcal{M}_i \models (\bigwedge_{p \in \mathcal{R}} p) \land \neg (\bigwedge_{p \in \mathcal{R}} wp(body, p))$ . Since wp distributes over  $\land$ , we have  $\bigwedge_{p \in \mathcal{R}} wp(body, p)) = wp(body, \bigwedge_{p \in \mathcal{R}} p)$  and thus  $\mathcal{M}_i \models I \land \neg wp(body, I)$ . Since I satisfies Check(Prog, I), we have arrived at a contradiction.

Having shown that  $\mathcal{R} \cap \mathcal{Q}_{guess} = \{\}$ , we know that  $\mathcal{R} \subseteq \mathcal{P} \setminus \mathcal{Q}_{guess}$ . Since  $\mathcal{M}_{guess} \models (\bigwedge_{p \in \mathcal{P} \setminus \mathcal{Q}_{guess}} p) \land \neg post$ , it implies that  $\mathcal{M}_{guess} \models (\bigwedge_{p \in \mathcal{R}} p) \land \neg post$ , which in turn implies  $\not\models I \implies post$ , which contradicts our assumption that Check(Prog, I).

# Proof of Lemma 4

*Proof.* Let FindInvAux return  $SUCCESS(\mathcal{R})$  for an argument  $\mathcal{R}$  to FindInvAux. Since both the if branches are not taken, all the following conditions hold:

- 1.  $\models (\bigwedge_{q \in \mathcal{R}} q) \implies post.$
- 2. For each  $q \in \mathcal{R}$ ,  $\models pre \implies q$ , and therefore  $\models pre \implies (\bigwedge_{q \in \mathcal{R}} q)$ .
- 3. For each  $q \in \mathcal{R}$ ,  $\models (\bigwedge_{p \in \mathcal{R}} p) \implies wp(body, q)$ . Since wp distributes over  $\land$ , this implies  $\models (\bigwedge_{p \in \mathcal{R}} p) \implies wp(body, (\bigwedge_{p \in \mathcal{R}} p))$ .

These conditions mean that  $Check(Prog, \bigwedge_{a \in \mathcal{R}} q)$  holds.

# Proof of Lemma 1

*Proof.* Part (1) is proved easily by combining Lemmas 2, 3, and 4.

To prove part (2), we establish the following precondition for FindInvAuxprocedure: For any set of predicates  $S \subseteq \mathcal{P}$  such that  $Check(Prog, \bigwedge_{p \in S} p)$ holds,  $S \cap \mathcal{Q}_{guess} = \{\}$ . The proof follows by induction on guess similar to the proof of Lemma 3. Similarly,  $\mathcal{R} \cup \mathcal{Q}_{guess} = \mathcal{P}$  is another precondition for FindInvAux. Therefore, whenever FindInvAux returns  $SUCCESS(\mathcal{R}), (\bigwedge_{p \in \mathcal{R}} p)$ is the strongest monomial invariant over  $\mathcal{P}$  that satisfies the program.  $\Box$